# Algorithmic Game Theory - Handout 6 

Uriel Feige, Robert Krauthgamer, Moni Naor

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We consider graphical games with $n$ players where the graph $G$ is a tree of maximum degree $d$, and each player has 2 possible actions. We assume all payoffs are in $[0,1]$, represented by $O(n)$ bits. Unless stated otherwise, we assume $d$ is constant (with respect to $n$ ), and measure complexity (e.g. running time) only in terms of $n$. Here are some open problem:

- Is there a polynomial-time algorithm for computing an (exact) Nash equilibrium in (graphical) tree games (with constant $d$ )? (The known algorithms find $\varepsilon$-Nash equilibrium.)
- Can the algorithm for $\varepsilon$-Nash equilibrium in tree game be extended to general $d$ ? (The known algorithm's runtime grows like $d^{d}$, slightly super-polynomial in the description size $2^{d}$.)
- Can the algorithm for $\varepsilon$-Nash equilibrium in tree game be generalized to, say, planar graphs?

Reading. More information on graphical games can be found in [NRTV, Chapter 7] and references therein.

Homework. Please keep the answers to the following questions short and easy to read.

1. Prove that for every $\varepsilon, d>0$ there is $\tau=\tau(d, \varepsilon)$, such that in every (graphical) tree game as above ( $n$ players, maximum degree $d, 2$ strategies for every player), for every Nash equilibrium there exists an $\varepsilon$-Nash equilibrium, where all players' probabilities are integer multiples of $\tau$, and in addition the $\varepsilon$-Nash approximates the given Nash in the sense that each player's expected payoff is changed by no more than $\varepsilon$.
Remark: For full credit, show $\tau \geq \Omega(\varepsilon / d)$.
2. For a given game, let $O P T$ denote the maximum, over all Nash equilibria, of the social welfare (i.e. total over all players of expected payoff). Show that for every constant $\varepsilon>0$ there is a polynomial-time algorithm that given as input a (graphical) tree game with constant $d$, computes an $\varepsilon$-Nash equilibrium with social welfare at least $O P T-n \varepsilon$.
3. Explain how to generalize the algorithm shown in class for finding an $\varepsilon$-Nash equilibrium in a (graphical) tree game to the following graph families: (a) $G$ is a two-dimensional (rectangular) grid of size $r \times(n / r)$ for constant $r$; and (b) $G$ is a cycle on $n$ vertices. The running time should be polynomial in $n$.
4. Extra credit: Show that the case $\varepsilon=0$ in Question 2, namely, the problem of finding a Nash equilibrium whose average utility is maximal (among all Nash equilibria) is NP-hard.

## References

[NRTV] Noam Nisan, Tim Roughgarden, Eva Tardos and Vijay V. Vazirani (Editors), Algorithmic Game Theory, Cambridge University Press, 2007.

