

Comparison of 802.1AS Annex B and P60802 Clock Stability

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Outline

- ❑ Introduction
- ❑ P60802 phase and frequency variation
- ❑ Background on clock stability and TDEV
- ❑ 802.1AS (2011 and 2020) clock stability (measurements)
- ❑ Comparison of P60802 and 802.1AS clock stability
- ❑ Conclusions

Introduction - 1

- IEC/IEEE P6802 gives the following requirements for the free-running clock in a PTP Instance:
 - Maximum fractional frequency offset: 100 ppm
 - Maximum rate of change of fractional frequency offset: 3 ppm/s
- In discussions in several P60802 meetings, one or more participants have indicated that previous simulations/analyses they or their colleagues have done assumed sinusoidal phase and frequency variation that meet the above requirements
- IEEE Std 802.1AS-2011, and the soon to be published 802.1AS-2020, have a TDEV requirement for clock stability of a PTP Instance in Annex B, Figure B-1
 - This requirement states that TDEV shall not exceed $5.0 \cdot \tau$ ns, where the observation interval τ is the range $0.05 \text{ s} \leq \tau \leq 10 \text{ s}$ (Table B-1/802.1AS), when measured using
 - A measurement interval that is at least 120 s (i.e., at least 12 times the longest observation interval),
 - A low-pass filter with 3 dB bandwidth of 10 Hz, first-order characteristic, and 20 dB/decade roll-off, and
 - A sampling interval that does not exceed 1/30 s.

Introduction - 2

- The TDEV requirement (mask) of Annex B/802.1AS is based on measurements reported in [2]
 - These measurements were made for an inexpensive oscillator, intended for consumer Audio/Video applications
- The purpose of the current presentation is to compare the above P60802 clock requirements with the Annex B/802.1AS TDEV requirement

P60802 Phase and Frequency Variation - 1

□ We will assume sinusoidal phase variation, and choose the amplitude and frequency of the variation such that

- Maximum frequency offset = 100 ppm
- Maximum rate of change of frequency offset = 3 ppm/s

□ Sinusoidal phase variation:

$$x(t) = A \sin(2\pi ft)$$

where

A = amplitude of the variation (units of time)

f = frequency of the variation (Hz)

P60802 Phase and Frequency Variation - 2

□ Then the frequency and rate of change of frequency are:

$$y(t) = \dot{x}(t) = 2\pi fA \cos(2\pi ft)$$

$$\dot{y}(t) = -4\pi^2 f^2 A \sin(2\pi ft)$$

□ Then, if f is in Hz and A is in s, the maximum frequency offset and drift rate requirements give

$$2\pi fA = 10^{-4} \text{ (i.e., 100 ppm)}$$

$$4\pi^2 f^2 A = 3 \times 10^{-6} \text{ s}^{-1} \text{ (i.e., 3 ppm/s)}$$

P60802 Phase and Frequency Variation - 3

□ Solving the above for f and A gives

$$2\pi fA = 10^{-4} \text{ (i.e., 100 ppm)}$$

$$\frac{4\pi^2 f^2 A}{2\pi fA} = 2\pi f = \frac{3 \times 10^{-6} \text{ s}^{-1}}{10^{-4}} = 0.03 \text{ s}^{-1}$$

□ Then

$$f = \frac{0.03}{2\pi} \text{ Hz} = 4.7746 \times 10^{-3} \text{ Hz} = 4.7746 \text{ mHz}$$

$$2\pi fA = 0.03A = 10^{-4}$$

$$A = \frac{10^{-4}}{0.03} \text{ s} = 0.00333 \text{ s} = 3.33 \text{ ms}$$

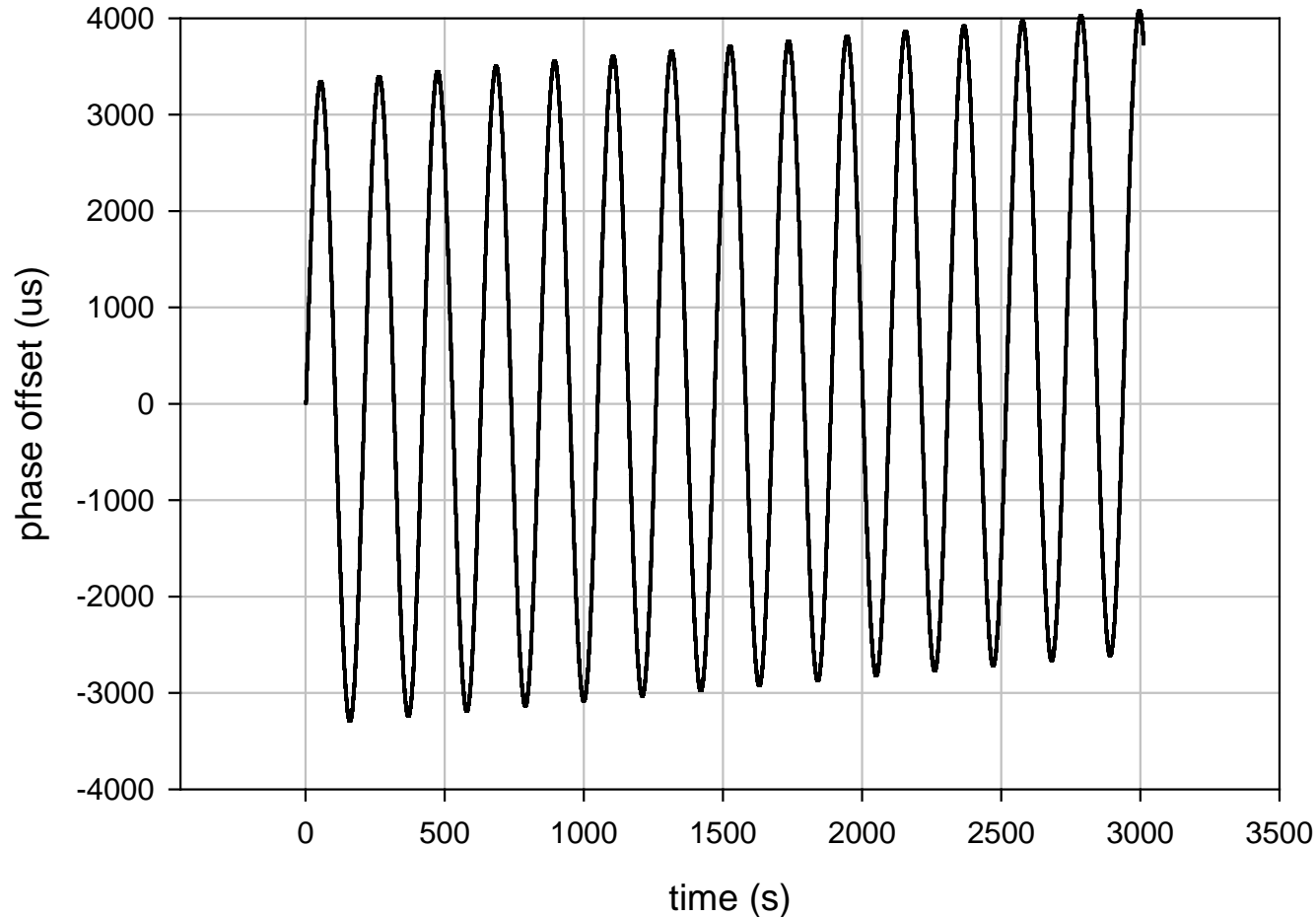
□ Note that the phase variation has relatively large amplitude and low frequency; plots of phase and frequency variation are on the following slides

