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MPLS-TP Network Management Framework draft-ietf-mpls-tp-nm-framework-01

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Abstract

This document provides the network management framework for the

Mansfield, et al. Expires April 26, 2010 [Page 1]

Transport Profile for Multi-Protocol Label Switching (MPLS-TP).

This framework relies on the management terminology from the ITU-T to describe the management architecture that could be used for an MPLS-TP management network.

The management of the MPLS-TP network could be based on multi-tiered distributed management systems. This document provides a description of the network and element management architectures that could be applied and also describes heuristics associated with fault, configuration, and performance aspects of the management system.

Table of Contents

1. Introduction	. 3
1.1. Terminology	. 3
2. Management Architecture	. 4
2.1. Network Management Architecture	. 4
2.2. Element Management Architecture	. 6
2.3. Standard Management Interfaces	. 9
2.4. Management and Control specific terminology	. 10
2.5. Management Channel	. 10
3. Fault Management	. 11
3.1. Supervision	
3.2. Validation	. 12
3.3. Alarm Handling	. 12
4. Configuration Management	
4.1. LSP ownership handover	. 12
5. Performance Management	. 13
6. Acknowledgements	. 14
7. Contributors	. 14
8. IANA Considerations	. 14
9. Security Considerations	
10. References	
10.1. Normative References	. 15
10.2. Informative References	
Authors' Addresses	. 16

Mansfield, et al. Expires April 26, 2010 [Page 2]

Internet-Draft

MPLS-TP NM Framework

1. Introduction

This document provides a framework for using the MPLS-TP NM requirements [1] for managing the elements and networks that support a Transport Profile for MPLS.

This framework relies on the management terminology from the ITU-T to describe the management architecture that could be used for an MPLS-TP management network.

1.1. Terminology

Communication Channel (CCh): A logical channel between network elements (NEs) that can be used <u>in</u> - e.g. - management plane applications or control plane applications. The physical channel supporting the CCh is technology specific. <u>An example of</u> <u>For MPLS-TP, the</u> physical

channels supporting the CCh is <u>the MPLS-TP Management Communication</u> Channel (MCC)a DCC channel within SDH.

Data Communication Network (DCN): A network that supports Layer 1 (physical), Layer 2 (data-link), and Layer 3 (network) functionality for distributed management communications related to the management plane, for distributed signaling communications related to the control plane, and other operations communications (e.g., order-wire/voice communications, software downloads, etc.).

Equipment Management Function (EMF): <u>T</u>the management functions within an NE. See ITU-T G.7710 [2].

...Label Switched Path (LSP): ...TBA

Local Craft Terminal (LCT): An out-of-band device that connects to an NE for management purposes.

Management Application Function (MAF): An application process that participates in system management. See ITU-T G.7710 [2].

Management Communication Channel (MCC): A CCh dedicated for management plane communications.

Message Communication Function (MCF): The communications process that performs functions such as information interchange and relay. See ITU-T M.3013 [6].

Management Communication Network (MCN): A DCN supporting management plane communication is referred to as a Management Communication Network (MCN).

MPLS-TP NE: \underline{A} network element (NE) that supports MPLS-TP functions. Another term that is used for a network element is node. In terms of this document, the term node is equivalent to NE.

Mansfield, et al. Expires April 26, 2010 [Page 3]

MPLS-TP network: At network in which MPLS-TP NEs are deployed.

Network Element Function (NEF): The set of functions necessary to manage a network element.

Operations System (OS): A system that performs the functions that support processing of information related to operations, administration, maintenance, and provisioning (OAM&P) for the networks, including surveillance and testing functions to support customer access maintenance.

Signaling Communication Network (SCN): A DCN supporting control plane communication is referred to as a Signaling Communication Network (SCN).

Signaling Communication Channel (SCC): \underline{A} CCh dedicated for control plane communications. The SCC may be used for GMPLS/ASON signaling and/or other control plane messages (e.g., routing messages).

