

# IEEE 802 Ethernet Networks for Automotive

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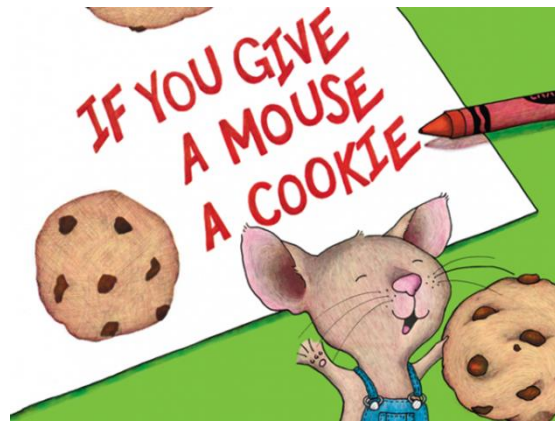
# Outline

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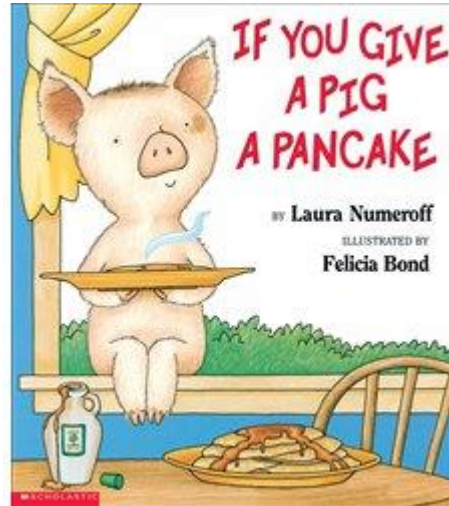
- Motivation
- PHY
- Time-Sensitive Networking (TSN)
  - reliability and timing
- Security
- Summary
- Q&A

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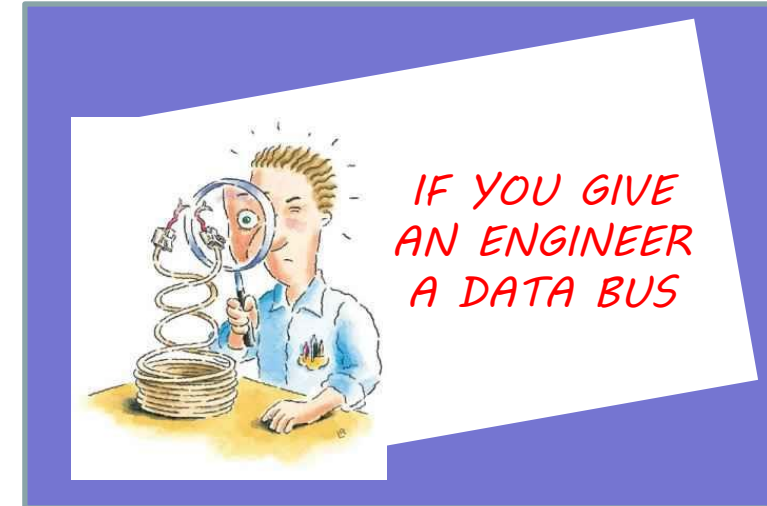
# MOTIVATION



*He's going  
to ask for a  
glass of milk.*



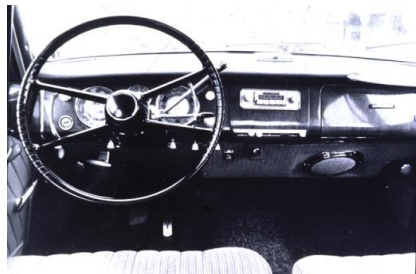
*She'll ask  
for a bottle  
of syrup.*



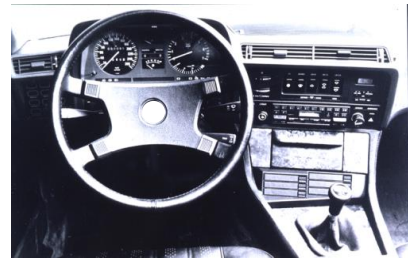
*He'll ask for more  
bandwidth and  
faster speeds.*

# Innovation in Automotive Technology is both Hardware & Software

- Increasing number of applications
  - Increasing complexity over time
  - Higher bandwidth requirements
  - Need reliable networks



Electronic Injection  
 Check engine control  
 Cruise control  
 Central locking  
 ...



Gearbox control  
 Climate control  
 ASC Anti Slip Control  
 ABS Anti-lock Brake Sys.  
 Telephone  
 Seat heating control  
 Automatic mirrors



Navigation system  
 CD-changer  
 Active Cruise Control  
 Airbags  
 Dynamic Stability Control  
 Roll stabilization  
 Xenon lighting  
 Vehicle Assist  
 Voice input  
 Emergency call



ACC Stop&Go  
 Lane departure warning  
 Blind spot warning  
 Traffic sign recognition  
 Night vision  
 Active headlight system  
 Parking automation  
 Efficient dynamics  
 Hybrid engines  
 Internet access  
 Telematics  
 Online Services  
 Bluetooth integration  
 Local Hazard Warning  
 Personalization  
 SW Update  
 Smart Phone Apps

1970

1980

1990

> 2010

Adapted from material provided by BMW

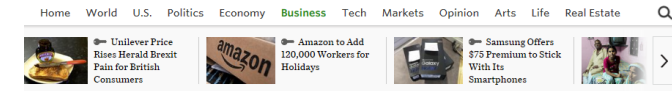
AUGUST 11, 2016

## 33 Corporations Working On Autonomous Vehicles



[http://www.driverless-future.com/?page\\_id=384](http://www.driverless-future.com/?page_id=384)

## THE WALL STREET JOURNAL



**GM Executive Credits Silicon Valley for Accelerating Development of Self-Driving Cars**  
 Head of GM's foresight and trends unit says timetable for autonomous vehicles likely moved from 2035 to 2020, if not sooner

By JOHN D. STOLL  
 Updated May 10, 2016 5:48 p.m. ET

**Ford: We'll sell fully autonomous cars by 2021 with no steering wheels**

By Bill Howard on August 17, 2016 at 11:30 am 26 Comments  
 13 shares



Autonomous vehicle by 2021 for the ride-hailing and ride-sharing markets. It'll be built with no steering wheel, no gas pedal, and no brake pedal.

**Meet the VW ID electric car: 300-plus mile range in 2020, self-driving by 2025**

By Bill Howard on September 30, 2016 at 9:22 am 47 Comments  
 1 shares



# Motivation for Ethernet

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- Data Needs
  - Raw camera data
  - Data logging (Government Regulations)
  - Map Data
  - Backbone aggregation
  - High resolution displays
  - In vehicle Wi-Fi hotspot (carrier link aggregation) – wired backhaul
- Latency Requirements
  - Minimum determined by Hardware
  - Maximum determined by Software
- Services
  - Precise Time Awareness
  - Redundancy / Fail over
  - Security

# How is Automotive Different?

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- Link Segment lengths are shorter
- Environment (EMC, Temperature, etc.) is harsher
- Qualification of Hardware is required
- Validation of Electronic Control Unit (ECU) Hardware and Software is required
- Reliability (higher MTBF)
- Start Up Time is shorter
- Latency is smaller
- Repeatability/Predictability is critical
- Safety/ASIL (ISO26262) compliance

# Latency

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- Real-time networks require **guaranteed not-to-exceed end-to-end latency** for critical data
- Two ways to accomplish this:
  - ~~1. Throw away late packets~~
  - 2. Provide zero congestion loss**
- Shapers and queueing define the time interval
- Worst-case latency
  - a) Is guaranteed
  - b) Grows linearly with the number of hops
- Average latency may be larger than simple priority



# Keys to Success

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- Reliability
- Predictability
- Flexibility
- Security

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**PHY**

# Automotive Networks

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- **CAN (Controller Area Network) – since 1991**
  - Low-speed serial data bus: 1 – 1000 Kbps
  - Shared medium with CSMA/CR (Collision Resolution)
  - Dominant control bus in all automotive domains
  - Standardized in ISO 11898; Multi-vendor support
  
- **FlexRay (consortium of automotive companies) – since 2005**
  - 10 Mb/s serial data bus (single or dual channel)
  - Shared medium with TDMA
  - Control bus for high dynamic applications, chassis control, but also designed for future “X-by-Wire” applications
  - Standardized in ISO 10681; Multi-vendor support

# Automotive Networks

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- **MOST (Media Oriented Systems Transport) – since 2001**
  - Shared ring topology: 25 Mb/s (POF), 50 Mb/s (Cu), 150 Mb/s (POF)
  - Bus system for control and streaming Infotainment data
  - Proprietary solution
- **Ethernet (100BASE-TX) – since 2008**
  - Mainly diagnostics and firmware upgrades during vehicle servicing (typically not used while the car is operating due to EMC limits)
  - Standardized in ISO 13400-3:2011 Road Vehicles – Diagnostic communication over Internet Protocol (DoIP) – Part 3: Wired vehicle interface based on IEEE 802.3
  - 100BASE-T1 – since 2013
- **LVDS / CML – since 2001**
  - Point-to-point high-speed links (1-4 Gb/s) for cameras and displays
  - Multi-vendor support but typically incompatible with each other