P60802 Phase and Frequency Variation - 4

P60802 phase offset

Maximum frequency offset = 100 ppm

Maximum frequency drift rate = 3 ppm/s

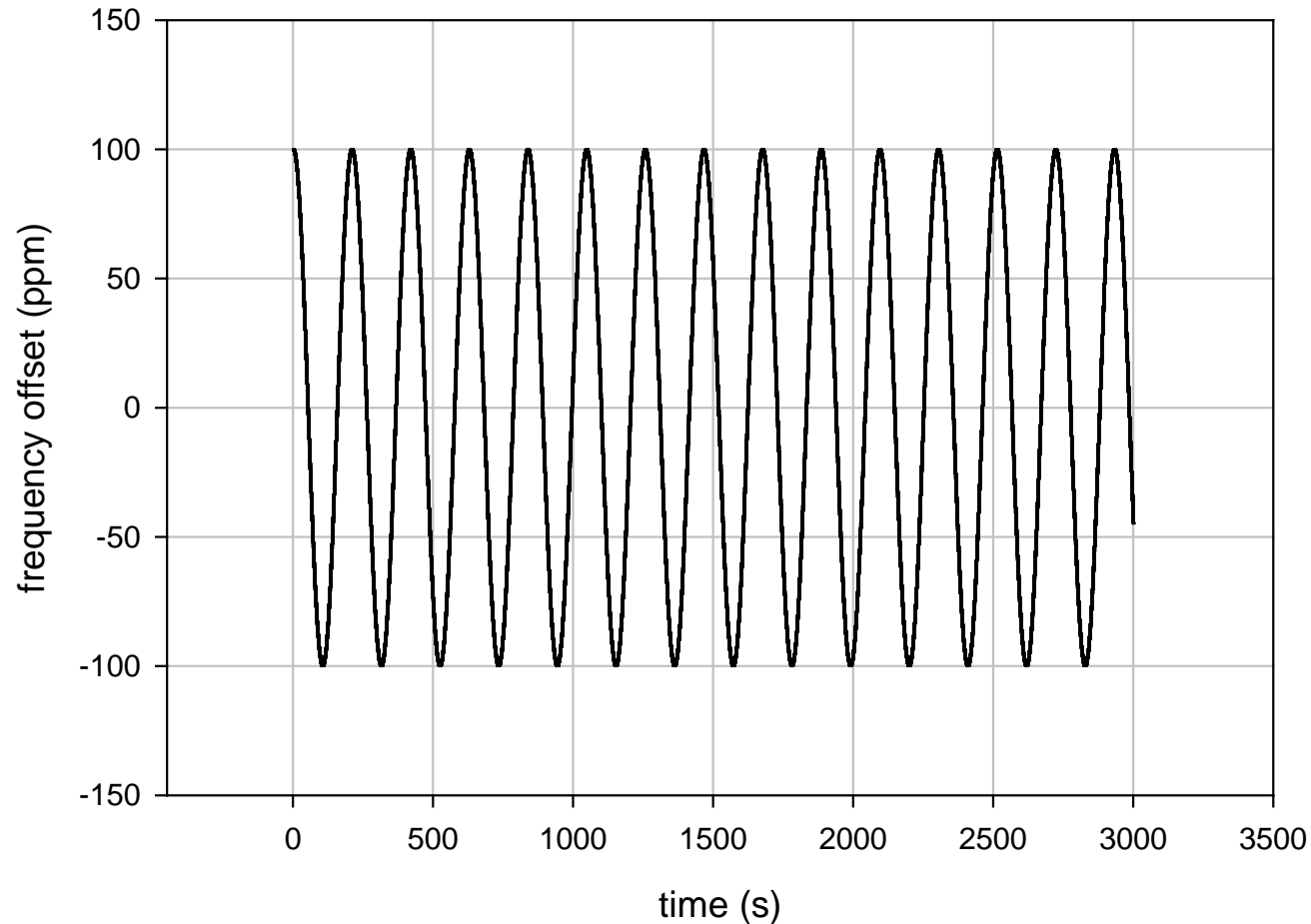


P60802 Phase and Frequency Variation - 5

P60802 frequency offset

Maximum frequency offset = 100 ppm

Maximum frequency drift rate = 3 ppm/s



Background on Clock Stability and TDEV - 1

- ❑ Most of the material in this section (slides 10-30) is taken from [3]
- ❑ It is presented here because many current participants of 802.1, and most IEC participants, were not attending 802.1 when [3] was originally presented (in July 2010)
- ❑ References [4], [5], and [8] contain a great deal of background material and cite many additional references
- ❑ The current presentation does not cover the material in [3] on simulation of power-law noise processes, as that material is needed here
 - That material will be needed for future presentations that present simulations

Background on Clock Stability and TDEV - 2

- Clock phase noise is typically modeled as a sum of random processes with one-sided power spectral density (PSD) of the form $Af^{-\alpha}$
- In the most general case usually considered in practice, 5 terms are considered (see [4] and [5])
 - $\alpha = 0$, White Phase Modulation (WPM)
 - $\alpha = 1$, Flicker Phase Modulation (FPM)
 - $\alpha = 2$, White Frequency Modulation (WFM)
 - $\alpha = 3$, Flicker Frequency Modulation (FFM)
 - $\alpha = 4$, Random-Walk Frequency Modulation (RWFM)

□ Can write the PSD, $S_x(f)$ as

$$S_x(f) = \frac{A}{f^4} + \frac{B}{f^3} + \frac{C}{f^2} + \frac{D}{f} + E, \text{ where } S_x(f) \text{ has units of ns}^2/\text{Hz}$$

- Often express as (ν_0 = nominal clock frequency)

$$S_\phi(f) = (2\pi\nu_0)^2 S_x(f), \text{ where units of } S_\phi(f) \text{ are rad}^2/\text{Hz}$$

□ The above processes are non-stationary; background on PSD for non-stationary processes is given in [8]

Background on Clock Stability and TDEV - 3

- Often, the one-sided PSD $S_{\phi}(f)$ is expressed in dBc/Hz, using the conversion

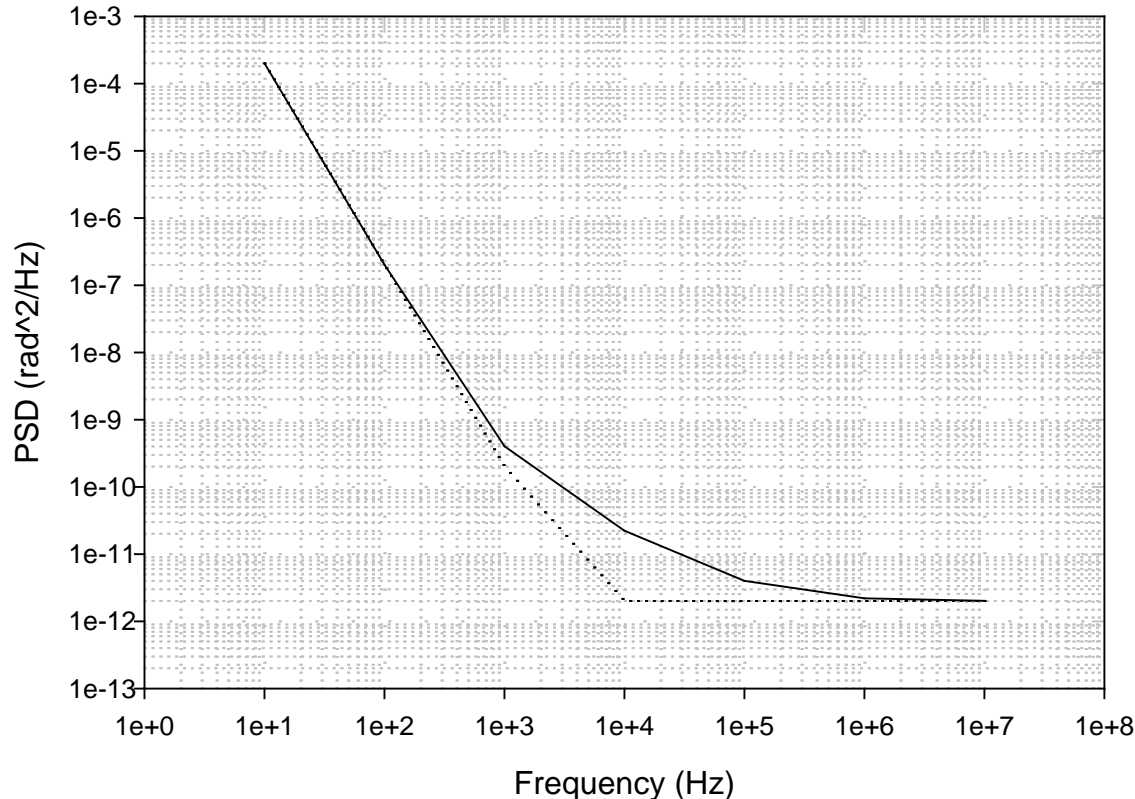
$$S_{\phi}(f) \text{ [dBc/Hz]} = 10 \log_{10} \{ S_{\phi}(f) \text{ [rad}^2\text{/Hz]} \}$$

- Must be careful on whether the PSD is one-sided or two-sided; respective equations will contain additional factors of 2 in converting between them
- An example PSD specification is given in Figure 12 of [7], and reproduced on the next slide (note that a similar example is given in Figure 2 of [6])
 - Data in [7] is given in dBc/Hz; data has been converted to rad²/Hz
 - Data in [7] is given only for frequencies below 10 kHz; here, we assume the PSD is flat above 10 kHz
 - Dotted curve on the next slide is the converted data of [7]; solid line is a conservative fit of the above power law sum
- The above example specification contains WPM, FPM, and FFM terms
 - In the wander region ($f \leq 10$ Hz), the FFM term (B/f^3) dominates
 - The 802.1AS wander generation specification is based on FFM behavior

Background on Clock Stability and TDEV - 4

**Example Clock Phase Noise Specification
Provided in [7] (data in [7] does not extend
above 10 kHz; PSD is assumed flat for higher
frequencies with the 10 kHz value)**

— analytic form of PSD
..... specification in [7]