2. Management Architecture

The management of the MPLS-TP network could be based on a multitiered distributed management systems, for example as described in ITU-T M.3010 [7] and ITU-T M.3060/Y.2401 [8]. Each tier provides a predefined level of network management capabilities. The lowest tier of this organization model includes the MPLS-TP Network Element that provides the transport service and the Operations System (OS) at the Element Management Level. The Mmanagement Application Ffunction (MAF) within

the NEs and OSs provides the management support. The <u>MAFmanagement</u> application function at each entity can include agents only, managers only, or both agents and managers. The <u>MAFmanagement application</u> function that include managers are capable of managing an agent included in other <u>MAFsmanagement application</u> functions.

The management communication to peer NEs and/or Operations Systems (OSs) is provided via the Mmessage Ceommunication \underline{F} function (MCF) within each entity (e.g. NE and OS). The user can access the management of the MPLS-TP transport network via a Local Craft Terminal (LCT) attached to the NE or via a Work Station (WS) attached to the OS.

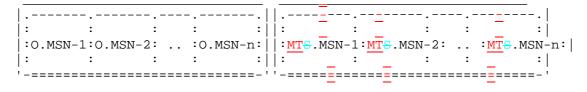
2.1. Network Management Architecture

A transport Management Network (MN) may consist of several transport technology specific Management Networks. <u>Management network</u> <u>partitioning (Figure 1)</u> below <u>based onfrom</u> ITU-T G.7710 [2] shows <u>thean</u> <u>example</u>

of management network partitioning. Notation used in G.7710 for a transport technology specific MN is x.MN, where x is the transport

Mansfield, et al. Expires April 26, 2010 [Page 4]

specific technology. In the example "O.MSN" is equivalent to an optical management subnetwork, and "S.MSN" is equivalent to an SDH management subnetwork. An MPLS-TP specific MN ismight be abbreviated as MPLS-TP.MN. In the figure "O.MSN" is equivalent to an optical management Subnetwork. Where there is no ambiguity, we will use "MN" for an MPLS-TP specific MN, and "MPLS TP.MN" (or "MPLS- TP MN") and "MN" where both are used in a given context.



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:	:	:	:	:
:x.MSN	J−1∶x.MS	N-2:	:x.MS	N-n:
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Management Network Partitioning

Figure 1

The management of the MPLS-TP network is be-separable from the management of the other technology-specific networks, and operate independently of any particular client or server layer management plane.

An MPLS-TP Management Network (MT.MN) could be partitioned into MPLS-TP Management SubNetworks ("MPLS-TP.MSN" or "MPLS-TP MSN", or just "MSN" where usage is unambiguous) for consideration of scalability (e.g. geographic or load balancing) or administrative (e.g. administrative or ownership).

The MPLS-TP MSN could be connected to other parts of the MN through one or more LCTs and/or OSs. The Mmessage Ceommunication Ffunction (MCF) of an MPLS-TP NE initiates/terminates, routes, or otherwise processes management messages over CChs or via an external interface.

Multiple addressable MPLS-TP NEs could be present at a single physical location (i.e. site or office). The inter-site communications link between the MPLS-TP NEs will normally be provided by the CChs. Within a particular site, the NEs could communicate via an intra-site CCh or via a LAN.

Mansfield, et al. Expires April 26, 2010

[Page 5]

Internet-Draft

2.2. Element Management Architecture

The Equipment Management Function (EMF) of a MPLS-TP NE provides the means through which a management system manages the NE.

The EMF interacts with the NE's transport functions by exchanging Management Information (MI) across the Management Point (MP) Reference Points. The EMF may contain a number of functions that provide a data reduction mechanism on the information received across the MP Reference Points.

The EMF includes functions such as Date & Time, FCAPS (Fault, Configuration, Accounting, Performance and Security) management, and Control Plane functions. The EMF provides event message processing, data storage and logging. The management Agent, a component of the EMF, converts internal management information (MI signals) into Management Application messages and vice versa. The Agent responds to Management Application messages from the Mmessage Ceommunication F=unction (MCF) by performing the appropriate operations on (for example) the Managed Objects in a Management Information Base (MIB), as necessary. The MCF ion function contains communications functions related to the outside world of the NE (i.e. Date & Time source, Management Plane, Control Plane, Local Craft Terminal and Local Alarms).