# Typical Wire Harness in a Car



Used with permission from Molex

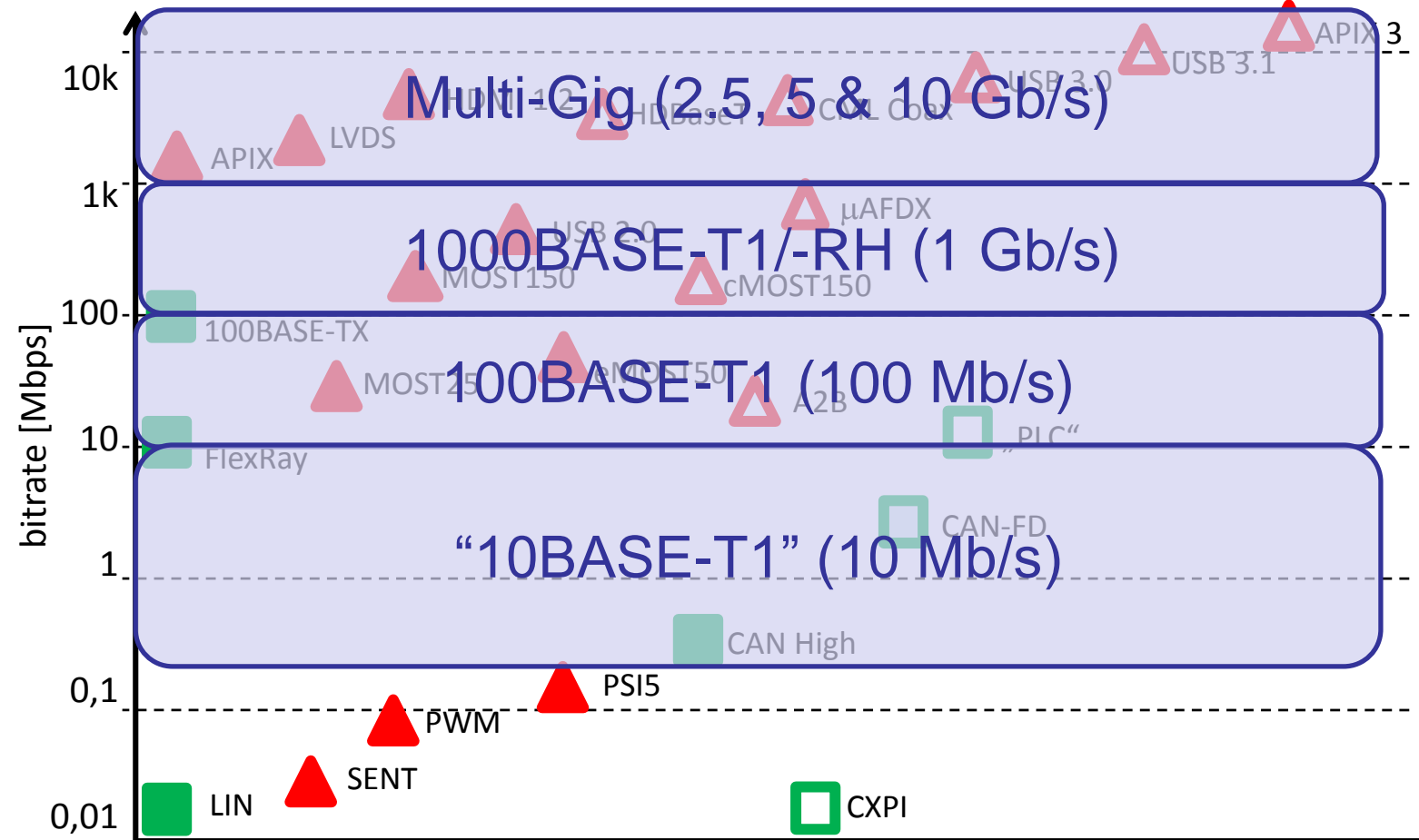
Cabling is the 3<sup>rd</sup> highest cost component in a car  
Engine (1st)  
Chassis (2nd)

Harnesses are built **ONE** at a time with 50% of cost in labor



Cabling is the 3<sup>rd</sup> heaviest component in a car  
Chassis (1st)  
Engine (2nd)



**Reducing cable weight has a direct impact on fuel economy!**

# Automotive Ethernet

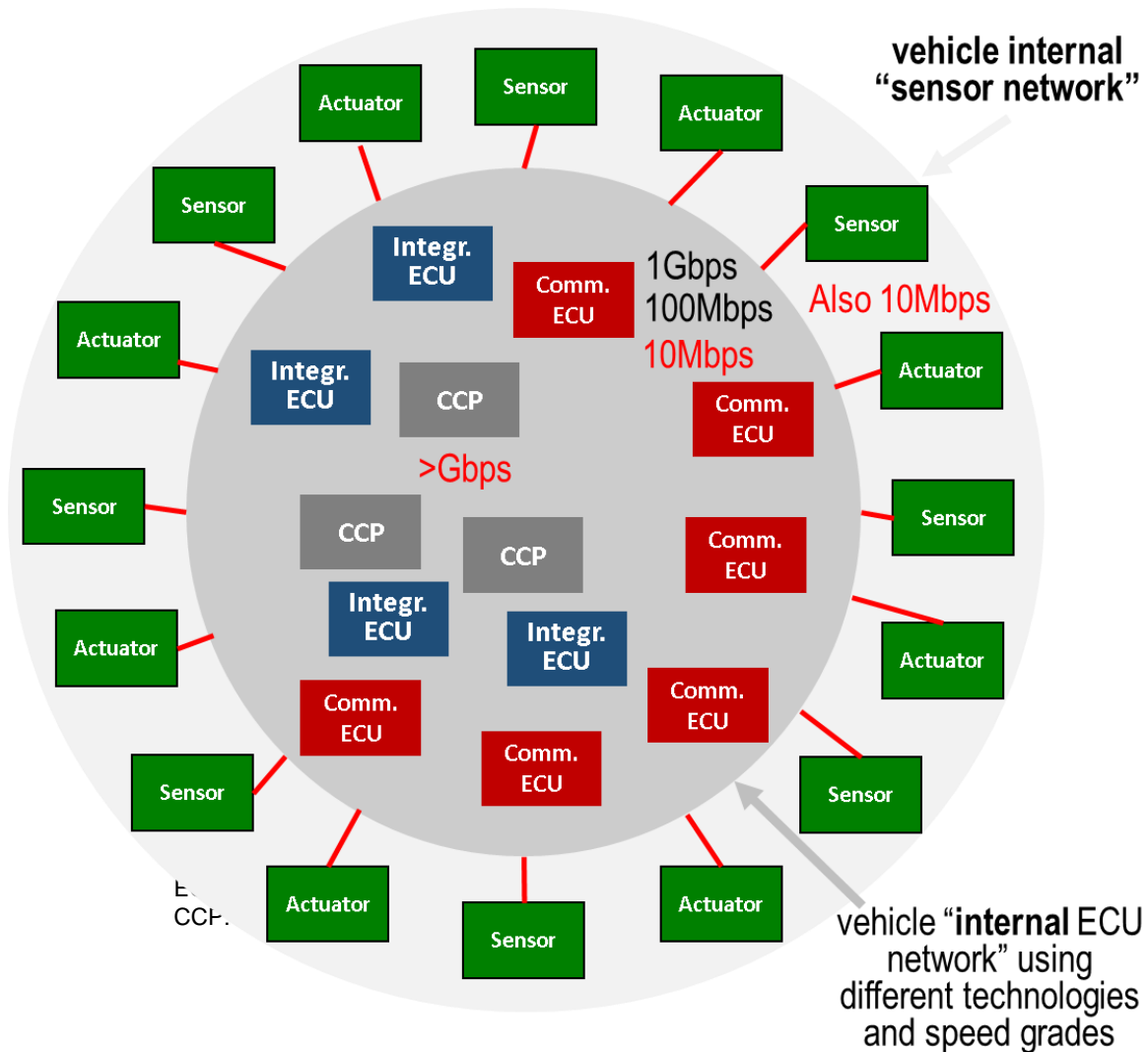


- ▶ There are no standard communication links for system usage above 1000 Mbps
- ▶ There are many proprietary communication links above 1000 Mbps
- ▶ Standard links are needed for this space
- ▶ There are no standard communication links for system usage between 100 Mbps and 1000 Mbps
- ▶ There are few standard communication links for system usage between 10 Mbps and 100 Mbps
- ▶ There are many standard communication links for system usage below 10 Mbps
- ▶ However, adding Ethernet in this space reduces the need for Gateways between various networks