Note: Data in [7]
is given in dBc/Hz;
data has been
converted to rad^2/Hz

Background on Clock Stability and TDEV - 5

- Another measure for clock noise, which is more convenient because it is a time domain parameter, is Time Variance (TVAR) [4], [5]
 - Time Deviation (TDEV) is the square root of TVAR
- TVAR is 1/6 times the expectation of the square of the second difference of the phase error averaged over an interval
 - TVAR is related to Modified Allan Variance (MVAR) (see next slide), which is in turn a generalization of Allan Variance (AVAR)

$$\text{TVAR}(\tau) = \frac{1}{6} E\left[\left(\Delta^2 \bar{x}\right)^2\right]$$

where $E[\cdot]$ denotes expectation,

\bar{x} denotes average over the integration time τ ,

and Δ^2 denotes second difference

Background on Clock Stability and TDEV - 6

□ TVAR may be estimated from measured or simulated data using [5]

$$\text{TVAR}(n\tau_0) = \frac{1}{6n^2(N-3n+1)} \sum_{j=1}^{N-3n+1} \left[\sum_{i=j}^{n+j-1} (x_{i+2n} - 2x_{i+n} + x_i) \right]^2, \quad n = 1, 2, \dots, \text{integer part}(N/3)$$

where τ_0 is the sampling interval and $\tau = N\tau_0$

□ TVAR is equal to $\tau^2/3$ multiplied by the Modified Allan Variance

□ For power-law noises with PSD proportional to $f^{-\alpha}$, TVAR is proportional to τ^β , where $\beta = \alpha - 1$

□ Note also that PTP Variance in 1588 (from which offsetScaledLogVariance is obtained) is equal to $\tau^2/3$ multiplied by the Allan Variance

Background on Clock Stability and TDEV - 7

□ The magnitude of TVAR may be related to the magnitude of PSD for power-law noises; see [4] and [5] for details

▪ FFM $S_x(f) = \frac{B}{f^3}$ $\text{TVAR}(\tau) = \frac{(2\pi)^2 9 \ln 2}{20} B \tau^2$

▪ WFM $S_x(f) = \frac{C}{f^3}$ $\text{TVAR}(\tau) = \frac{(2\pi)^2}{12} C \tau$

▪ FPM (result is from [4]; a more exact expression is given in [5])

$$S_x(f) = \frac{D}{f} \quad \text{TVAR}(\tau) = \frac{3.37}{3} D$$

▪ WPM $S_x(f) = E$ $\text{TVAR}(\tau) = \frac{\tau_0 f_h}{\tau} E$

f_h = noise bandwidth

Background on Clock Stability and TDEV - 8

- TVAR and TDEV (or Allan Variance or Modified Allan Variance) are used to characterize phase noise in oscillators rather than classical variance
 - The time-domain estimator for classical variance diverges for some power-law noise processes
 - The time-domain estimators for TVAR, Allan Variance, and Modified Allan Variance converge for all power-law noise processes
- For the 802.1AS Annex B, Figure B-1 TDEV mask

$$\text{TDEV}(\tau) = 5 \times 10^{-9} \tau \quad 0.05 \text{ s} \leq \tau \leq 10 \text{ s}$$

$$\frac{(2\pi)^2 9 \ln 2}{20} B = (5 \times 10^{-9})^2$$

$$B = \frac{(5 \times 10^{-9})^2 (20)}{(2\pi)^2 9 \ln 2} \text{ s}^2/\text{Hz} = 2.0302 \times 10^{-18} \text{ s}^2/\text{Hz}$$

$$B = 2.0302 \text{ ns}^2/\text{Hz}$$

802.1AS Clock Stability

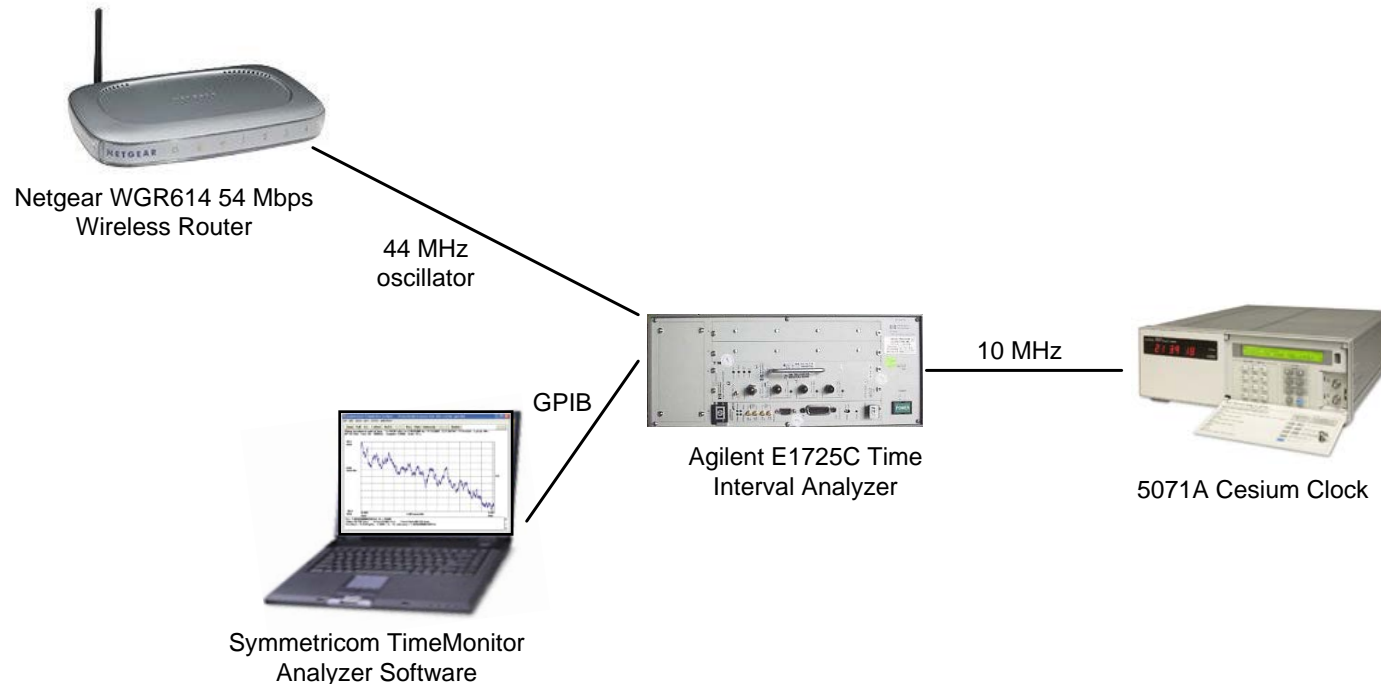
- ❑ This section describes the measurements of [2], on which the current Annex B/802.1AS TDEV requirement is based
- ❑ The slides are reproduced from [2], with minor modifications (e.g., updating of footers)
- ❑ The intent was to measure the wander performance of an inexpensive, oscillator that might be used in a consumer-grade product (in this case a consumer-grade wireless router)
- ❑ Note that at the time the measurements were made, the draft 802.1AS TDEV requirement (mask) was one-half its current value, i.e., its level was $2.5 \cdot \tau$ ns, rather than $5 \cdot \tau$ ns (i.e., it was more stringent)
 - As a result of these measurements, the mask level was doubled, i.e., the requirement was made less stringent
 - Subsequent simulations were run using the new mask
- ❑ The author of the current presentation would like to acknowledge Lee Cosart (the first author of [2]), who made the measurements

Measurement Setup - 1

- ❑ The measurement was made using an Agilent E1725C Time Interval Analyzer
 - Measurement data collected and analyzed using Symmetricom TimeMonitor Analyzer software
 - E1725C has a single shot timing resolution of 50 ps, more than adequate for this test
- ❑ A 10 MHz reference was supplied to the time interval analyzer from a 5071A Cesium clock
- ❑ The measured oscillator was contained in a consumer-grade wireless router product – the Netgear WGR614 54 Mbps Wireless Router
 - 802.11g wireless
 - 4 10/100 Mbit/s Ethernet LAN ports
 - 1 10/100 Mbit/s Ethernet WAN port
 - The measurements were made on one sample device (i.e., one unit)
- ❑ The oscillator was accessed by removing the top of the wireless router and using an oscilloscope probe