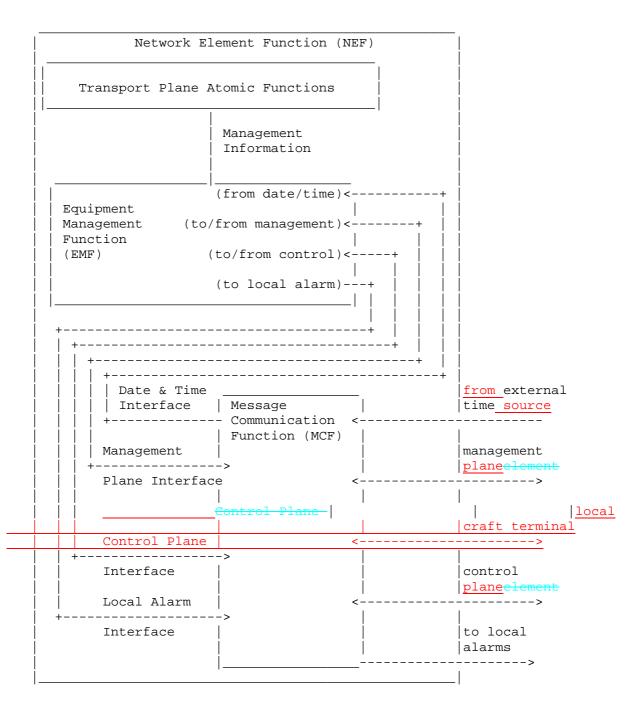
The Date & Time functions keep track of the NE's date/time which is used by the FCAPS management functions to e.g. time stamp event reports.

Below are diagrams that illustrate the components of the E-lement Management F=unction (EMF) of a Naetwork Eelement (NE). The high-level decomposition of the Network Element Function (NEF) picture (Figure 2) provides the breakdown of

the Network Element Function, then the EMFequipment picture (Figure 3) provides the details of Equipment Management Function, and finally the Mmessage C_{\ominus} ommunication F_{\pm} unction (MCF) picture (Figure 4) details the Message Communication Function.

Mansfield, et al. Expires April 26, 2010

[Page 6]



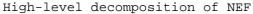
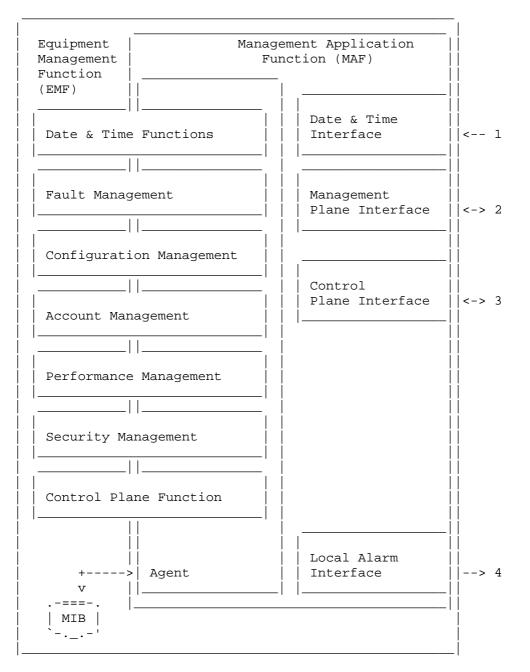


Figure 2

Mansfield, et al. Expires April 26, 2010

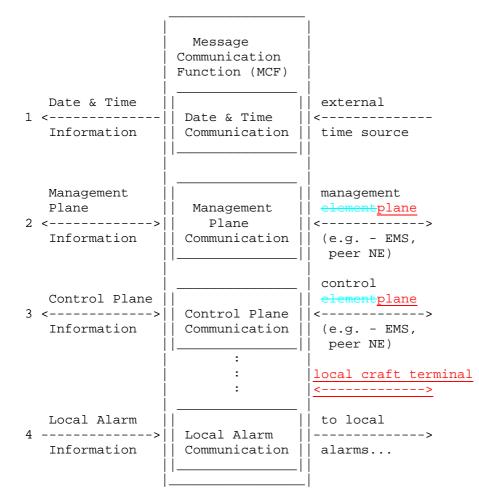
[Page 7]