 Specific use  
 System use  
 Proposed technologies

 Specific use  
 System use  
 Technologies in series development

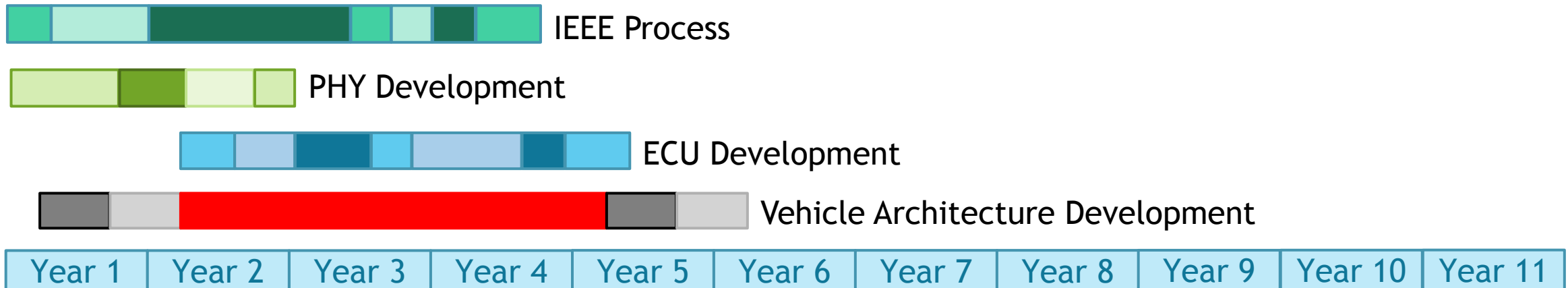
# Automotive Architecture Trends



- The transition to Ethernet is underway.
  - 802.3bp, 802.3bw
- There is a desire to converge towards **one** network type (“Ubiquitous IP”).
  - Independence of physical and logical network.
  - Reduction in number of In-Vehicle Network (IVN) technologies. (MOST / FlexRay / ...)
  - Reduction of multiple gateways.

# Total Automotive Ethernet PHY Development from Concept to Production

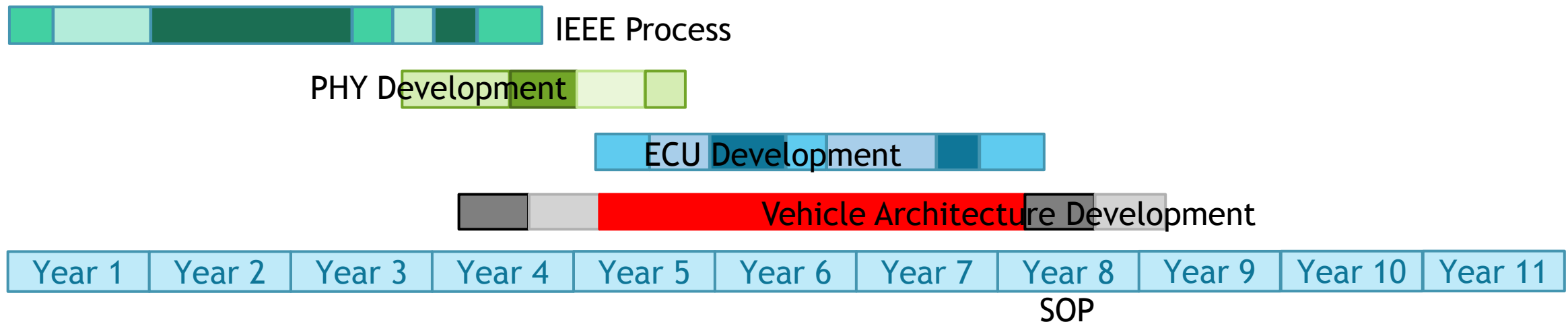
- ▶ Vehicle Architecture Development takes about 1 year and is done every 4 to 6 years.
- ▶ ECU Development takes about 3.5 years from RFQ to SOP.
- ▶ ECU Development starts after Vehicle Architecture Development.
- ▶ PHY Development takes about 2 years from the time all requirements are known and silicon is available for qualification.
- ▶ PHY samples must be available before end of Vehicle Architecture Development in order to be considered for the Architecture.
- ▶ The IEEE Process takes about 4 years.
- ▶ PHY sample development can start about 3 years into this process.





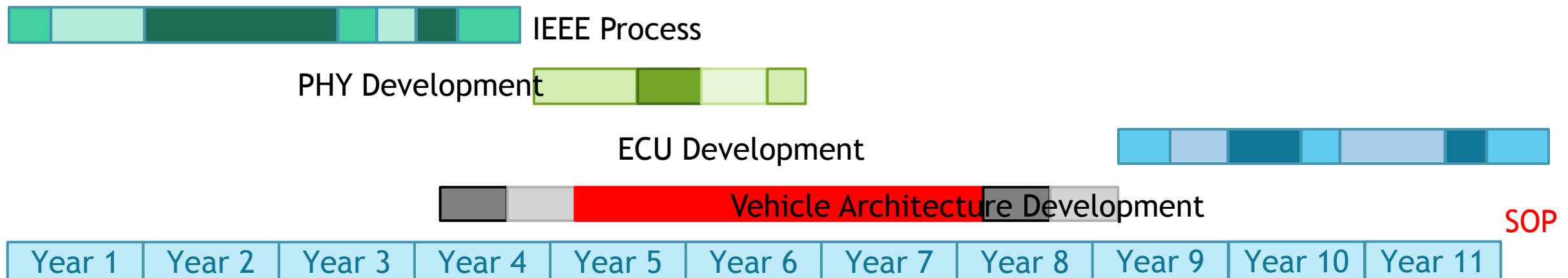
# Total Automotive Ethernet PHY Development from Concept to Production

- ▶ The IEEE Process takes about 4 years.
- ▶ PHY sample development can start about 3 years into this process.
- ▶ If this lines up with the Vehicle Architecture Development, SOP is 8 years after the start of the IEEE Process.



# Total Automotive Ethernet PHY Development from Concept to Production

- ▶ PHY Development may not start until the IEEE Process completes.
- ▶ If this does not line up with the Vehicle Architecture Development, SOP may be 11 (or more) years after the start of the IEEE Process.



# Automotive Conditions

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- **Harsh Environmental Conditions**

- Operating temperatures:
  - Body & cabin: -40°C to 85°C
  - Chassis & powertrain: -40°C to 125°C or even 150°C
- Mechanical accelerations:
  - Body & cabin: up to 4 G
- Dirt, water, salt, dust, ice, snow, mud, oil, grease, transmission fluid, brake fluid, engine coolant, hydraulic fluid, fuel, etc. (i.e., this is not a data center)

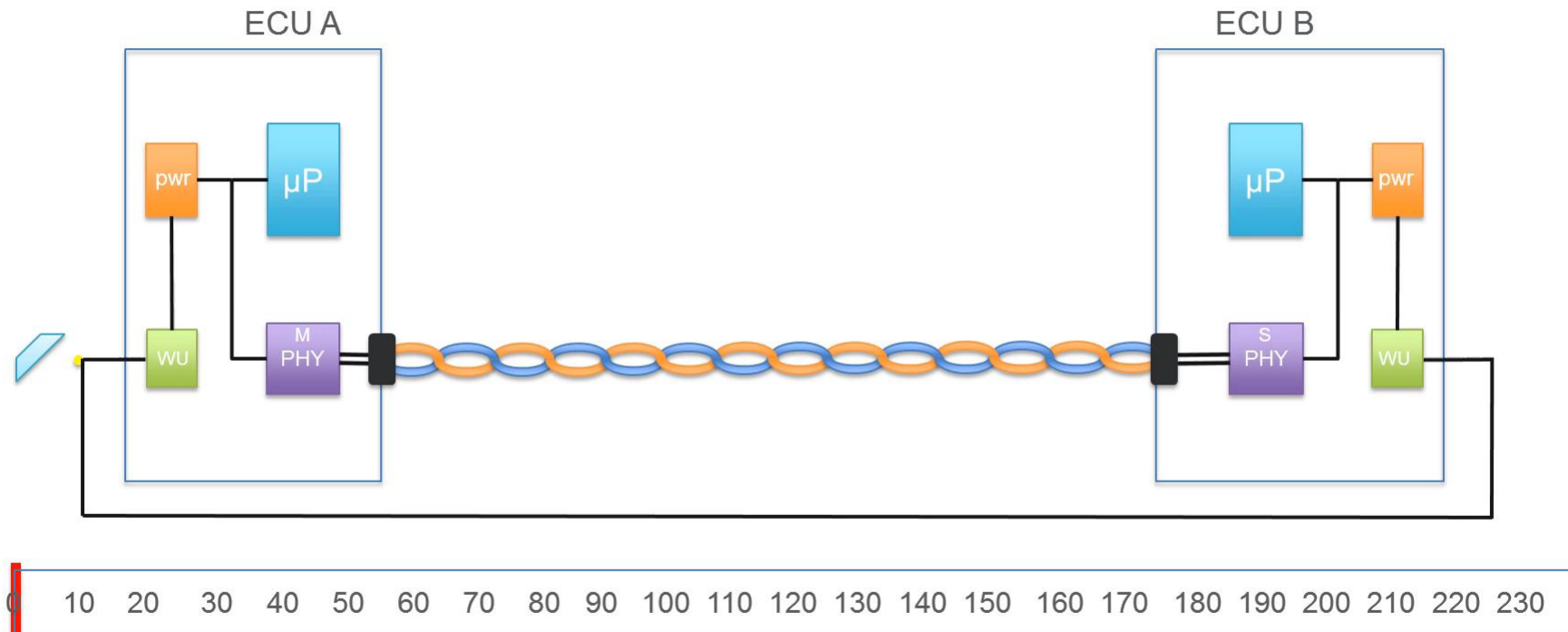
- **Automotive EMC requirements are stringent!**