Measurement Setup - 2

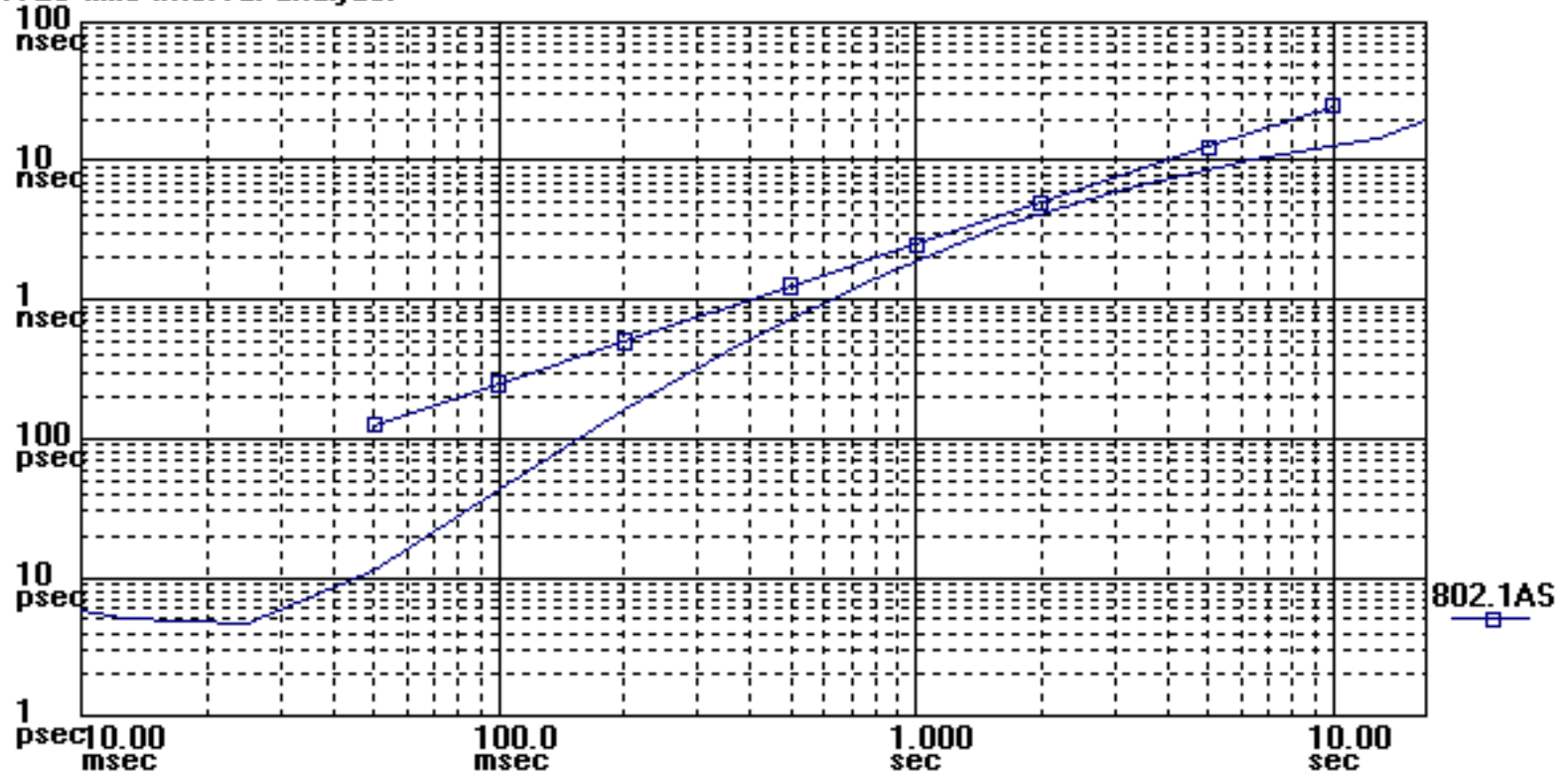
- Initially, samples were collected over 50 s at a rate of 2.5 kHz
 - Later test used 1000 s measurement interval
- Timestamps were converted to phase deviation, for the TDEV calculation
- The measured oscillator frequency was approximately 44 MHz



Measurement Results - 1

- TDEV result – first 50 s measurement
 - Passes, though not with a large margin

Symmetricom TimeMonitor Analyzer (file=Netgear256k_50s.pan)
TDEV; Fo=44.00 MHz; Fs=2.560 kHz; 2009/10/20; 14:37:05
HP E1725 time interval analyzer



Measurement Results - 2

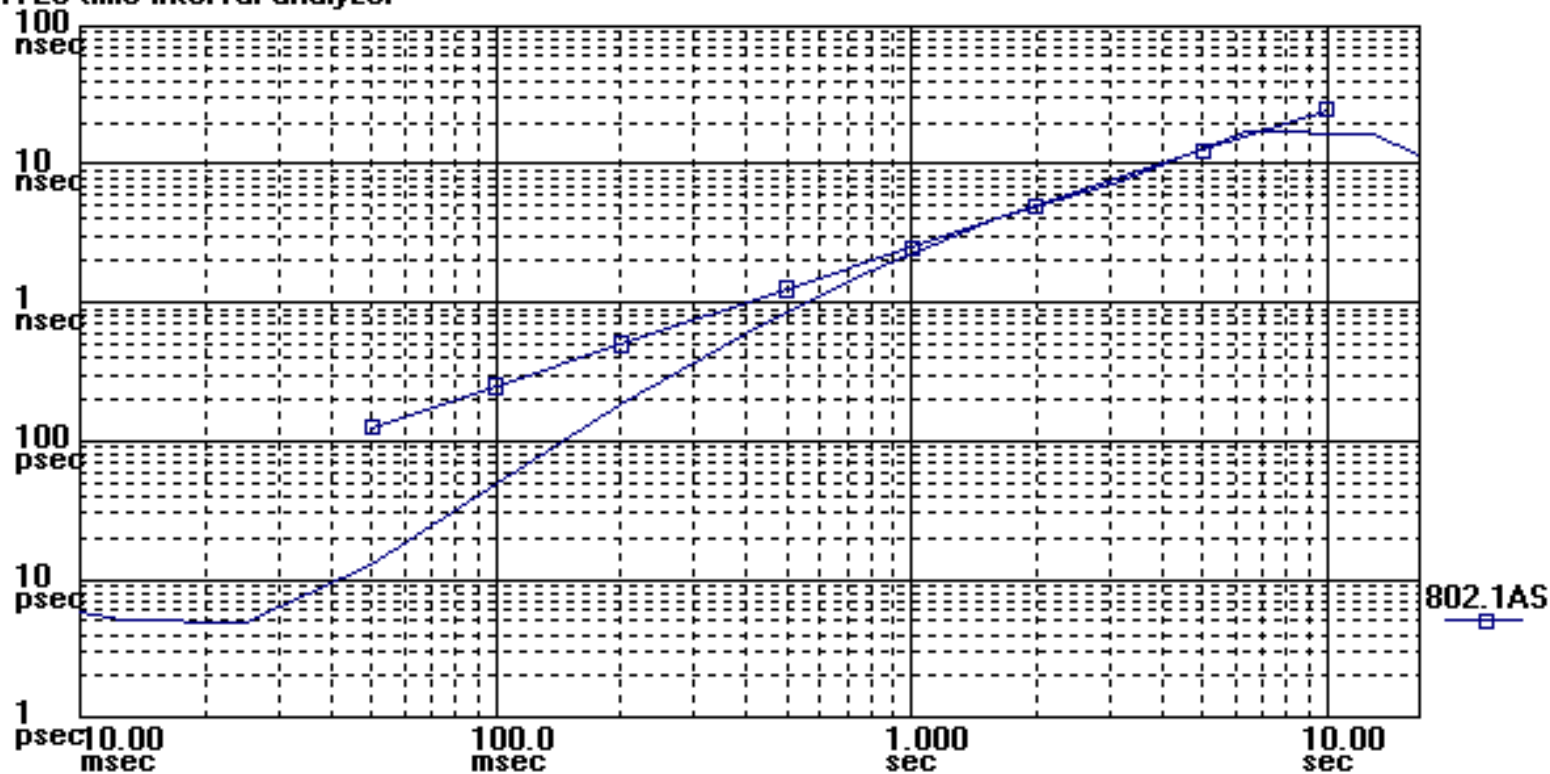
□ TDEV result – second 50 s measurement

- Marginally fails

Symmetricom TimeMonitor Analyzer (file=Netgear256k_50s_2.pan)

