



ETHERNOVIA

VIRTUALIZING VEHICLE COMMUNICATION



Drift Measurement TLV

Consequences for the use of Announce in
static configuration networks

2023-01-20

Drift Measurement TLV

Process

- Added to ASdm
- PAR and CSD modification discussion this afternoon
- Comment on next draft of ASdm
 - Including detailed contribution?
- Current intent is that TLV includes...
 - Sync message TX timestamp (similar to pDelayResp)
 - stepsRemoved (same as Announce)
 - Grand Master Identity (same as Announce)

<https://www.ieee802.org/1/files/public/docs2023/60802-McCall-Time-Sync-Update-16-Jan-0123-v01.pdf>

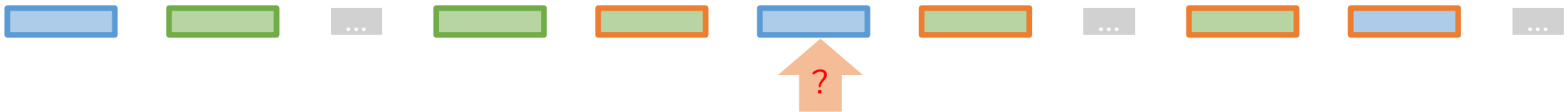
Assumptions and prerequisites

- This argument assumes a fully static network configuration and therefore a pre-determined sync-tree for all (error) cases and domains – i.e. full external port configuration!
- Changes to the GM identity or the number of hops (steps removed) is only relevant in a specific AS-Domain!
- The AS domainNumber is the only element linking Announce and Sync/FollowUp messages.
- Sync/FollowUp (w/ Drift Measurement TLV) and Announce are sent at significantly different intervals, with the Announce interval assumed to be longer.
- Sync/FollowUp (w/ Drift Measurement TLV) and Announce are triggered by independent state machines.

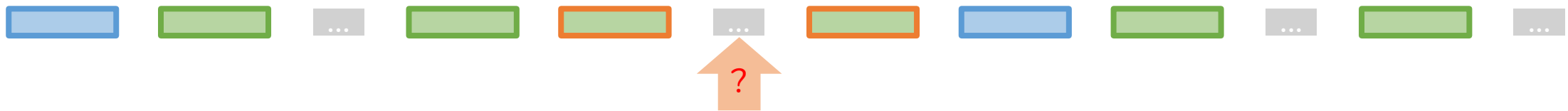
Two difficult examples



Case 1:



Case 2:



time

Conclusion and suggestion

- The combination of using Sync/FollowUp with Drift Measurement TLV AND Announce likely raises more handling questions than it helps an implementation.
- Use either Announce OR Sync/FollowUp with Drift Measurement TLV.
- **Add this as an informative statement in ASdm.**
- Do not(!) try to resolve the handling questions from using both in ASdm.



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THANK YOU

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