- Tighter requirements than Class A/Class B EMI specs for consumer products
- Automotive EMC test specs exist, e.g., CISPR25 & ISO11452-2 & -4
- ESD, owners don't wear ESD straps

**For additional information see:**

- [http://www.ieee802.org/3/bw/public/buntz\\_tazebay\\_3bw\\_01\\_0914.pdf](http://www.ieee802.org/3/bw/public/buntz_tazebay_3bw_01_0914.pdf)
- [http://www.ieee802.org/3/bw/public/Wienchowski\\_3bw\\_02\\_0914.pdf](http://www.ieee802.org/3/bw/public/Wienchowski_3bw_02_0914.pdf)

# ECU START-UP EXAMPLE 1 PHY MASTER/SLAVE PRE-CONFIGURED



GENERAL MOTORS

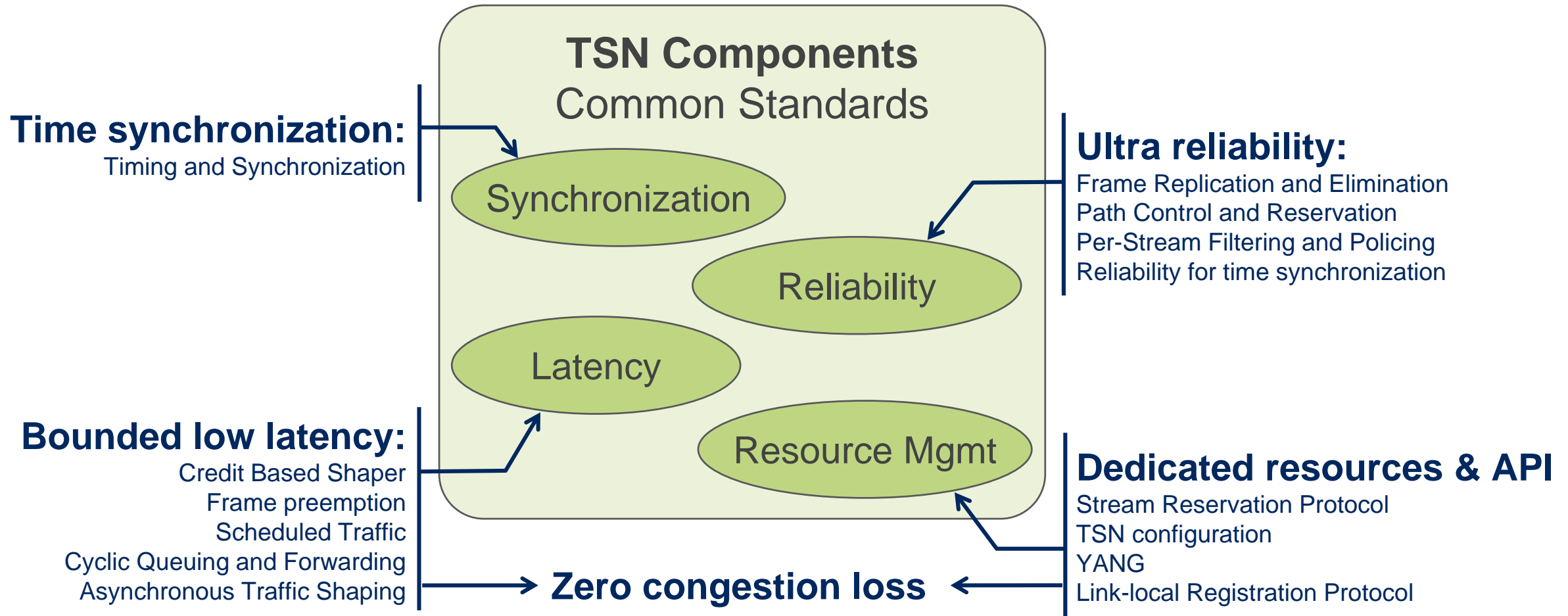
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# **TIME-SENSITIVE NETWORKING**

## **RELIABILITY AND TIMING**

# Time-Sensitive Networking (TSN)



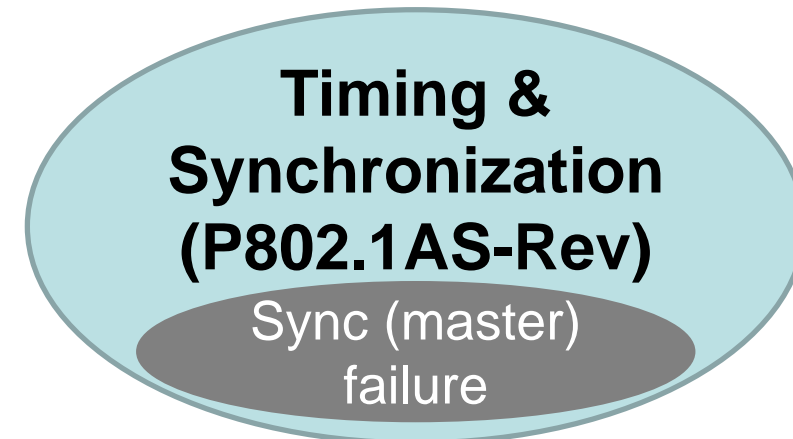
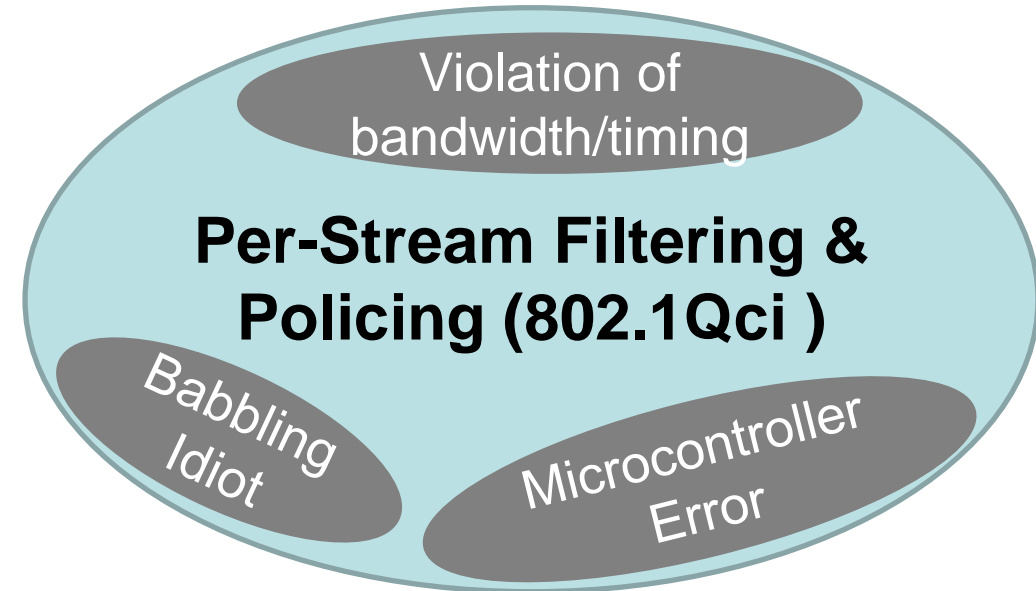
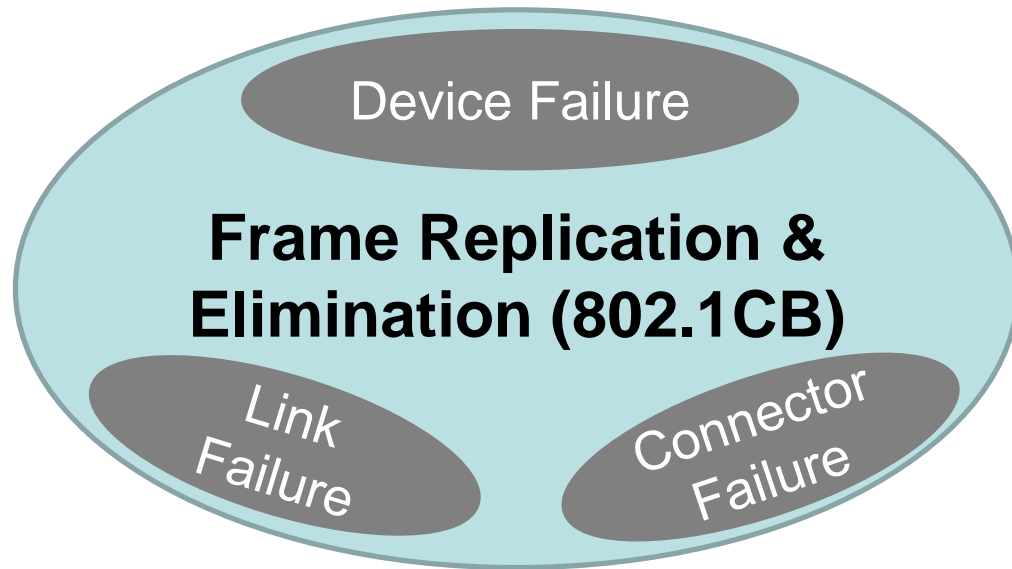
**Guaranteed data transport with bounded low latency, low delay variation, and extremely low loss**