TDEV; Fo=44.00 MHz; Fs=2.560 kHz; 2009/10/20; 14:37:55

HP E1725 time interval analyzer

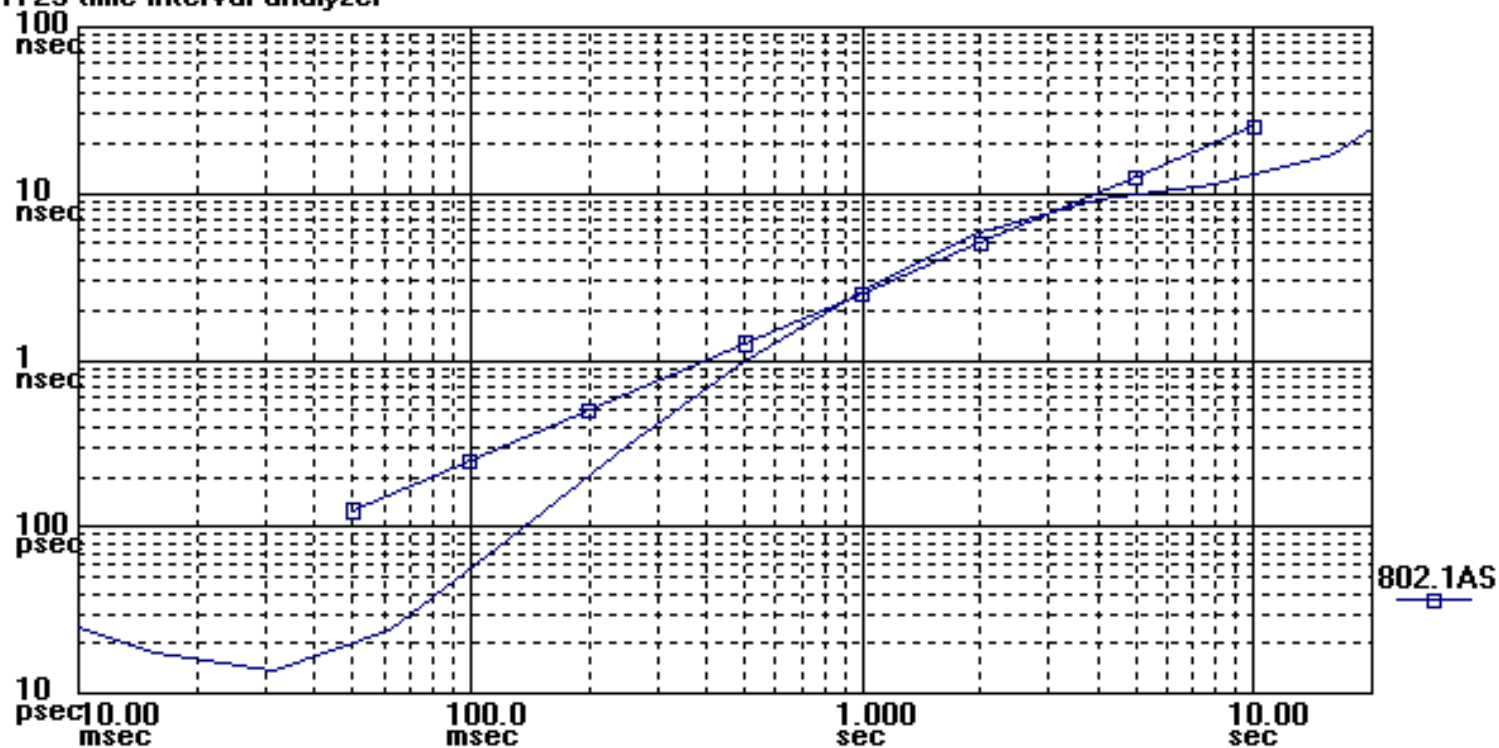


Measurement Results - 3

□ TDEV result – 1000 s measurement

- Marginally fails

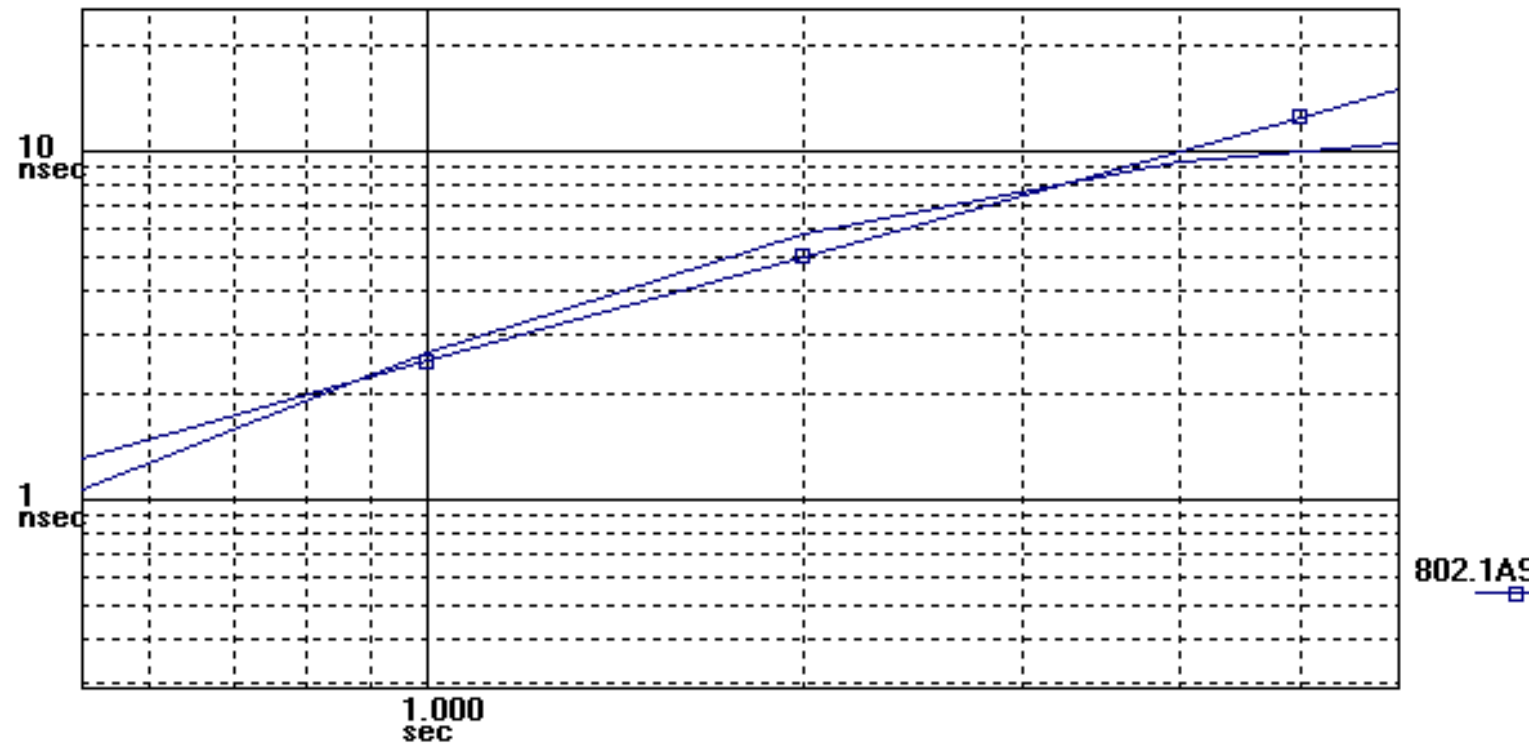
Symmetricom TimeMonitor Analyzer (file=Netgear256k_1000s.pan)
TDEV; Fo=44.00 MHz; Fs=256.0 Hz; 2009/10/20; 14:40:44
HP E1725 time interval analyzer



Measurement Results - 4

- TDEV result – 1000 s measurement, region of marginal failure
 - Mask is exceeded by approximately 16%, at 2 s observation interval

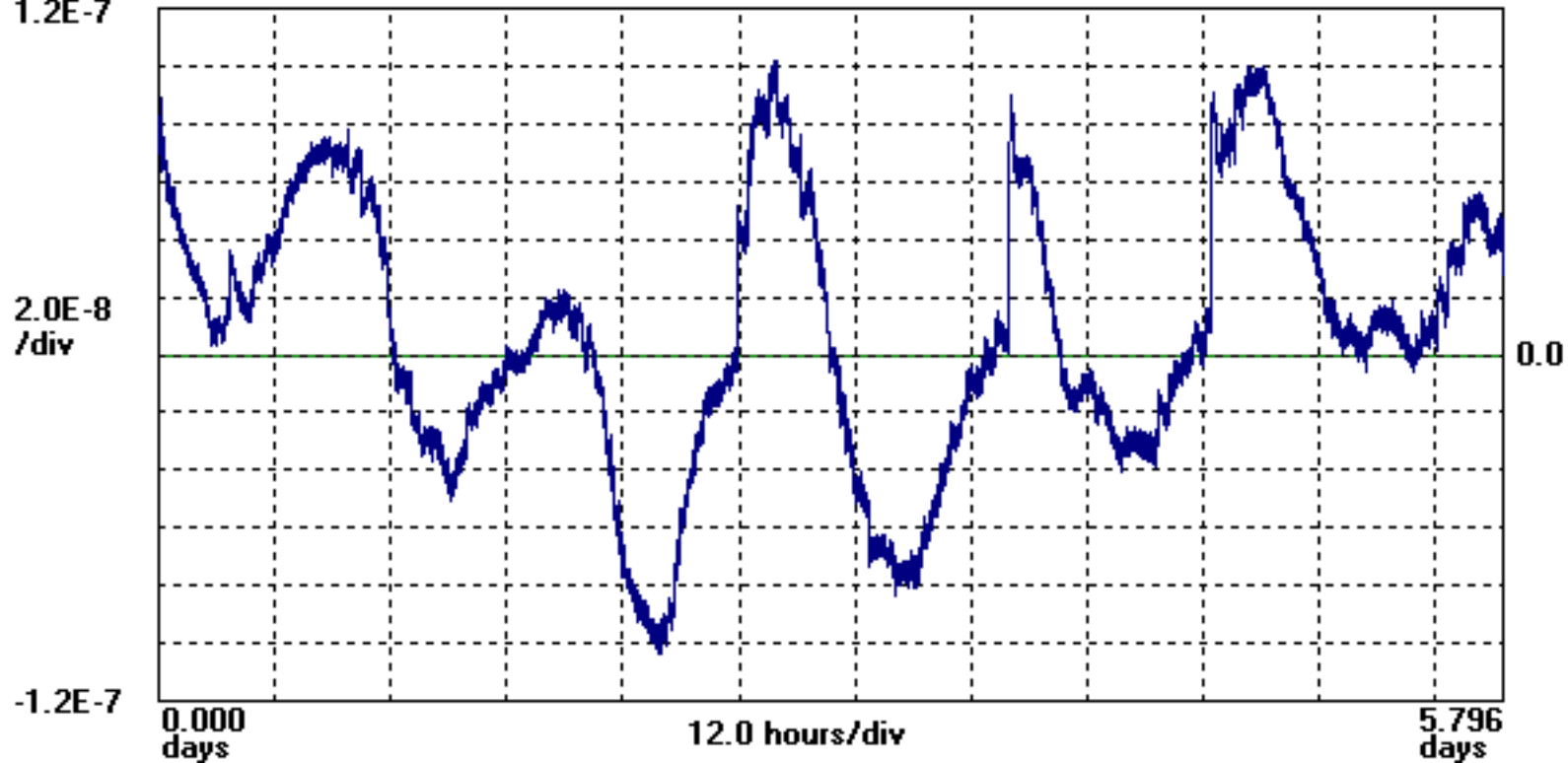
Symmetricom TimeMonitor Analyzer (file=Netgear256k_1000s.pan)
TDEV; Fo=44.00 MHz; Fs=256.0 Hz; 2009/10/20; 14:40:44
HP E1725 time interval analyzer