Equipment Management Function

Figure 3

Mansfield, et al. Expires April 26, 2010 [Page 8]



Message Communication Function

Figure 4

2.3. Standard Management Interfaces

The MPLS-TP NM requirements [1] document places no restriction on which management interface is to be used for managing an MPLS-TP network. It is possible to provision and manage an end-to-end connection across a network where some segments are created/managed/ deleted, for example by netconf or snmp and other segments by CORBA interfaces. Use of any network management interface for one management related purpose does not preclude use of another network management interface for other management related purposes, or the same purpose at another time. The protocol(s) to be supported are at

Mansfield, et al. Expires April 26, 2010 [Page 9]

the discretion of the operator.

2.4. Management and Control specific terminology

Data Communication Network (DCN) is the common term for the network used to transport Management and Signaling information between: management systems and network elements, management systems to other management systems, and networks elements to other network elements. The Management Communications Network (MCN) is the part of the DCN which supports the transport of Management information for the Management Plane. The Signaling Communications Network (SCN) is the part of the DCN which supports transport for signaling information for the Control Plane. As shown in the communication channel terminology picture (Figure 5) each technology has its own terminology that is used for the channels that support management and control plane information transfer. For MPLS-TP, the management plane uses the Management Communication Channel (MCC) and the control plane uses the Signaling Communication Channel (SCC).

2.5. Management Channel

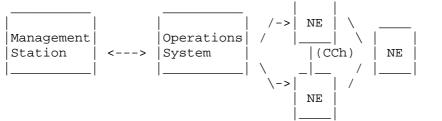
The Communication Channel (CCh) provides a logical channel between NEs for transferring Management and/or Signaling information. Note that some technologies provide separate communication channels for Management (MCC) and Signaling (SCC).

MPLS-TP NEs communicate via the DCN. The DCN connects NEs with management systems, NEs with NEs, and management systems with management systems.

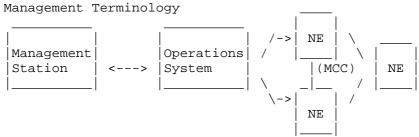
Mansfield, et al. Expires April 26, 2010

[Page 10]

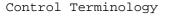
Common Terminology

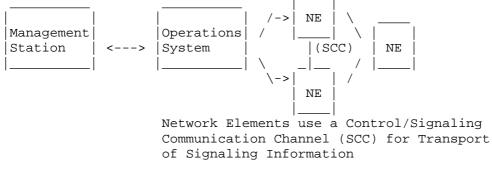


Network Elements use a Communication Channel (CCh) for Transport of Information



Network Elements use a Management Communication Channel (MCC) for Transport of Management Information





Communication Channel Terminology

Figure 5

3. Fault Management

A fault is the inability of a function to perform a required action. This does not include an inability due to preventive maintenance,

Mansfield, et al. Expires April 26, 2010 [Page 11]

lack of external resources, or planned actions. Fault management provides the mechanisms to detect, verify, isolate, notify, and recover from the fault.

3.1. Supervision

ITU-T G.7710 [2] lists five basic categories of supervision that provide the functionality necessary to detect, verify, and notify a fault. The categories are: Transmission Supervision, Quality of Service Supervision, Processing Supervision, Hardware Supervision, and Environment Supervision. Each of the categories provides a set of recommendations to ensure the fault management process is fulfilled.

3.2. Validation

ITU-T G.7710 [2] describes a fault cause as a limited interruption of the required function. It is not reasonable for every fault cause to be reported to maintenance personnel. The validation process is used to turn fault causes (events) into failures (alarms).

3.3. Alarm Handling

Within an element management system, it is important to consider mechanisms to support severity assignment, alarm reporting control, and logging.

4. Configuration Management

Configuration management provides the mechanisms to provision the MPLS-TP services, setup security for the MPLS-TP services and MPLS-TP network elements, and provides the destination for fault notifications and performance parameters. Inventory reporting is also considered part of configuration management.

Associated with configuration management are hardware and software provisioning and inventory reporting.