Audio Video Bridging (AVB) → Time-Sensitive Networking (TSN)

# Reliability

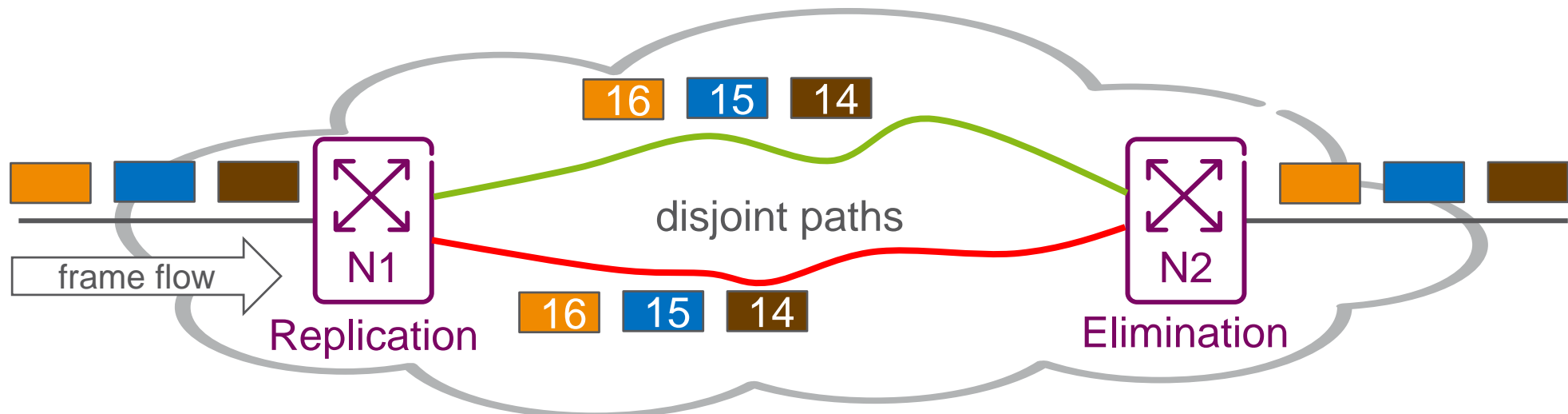
Issue

**TSN support**



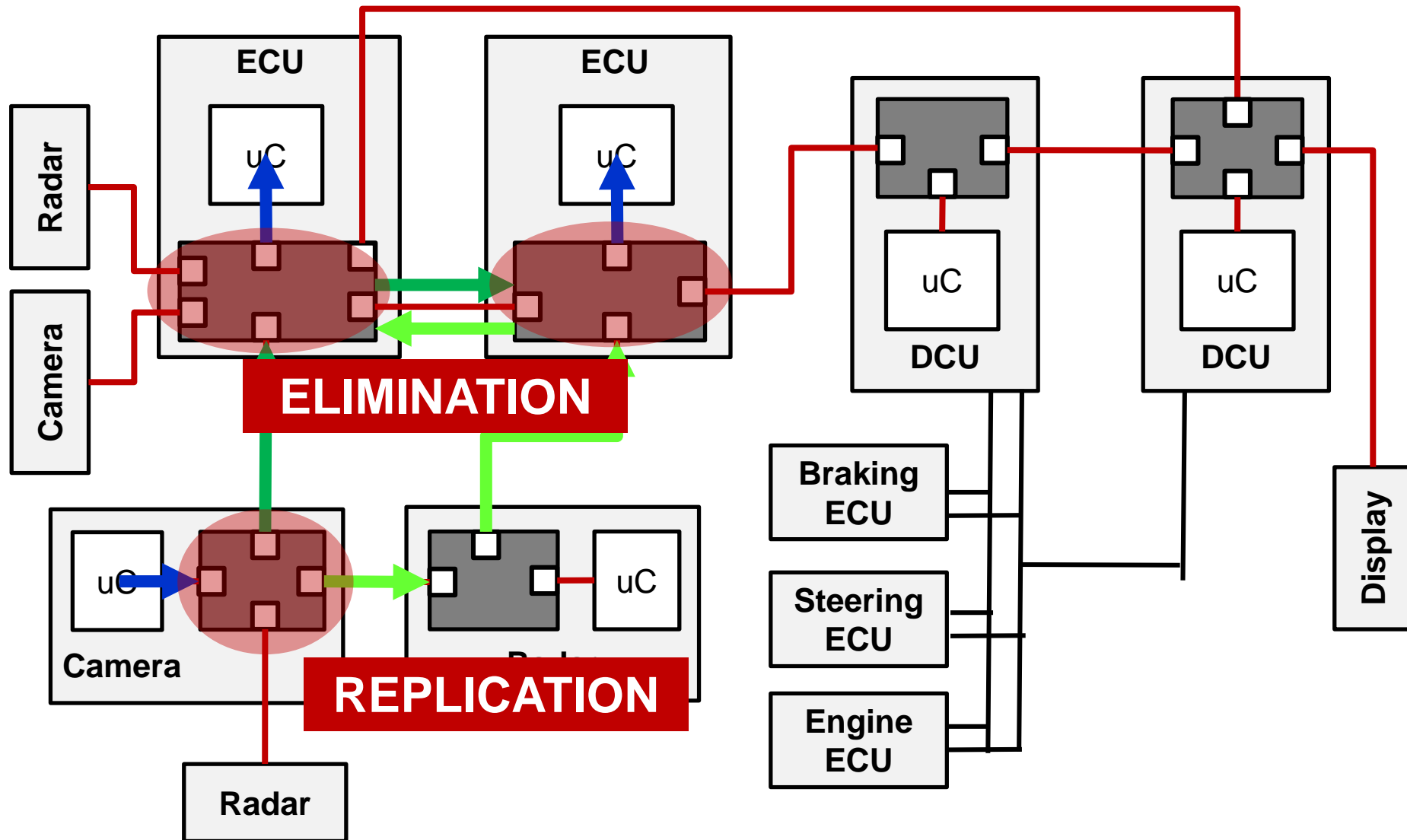
# Frame Replication and Elimination

- Avoid frame loss due to equipment failure (802.1CB)
- Per-frame 1+1 redundancy
  - NO failure detection / switchover
- Serialize frames, send on two maximally disjoint paths, then combine and delete extras