Measurement Results - 5

- Frequency measurement over 6 days (note diurnal cycle)

Symmetricom TimeMonitor Analyzer (file=00001.dat)
Fractional frequency offset; $F_s=66.06$ mHz; $F_o=44.00$ MHz; *10/20/2009 3:07:48 PM*;
Test: 1; NetgearWGR614v4; 44M oscillator; Samples: 33083; Gate: 15 s; Freq/Time Data Only;
1.2E-7

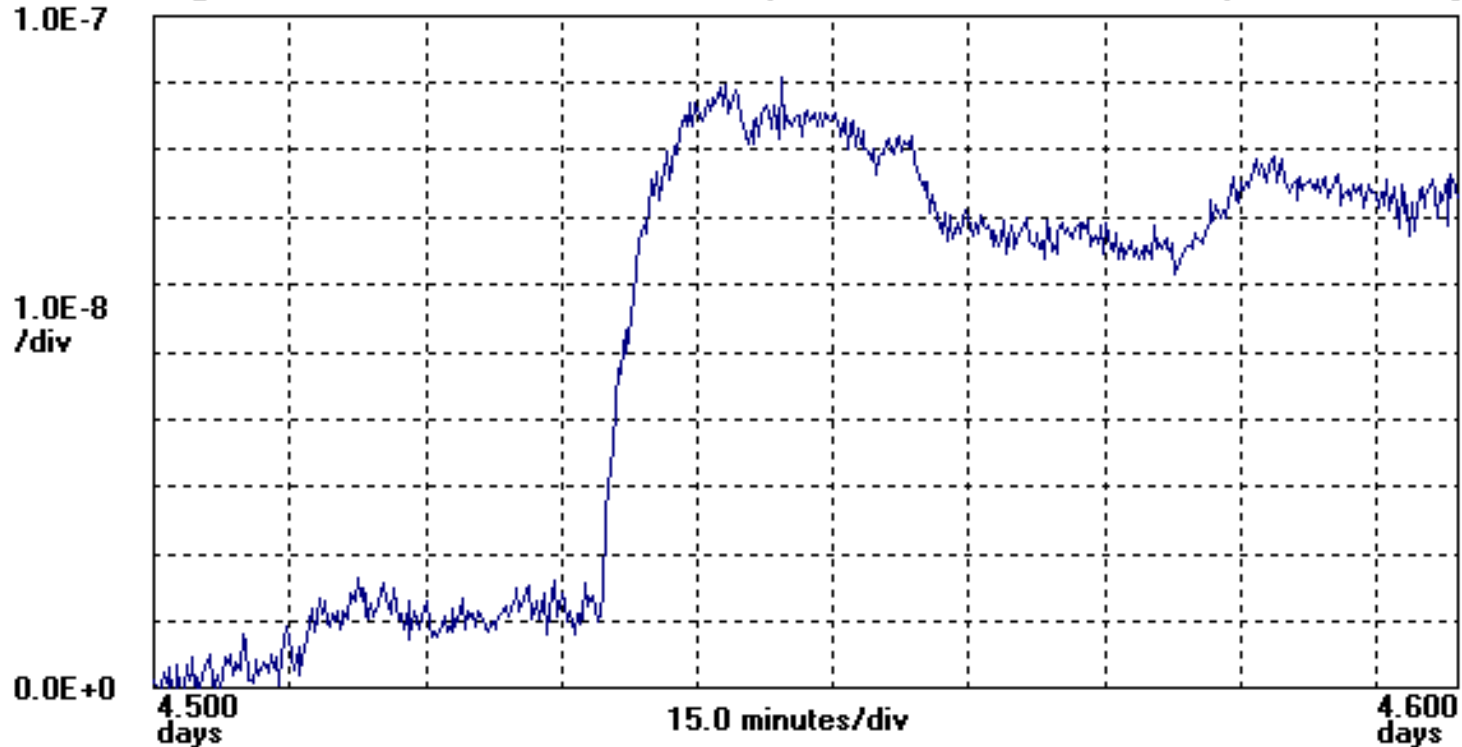


Measurement Results - 6

□ Frequency measurement over 6 days, detail of final steep increase

- Maximum rate of frequency change is on the order of $1.2 \times 10^{-8} / 1 \text{ min} = 2 \times 10^{-10} / \text{s} = 0.0002 \text{ ppm/s}$

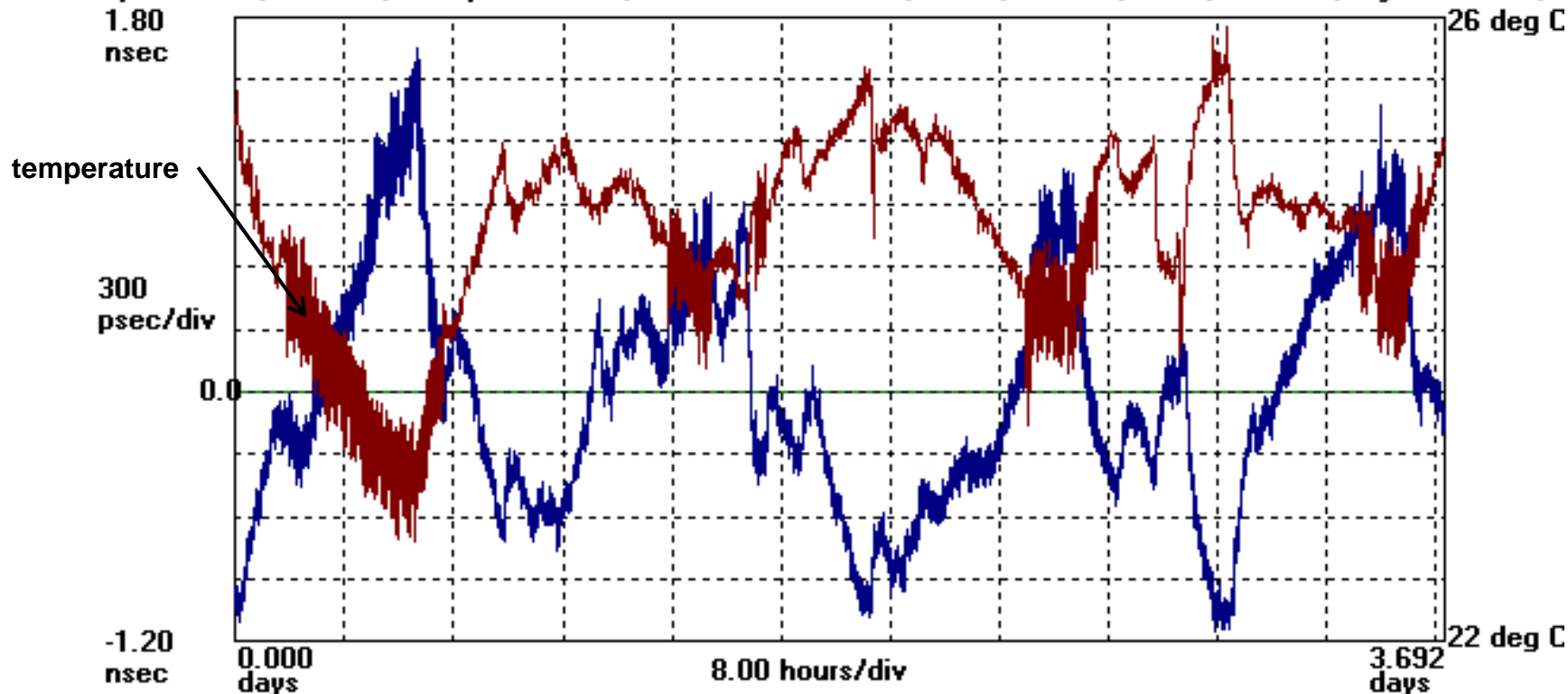
Symmetricom TimeMonitor Analyzer (file=00001.dat)
Fractional frequency offset; Fs=66.06 mHz; Fo=44.00 MHz; *10/20/2009 3:07:48 PM*;
Test: 1; NetgearWGR614v4; 44M oscillator; Samples: 33083; Gate: 15 s; Freq/Time Data Only;