4.1. LSP ownership handover

MPLS-TP networks can be managed not only by Network Management Systems (i.e. Mmanagement Pplane (MP)), but also by Ceontrol Pplane (CP) protocols. The utilization of the Ceontrol Pplane is not a mandatory requirement (see MPLS-TP Requirements [3]) but it is often used by network operators in order to make network configuration and Label Switched Path (LSP) recovery

both faster and simpler.

Mansfield, et al. Expires April 26, 2010 [Page 12]

In networks where both CP and MP are provided, an LSP could be created by either (CP or MP). The entity creating an LSP owns the data plane resources comprising that LSP. Only the owner of an LSP is typically able to modify/delete it. This results in a need for interaction between the MP and CP to allow either to manage all the resources of a network.

Network operators might prefer to have full control of the network resources during the set-up phase and then allow the network to be automatically maintained by the <u>C</u>eontrol <u>P</u>plane. This can be achieved by creating LSPs via the <u>M</u>management <u>P</u>plane and subsequently transferring LSP ownership to the <u>C</u>eontrol <u>P</u>plane. This is referred to as "ownership handover" RFC 5493 [9]. MP to CP ownership handover is then considered a requirement where a <u>C</u>eontrol <u>P</u>plane is in use that supports it. The converse (CP to MP ownership handover) is a feature that is recommended - but not required - for (G)MPLS networks because it has only minor applications (for example moving LSPs from one path to another as a maintenance operation).

The LSP handover procedure has already been standardized for GMPLS networks, where the signaling protocol used is RSVP-TE RFC 3209 [4]. The utilization of RSVP-TE enhancements are defined in [5].

MP and CP interworking includes also the exchange of information that is either requested by the MP, or a notification by the CP as a consequence of a request from the MP or an automatic action (for example a failure occurs or an operation is performed). The CP is asked to notify the MP in a reliable manner about the status of the operations it performs and to provide a mechanism to monitor the status of <u>Ceontrol Pplane</u> objects (e.g. TE Link status, available resources), and to log <u>Ceontrol Pplane</u> LSP related operations. Logging is one of the most critical aspects because the MP always needs to have an accurate history and status of each LSP and all <u>D</u>data <u>Pplane</u> resources involved in it.

5. Performance Management

Performance statistics could overwhelm a <u>M</u>-anagement <u>N</u>-etwork, so it is important to provide flexible instrumentation that provides control over the amount of performance data to be collected.

A distinction is made between performance data that is collected ondemand and data that is collected proactively.

On-demand measurement provides the operator with the ability to do performance measurement for maintenance purpose such as diagnosis or to provide detailed verification of proactive measurement. It is

Mansfield, et al. Expires April 26, 2010 [Page 13]

used typically on specific LSP service instances for a limited time, thus limiting its impact on network performance under normal operations. Therefore on demand measurement does not result in scaling issues.

Proactive measurement is used continuously over time after being configured with periodicity and storage information. Data collected from proactive measurement are usually used for verifying the performance of the service. Proactive performance monitoring has the potential to overwhelm both the process of collecting performance data at a <u>Network E</u>element (for some arbitrary number of service instances traversing the NE), and the process of reporting this information to the OS. As a consequence of these considerations, operators would typically limit the services to which proactive performance measurement would be applied to a very selective subset of the services being provided and would limit the reporting of this information to statistical summaries (as opposed to raw or detailed performance statistics).

6. Acknowledgements

The authors/editors gratefully acknowledge the thoughtful review, comments and explanations provided by Diego Caviglia and Bernd Zeuner.

- 7. Contributors
- 8. IANA Considerations

This memo includes no request to IANA.

9. Security Considerations

Provisions to any of the network mechanisms designed to satisfy the requirements described herein need to prevent their unauthorized use and provide a means for an operator to prevent denial of service attacks if those network mechanisms are used in such an attack.

Solutions need to provide mechanisms to prevent private information from being accessed by unauthorized eavesdropping, or being directly obtained by an unauthenticated network element, system or user.

Performance of diagnostic functions and path characterization involves extracting a significant amount of information about network

Mansfield, et al. Expires April 26, 2010 [Page 14]

construction that the network operator considers private.

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Mansfield, et al. Expires April 26, 2010 [Page 15]

Internet-Draft

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Mansfield, et al. Expires April 26, 2010

[Page 16]