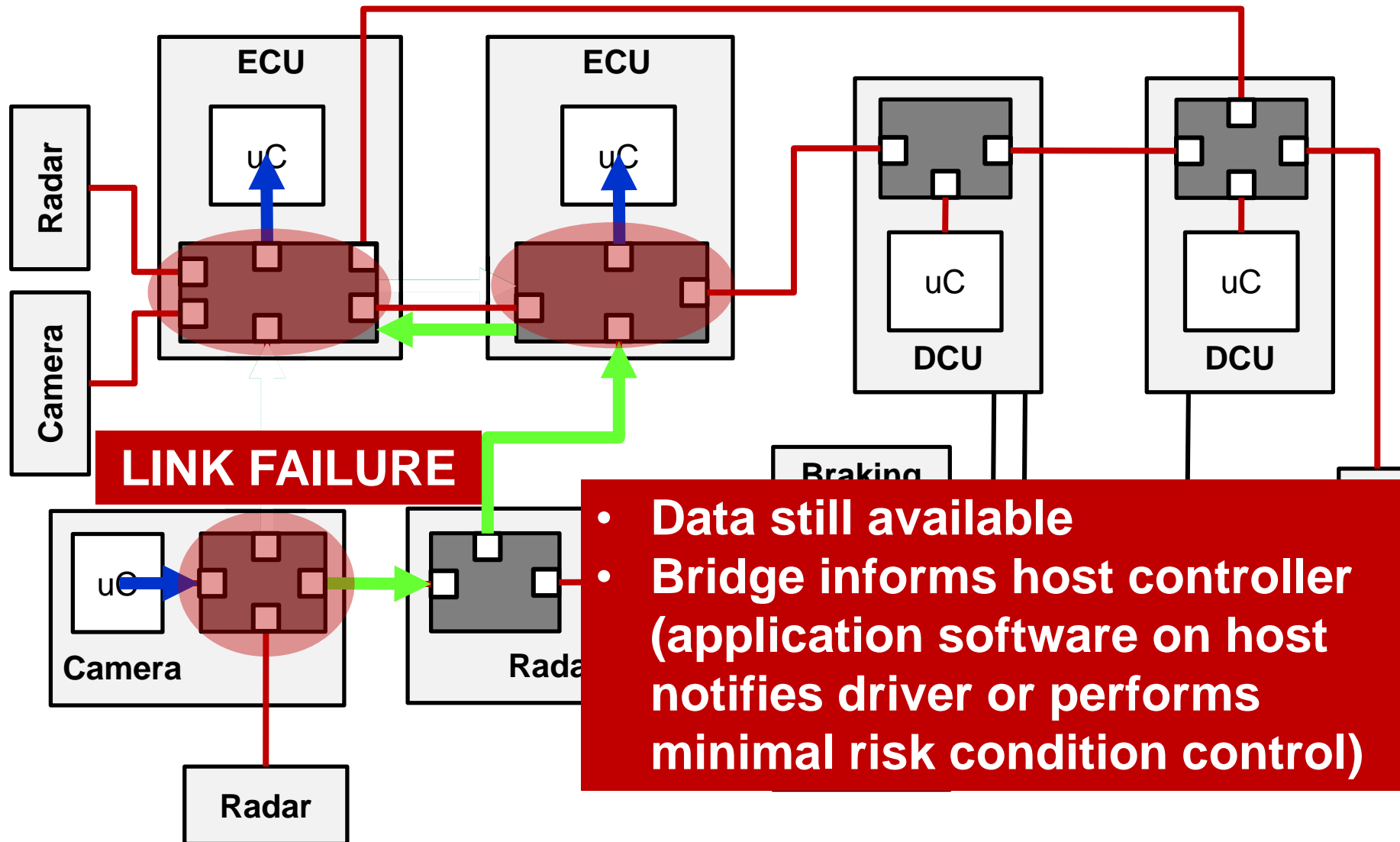




# Frame Replication and Elimination in a Car

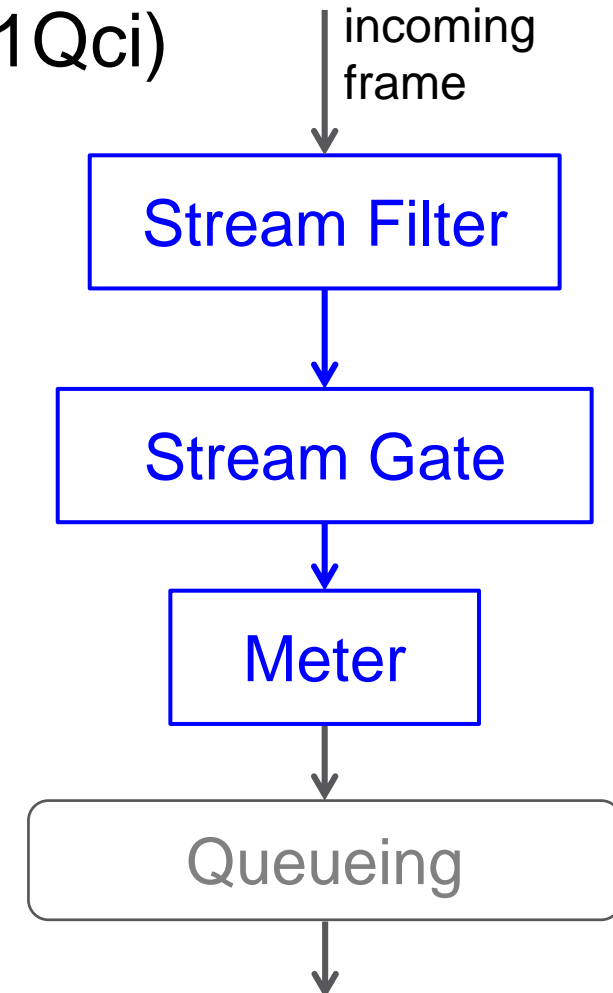


# Frame Replication and Elimination in a Car

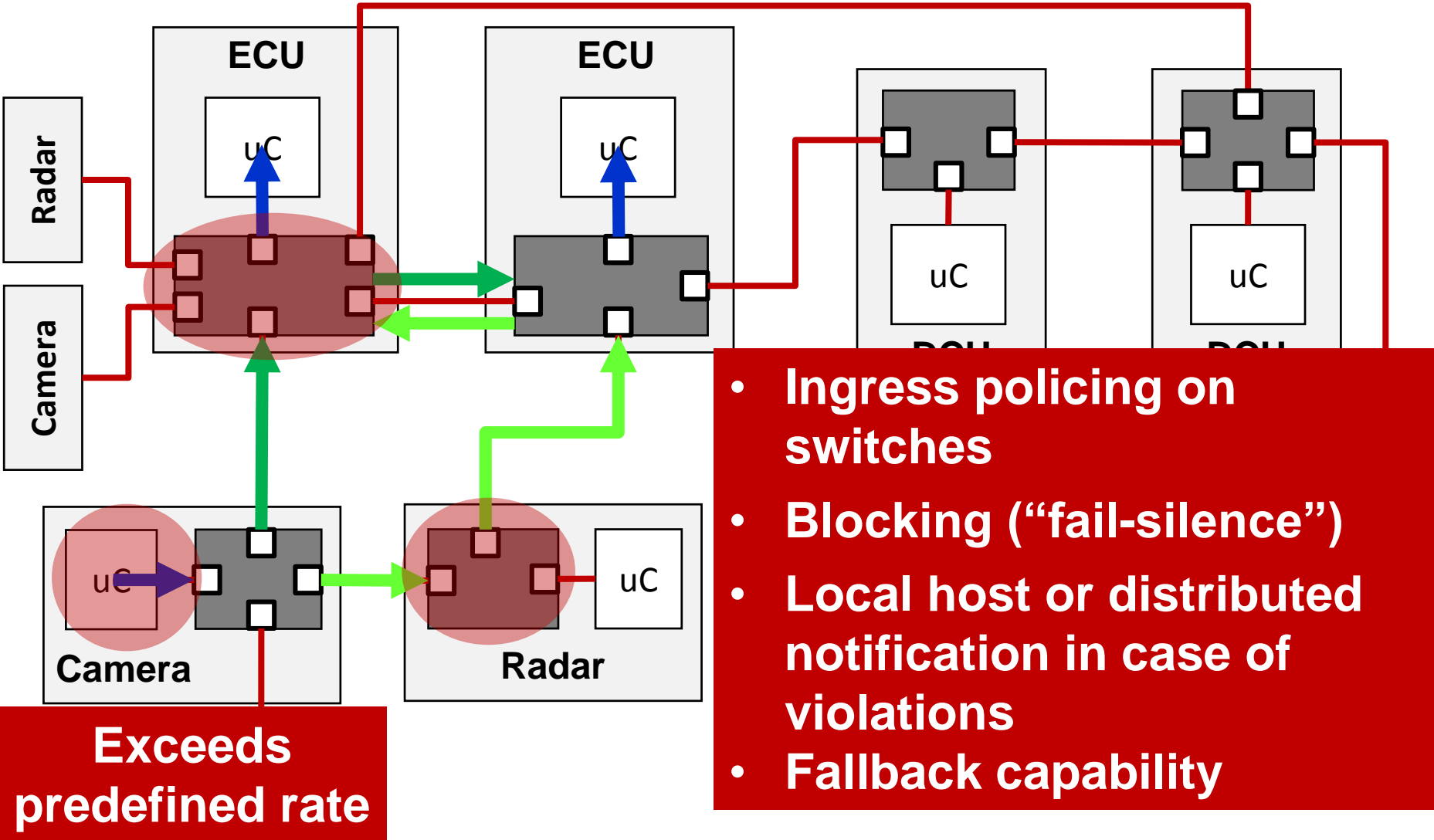


# Per-Stream Filtering and Policing

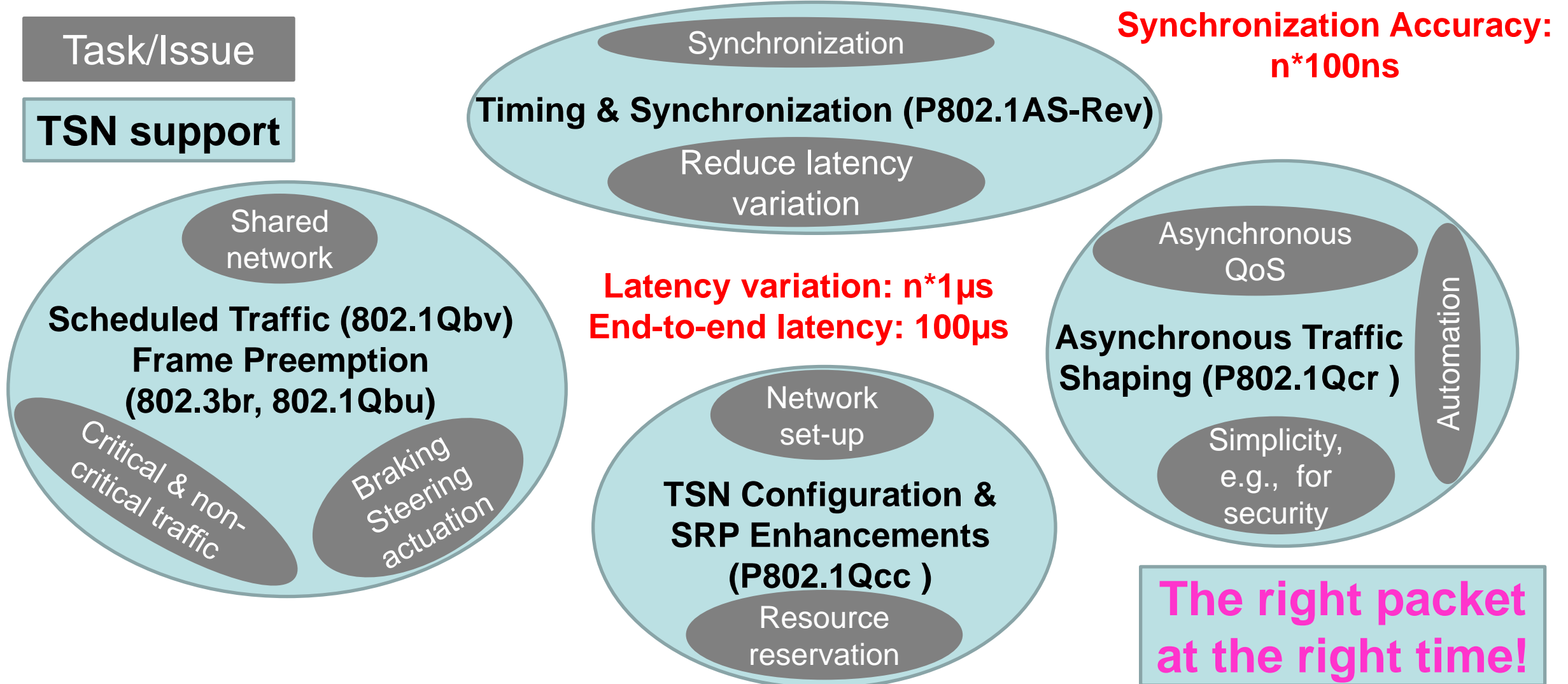
- Protection against bandwidth violation, malfunctioning, malicious attacks, etc. (802.1Qci)
- Decisions on per-stream, per-priority, etc.
- Stream Filter → Defense
  - Filters, Counters
- Stream Gate → Defense
  - Open or Closed
  - can be time-scheduled
- Meter → Defense
  - Bandwidth Profile of MEF 10.3
  - Marking



# Per-Stream Filtering and Policing in a Car



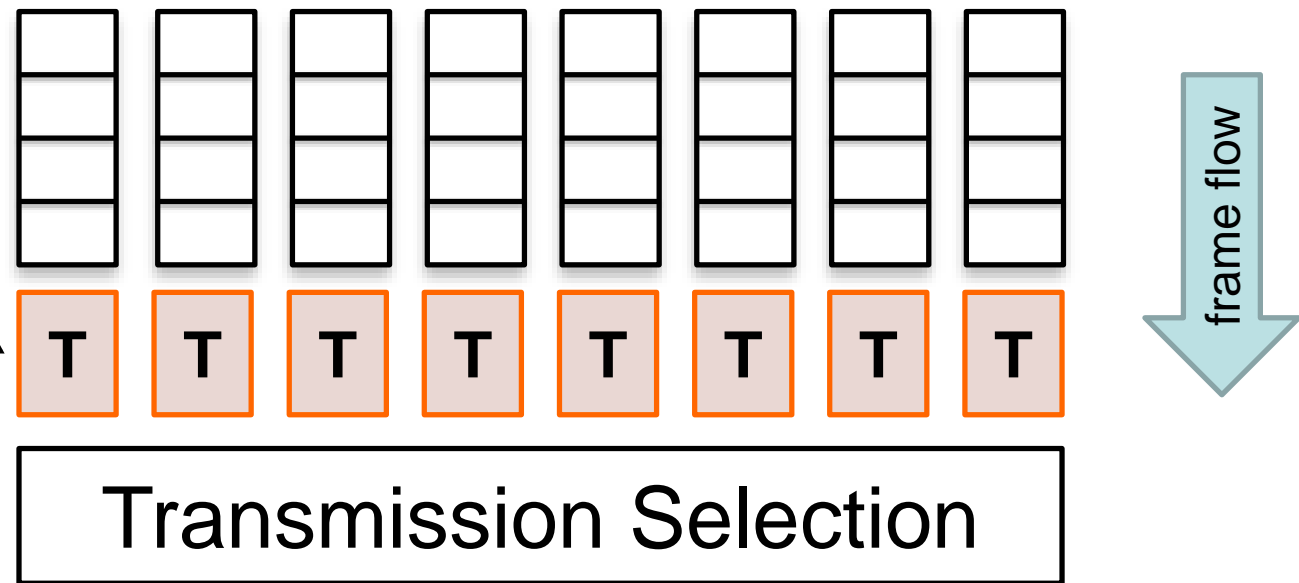