Measurement Results - 7

- Sample temperature (ambient room temperature) and phase error history (red plot is temperature, blue plot is phase error)
 - Temperature variation is representative of conditions in lab for previous measurements (temperature does not change by more than 3 – 4 deg C)

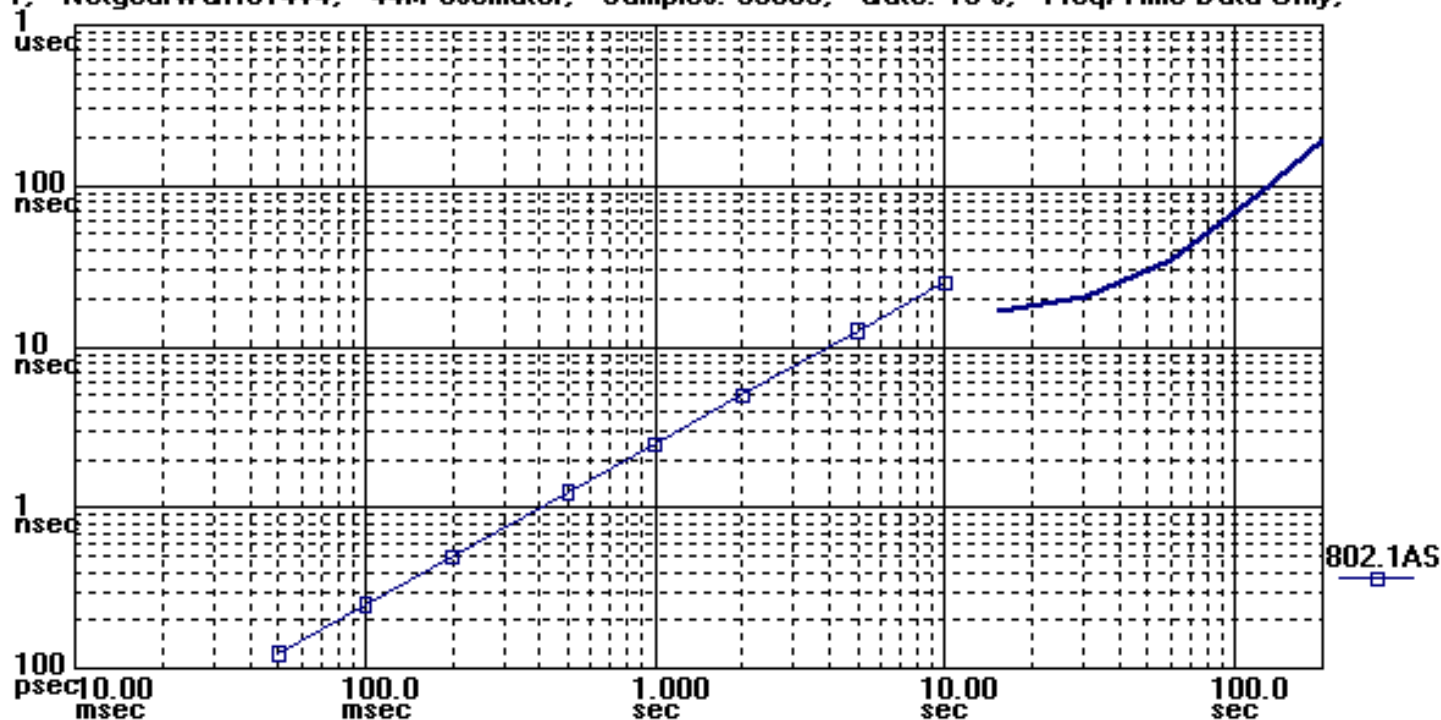
Symmetricom TimeMonitor Analyzer (file=squid_temperature.csv)
Phase deviation in units of time; $F_s=125.0$ MHz; $F_o=10.000000$ MHz; 2003/03/27 17:03:01
Squid Phase; Chan 1; Samples: 39865; Total Points: 39872; Ideal; No Cal; BNC; RS-232; SystemRef10; t



Measurement Results - 8

- TDEV result – 6 day measurement interval (observation interval ranged from approximately 15 s to 200 s)
 - TDEV is within an extrapolation of the requirement

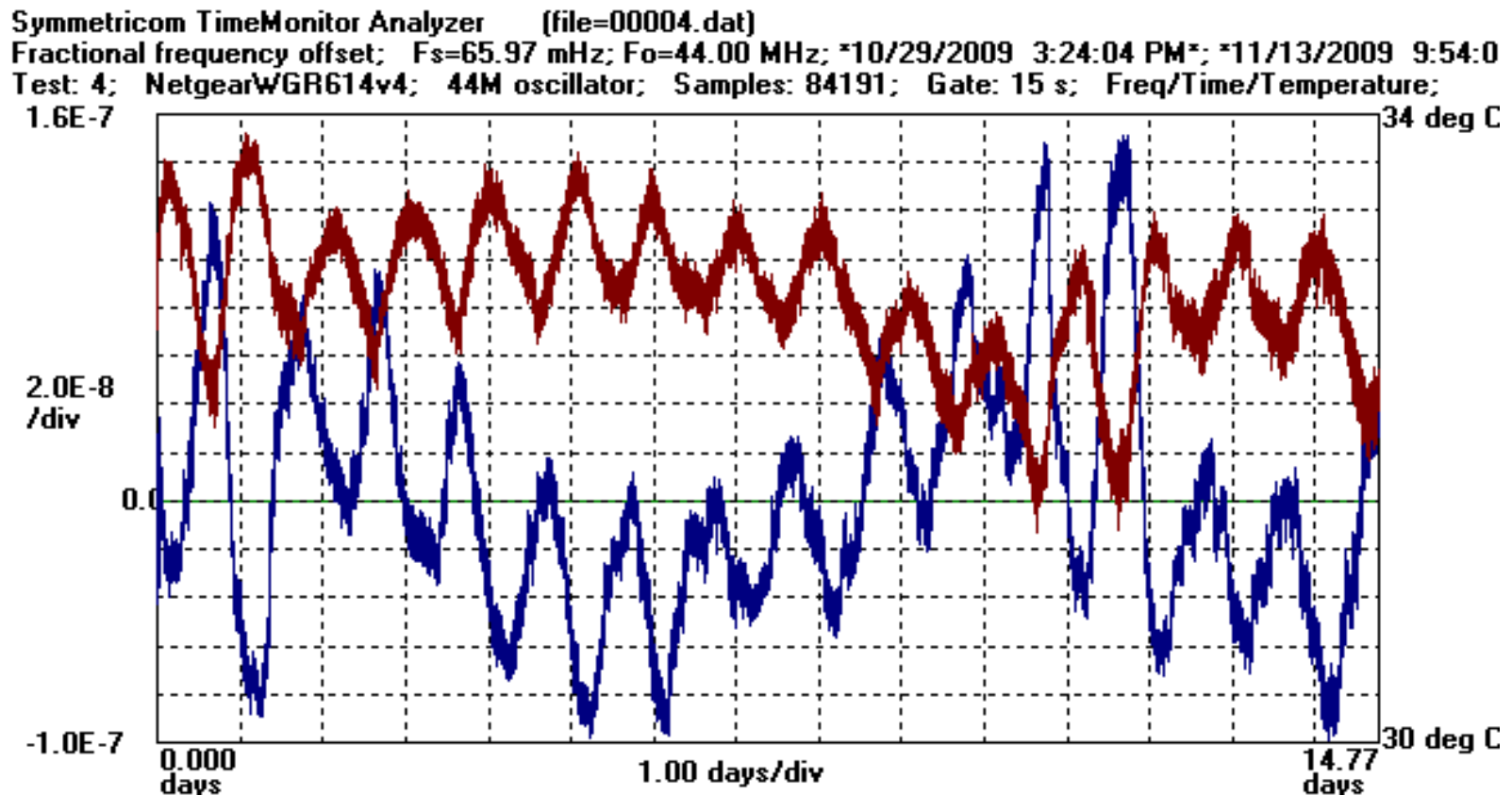
Symmetricom TimeMonitor Analyzer (file=00001.dat)
TDEV; Fo=44.00 MHz; Fs=66.06 mHz; *10/20/2009 3:07:48 PM*;
Test: 1; NetgearWGR614v4; 44M oscillator; Samples: 33083; Gate: 15 s; Freq/Time Data Only;