# Deterministic Low Latency





# Scheduled Traffic

- Reduces latency variation for Constant Bit Rate (CBR) streams, which are periodic with known timing
- Time-based control/programming of the 8 bridge queues (802.1Qbv)
- Time-gated queues
- Gate: **Open** or **Closed**
- Periodically repeated time-schedule
- Time synchronization is needed

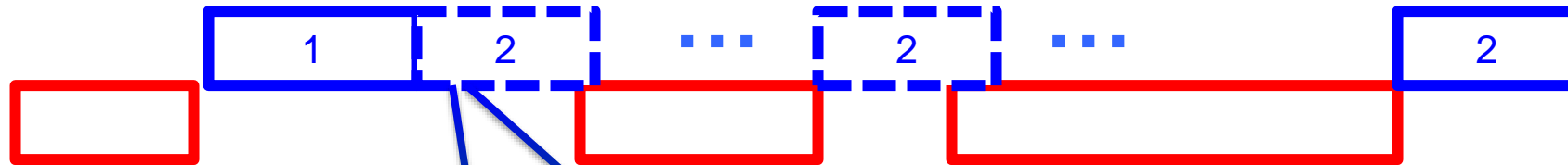


# Frame Preemption

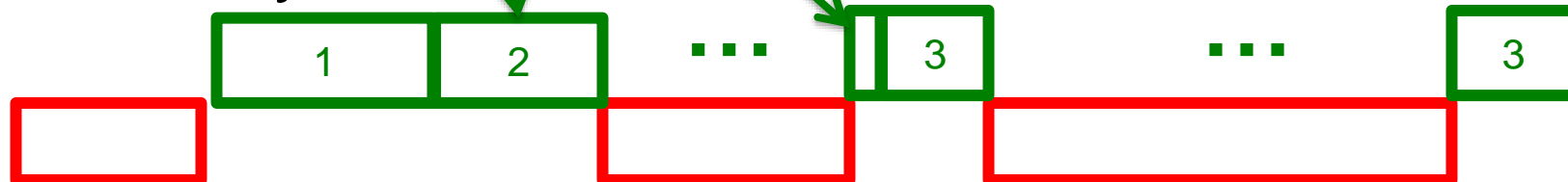
- **Express** frames suspend the transmission of **preemptable** frames (802.3br and 802.1Qbu)
- Scheduled **rocks of critical packets** in each cycle:



- Conflict excessively with **non-guaranteed packet rocks**:



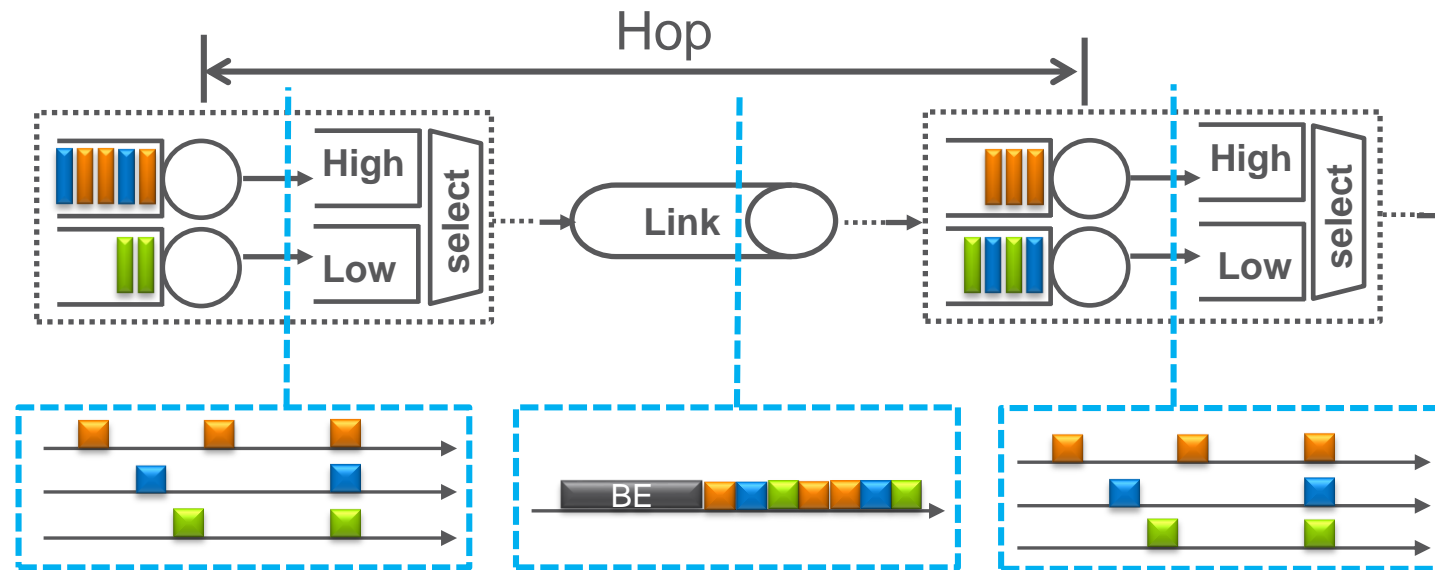
- Problem solved by preemptive **sand** between the **rocks**:  
→ reduced latency variation for **rocks** & more bandwidth for **sand**





# Asynchronous Traffic Shaping

- Zero congestion loss without time synchronization
- Asynchronous Traffic Shaping (P802.1Qcr ATS)
  - Smoothen traffic patterns by re-shaping per hop
  - Prioritize urgent traffic over relaxed traffic



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# SECURITY

# Security

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- What's different about the car network
- Threats
- Countermeasures
- Enrollment, authentication, authorization, ..
  - Knowing what is/what is meant to be attached to the network, where
- Data Authenticity and Integrity
  - Knowing received data was transmitted by the apparent source
  - So filters/policers/shapers operate on trustworthy information, doing what they were intended to do

# Security: The Car Network

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## *What's different about the car network?*

- *As compared to the provider networks, backbone networks, large enterprise and industrial networks 802.1 has worried about in the past*
- Small, simple, though no single blueprint
- Small number of flows
- Severely resource constrained (particularly power)
- Infrequent repair by stopping (roadside or limp home)
  - Can require external network access or equipment
- Network configuration can be/is fixed
  - At least when car is in operation, perhaps by initial build
  - Reliability/redundancy pre-configured/continuously operational

# Security: Threats

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- **Attacks on data recipients *and* resources**
  - Including bandwidth allocation and timing for shared links
- **Wide range of attached devices**
  - Some complex (easily compromised)
  - Some with external access (e.g. infotainment)
  - Problems include accident and misuse as well as malice
  - Can be installed by many different organizations/people
- **Vulnerability**
  - Some links deliberately open: external sensors, trailer hitches etc.
  - Others might be deemed inaccessible, particularly when car is in motion
  - Conventional to consider attacker's cost/benefit vs alternative attack vectors
  - But 'reputational risk' of new technology may skew calculation
  - Can never defend against 'wire cutting' attacks

# Security: Countermeasures

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- Separate functions, separate devices
  - Can securely verify device code/config but not easy
- Fixed network configuration and filters
- Enrollment, authentication, authorization, provisioning
  - Know what is connected where and what it is allowed to do
  - Device Identity → Authorized Device
- Data authenticity and integrity
  - Data received was transmitted by claimed source
  - Authorized Device → Data authenticity and integrity
- Apply filters/policers/shapers to known good data
  - Data authenticity and integrity → Data segregation, limitation
  - An attack that can't arrive at the intended target has been effectively dealt with

# Security: Enrollment .. provisioning

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- Locate the device within the network
  - Don't require separate SKUs per component position
  - Asymmetric VLAN tagging of enrollment/authentication packets
  - Don't trust device's apparent MAC address
- Enrollment and authentication protocol (multiple choices)
  - Supported by 802.1AR X.509 IDevID (Initial Device Identifier)
  - Require Internet (or equivalent) access, assume car stationary
  - Participants: Device, in-car controller, device and car mfr.s
  - Does device belong in this car/compatible with other devices ?
  - Has it been stolen/salvaged/subject to recall ?
  - Install 802.1AR LDevID (Local DevID, can support auth/reauth)
  - Provision device/location dependent & independent addresses/VLANs
  - Provision MACsec CAKs (symmetric crypto keys)

# Security: Data Integrity/Authenticity

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- MACsec Key Agreement (MKA, 802.1X)
  - MACsec CAKs prove prior authentication/authorization
    - Don't reauth every time ignition switched on
  - Can be used without MACsec data protection for non-vulnerable links
    - But see 'reputational risk'
  - Distributes/refreshes MACsec data protecting keys (SAKs)
- MACsec (802.1AE)
  - Full rate constant delay (TSN friendly) implementations
  - Integrity only option (where confidentiality not required)
  - Protection and verification hop-by-hop
  - Single hop can skip over switches (e.g. a Provider Network, 802.1AEcg)
    - Viable where full mesh connectivity not required and intermediate links not vulnerable
    - But see 'reputational risk'



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# SUMMARY

# Summary

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- Automotive networks have requirements not usually seen in the enterprise
- 802.3 PHYs provide fast start-up, automotive EMC performance, and support smaller, lighter-weight media
- 802.1 provides reliability and deterministic latency
- 802.1 provides security

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# Q & A

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# Thank You!

# Further Reading

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- [IEEE Std 802.3bf -2011](#) Media Access Control (MAC) Service Interface and Management Parameters to Support Time Synchronization Protocols
- [IEEE Std 802.3bp -2016](#) Physical Layer Specifications and Management Parameters for 1 Gb/s Operation over a Single Twisted-Pair Copper Cable (1000BASE-T1)
- [IEEE Std 802.3bw -2015](#) Physical Layer Specifications and Management Parameters for 100 Mb/s Operation over a Single Balanced Twisted Pair Cable (100BASE-T1)
- [IEEE Std 802.3br-2016](#) Specification and Management Parameters for Interspersing Express Traffic
- [P802.3.2 \(IEEE 802.3cf\)](#) YANG Data Model Definitions Task Force
- [P802.3cg](#) 10 Mb/s Single Twisted Pair Ethernet Task Force
- [P802.3ch](#) Multi-Gig Automotive Ethernet PHY Task Force

# Further Reading

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- <http://www.ieee802.org/1,>  
<http://www.ieee802.org/1/pages/tsn.html>
- [IEEE 802.1 TSN for Automotive – flyer](#)
- [Introduction to IEEE 802.1 TSN](#)
- [A Time-Sensitive Networking Primer: Putting It All Together](#)
- [Heterogeneous Networks for Audio and Video: Using IEEE 802.1 Audio Video Bridging](#)
- [Tutorial on IEEE 802.3br Interspersing express traffic \(IET\) and IEEE 802.1 Time-Sensitive Networking](#)
- [Tutorial on Deterministic Ethernet](#)

# Further Reading

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- [IEEE Std 802.1AE-2006](#) MAC Security
- [IEEE Std 802.1AEbn-2011](#) Amendment: GCM-AES-256 Cipher Suite
- [IEEE Std 802.1AEbw-2013](#) Amendment: Extended Packet Numbering
- [IEEE Std 802.1X-2010](#) Port-Based Network Access Control
- [IEEE Std 802.1Xbx-2014](#) Amendment: MAC Security Key Agreement Protocol (MKA) Extensions
- [P802.1AR-Rev/D2.2](#) Secure Device Identity
- [P802.1Xck](#) Amendment: YANG Data Model
- [RFC 7030](#) Enrollment over Secure Transport