Measurement Results - 9

□ Frequency and temperature measurement over 14 days (red plot is temperature, blue plot is frequency)

- Temperature measurement is at oscillator (it is higher than slide 16 temperature because that is ambient room temperature)
- Results are qualitatively similar to 6-day results; note diurnal cycle



Conclusions

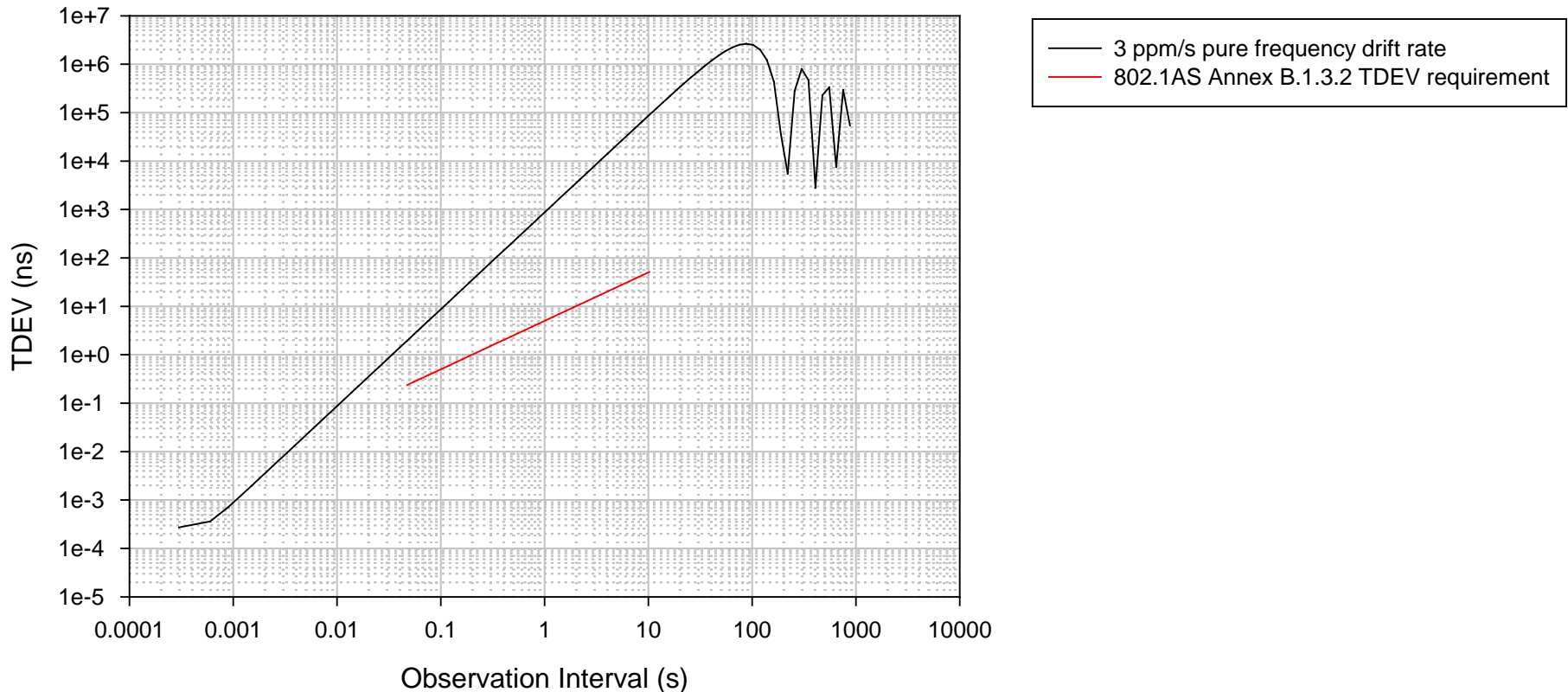
- ❑ Measured TDEV is either very close to the mask or marginally fails for observation intervals in the range of approximately 1 – 3 s
- ❑ For observation intervals less than 0.5 s, measured TDEV is well within the mask
- ❑ For temperature conditions in the lab (slide 27), maximum rate of frequency change is on the order of 0.0002 ppm/s
 - This indicates that the current 802.1AS assumption of 4 ppm/s or 1 ppm/s (assumption 9 of Annex Z) is extremely conservative
- ❑ Frequency variation over 14 days is qualitatively similar to variation over 6 days
- ❑ The results are very promising, but indicate that the present TDEV requirement should be increased to allow for margin for observation intervals in the range 1 – 3 s
 - It appears an increase in the mask by a factor of 2 would suffice, providing the performance for timing transport is acceptable (this must be checked via simulation)

Comparison of P60802 and 802.1AS clock stability

- ❑ TDEV was computed for the P60802 phase offset (slide 8), and compared with the current Annex B/802.1AS TDEV mask
- ❑ Due to the fact that the frequency of the phase variation, i.e., 4.7746 mHz (see slide 7), is much less than 10 Hz, the 10 Hz low-pass measurement filter (see slide 3) was omitted
- ❑ Note that the other bullet items on slide 3 are met:
 - A measurement interval that is at least 120 s (i.e., at least 12 times the longest observation interval),
 - A sampling interval that does not exceed 1/30 s.
- ❑ Results are on the next slide

Comparison of P60802 and 802.1AS clock stability

Comparison of TDEV for P60802 frequency drift rate (3 ppm/s)
and 802.1AS-2020 TDEV requirement of Annex B.1.3.2
Assumes sinusoidal phase and frequency variation, with maximum
frequency offset of 100 ppm



Comparison of P60802 and 802.1AS clock stability

- ❑ TDEV for the P60802 phase variation increases linearly (on a log-log scale) up to approximately 100 s
 - This is approximately $\frac{1}{2}$ the period of the phase variation (i.e., $0.5 * (2\pi / 0.03 \text{ rad/s}) = 105 \text{ s}$)
- ❑ Then TDEV shows oscillatory behavior (this would be with decreasing amplitude if the measurement interval were longer)
- ❑ The slope of TDEV in the linear (on a log-log scale) region is 2
- ❑ The P60802 TDEV exceeds the Annex B/802.1AS mask by approximately a factor of 10 at 0.05 s observation interval, and more than a factor of 1000 at 10 s observation interval
- ❑ This is consistent with the measurement results of [2], which showed much smaller rates of frequency change (e.g., 0.0002 ppm/s maximum, see slide 30)

Conclusions

- ❑ The allowable P60802 frequency variation is considerably larger, i.e., by 1 to 3 orders of magnitude, than the variation allowed by the Annex B/802.1AS TDEV mask
 - Note that, for the measurements, the temperature variation in the lab was within 3°C
 - It is likely that larger temperature variation would have resulted in larger TDEV
 - However, P60802 does not state a temperature range or requirement
- ❑ In any case, the most important consideration is the dTE that results from the P60802 frequency stability and from the Annex B/802.1AS frequency stability
- ❑ Both the P60802 and Annex B/802.1AS frequency stability requirements will be considered, for the simulation cases that are planned

References - 1

- [1] IEC/IEEE 60802 - Time-Sensitive Networking Profile for Industrial Automation/D1.1, September 2019
- [2] Lee Cosart and Geoffrey M. Garner, *Wander TDEV Measurements for Inexpensive Oscillator*, Symmetricom and Samsung presentation to IEEE 802.1, November 2, 2009.
- [3] Geoffrey M. Garner, *Simulation Results for 802.1AS Synchronization Transport with Clock Wander Generation and Updated Residence and Pdelay Turnaround Times*, Samsung presentation to IEEE 802.1, July 12, 2010.
- [4] David W. Allan, Marc A. Weiss, and James L. Jespersen, *A Frequency Domain View of Time Domain Characterization of Clocks and Time and Frequency Distribution Systems*, Forty-Fifth Annual Symposium on Frequency Control, Los Angeles, CA, May 29 – 31, 1991, pp. 667 – 678.
- [5] Stefano Bregni, *Synchronization of Digital Telecommunications Networks*, Wiley, 2002.

References - 2

- [6] *Phase Noise*, Vectron International, Application Note, available at <http://www.vectron.com>.
- [7] *Jitter and Signal Noise in Frequency Sources*, Raltron, Application Note, available at <http://www.raltron.com/>
- [8] N. Jeremy Kasdin, *Discrete Simulation of Colored Noise and Stochastic Processes and $1/f^\alpha$ Power Law Noise Generation*, Proceedings of the IEEE, Vol. 83, No. 5, May 1995

Thank you