# Revocation and Tracing Schemes for Stateless Receivers 

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#### Abstract

We deal with the problem of a center sending a message to a group of users such that some subset of the users is considered revoked and should not be able to obtain the content of the message. We concentrate on the stateless receiver case, where the users do not (necessarily) update their state from session to session. We present a framework called the Subset-Cover framework, which abstracts a variety of revocation schemes including some previously known ones. We provide sufficient conditions that guarantees the security of a revocation algorithm in this class.

We describe two explicit Subset-Cover revocation algorithms; these algorithms are very flexible and work for any number of revoked users. The schemes require storage at the receiver of $\log N$ and $\frac{1}{2} \log ^{2} N$ keys respectively ( $N$ is the total number of users), and in order to revoke $r$ users the required message lengths are of $r \log N$ and $2 r$ keys respectively. We also provide a general traitor tracing mechanism that can be integrated with any Subset-Cover revocation scheme that satisfies a "bifurcation property". This mechanism does not need an a priori bound on the number of traitors and does not expand the message length by much compared to the revocation of the same set of traitors.

The main improvements of these methods over previously suggested methods, when adopted to the stateless scenario, are: (1) reducing the message length to $O(r)$ regardless of the coalition size while maintaining a single decryption at the user's end (2) provide a seamless integration between the revocation and tracing so that the tracing mechanisms does not require any change to the revocation algorithm.


## 1 Introduction

The problem of a Center transmitting data to a large group of receivers so that only a predefined subset is able to decrypt the data is at the heart of a growing number of applications. Among them are pay-TV applications, multicast communication, secure distribution of copyright-protected material (e.g. music) and audio streaming. The area of Broadcast Encryption deals with methods to efficiently broadcast information to a dynamically changing group of users who are allowed to receive the data. It is often convenient to think of it as a Revocation Scheme, which addresses the case where some subset of the users are excluded from receiving the information. In such scenarios it is also desirable to have a Tracing Mechanism, which enables the efficient tracing of leakage, specifically, the source of keys used by illegal devices, such as pirate decoders or clones.

One special case is when the receivers are stateless. In such a scenario, a receiver is not capable of recording the past history of transmissions and change its state accordingly. Instead, its operation must be

[^0]based on the current transmission and its initial configuration. Stateless receivers are important for the case where the receiver is a device that is not constantly on-line, such as a media player (e.g. a CD or DVD player where the "transmission" is the current disc), a satellite receiver (GPS) and perhaps in multicast applications.

This paper introduces very efficient revocation schemes which are specifically suitable for stateless receivers. Our approach is quite general. We define a framework of such algorithms, called Subset-Cover algorithms, and provide a sufficient condition for an algorithm in this family to be secure. Furthermore, we suggest two particular implementations for schemes in this family; the performance of the second method is substantially better than any previously known algorithm for this problem (see Section 1.1). We also provide a general property ('bifurcation') of revocation algorithms in our framework that allows efficient tracing methods, without modifying the underlying revocation scheme.

## Copyright Protection

An important application that motivates the study of revocation and tracing mechanisms is Copyright Protection. The distribution of copyright protected content for (possibly) disconnected operations involves encryption of the content on a media. The media (such as CD, DVD or a flash memory card) typically contains in its header the encryption of the key $K$ which encrypts the content following the header. Compliant devices, or receivers, store appropriate decryption keys that can be used to decrypt the header and in turn decrypt the content. A copyright protection mechanism defines the algorithm which assigns keys to devices and encrypts the content.

An essential requirement from a copyright protection mechanism is the ability to revoke, during the lifetime of the system, devices that are being used illegally. It is expected that some devices will be compromised, either via reverse engineering or due to sloppy manufacturing of the devices. As a result keys of a number of compromised devices can then be cloned to form a decrypting unit. This copyright protection violation can be combated by revoking the keys of the compromised devices. Note that devices are stateless as they are assumed to have no capability of dynamically storing any information (other than the original information that is stored at the time of manufacturing) and also since they are typically not connected to the world (except via the media). Hence, it is the responsibility of the media to carry the current state of the system at the time of recording in terms of revoked devices.

It is also highly desirable that the revocation algorithm be coupled with a traitors tracing mechanism. Specifically, a well-designed copyright protection mechanism should be able to combat piracy in the form of illegal boxes or clone decoding programs. Such decoders typically contain the identities of a number of devices that are cooperating; furthermore, they are hard to disassemble ${ }^{1}$. The tracing mechanism should therefore treat the illicit decoder as a black box and simply examine its input/output relationship. A combination of a revocation and a tracing mechanism provides a powerful tool for combating piracy: finding the identities of compromised devices, revoking them and rendering the illegal boxes useless.
Caveat. The goal of a copyright protection mechanism is to create a legal channel of distribution of content and to disallow its abuse. As a consequence, an illegal distribution will require the establishment of alternative channels and should not be able to piggyback on the legitimate channel ${ }^{2}$. Such alternative channels should be combated using other means and is not under the scope of the techniques developed in this paper, thought techniques such as revocation may be a useful deterrent against rough users.

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### 1.1 Related Work

Broadcast Encryption. The area of Broadcast Encryption was first formally studied (and coined) by Fiat and Naor in [23] and has received much attention since then. To the best of our knowledge the scenario of stateless receivers has not been considered explicitly in the past in a scientific paper, but in principle any scheme that works for the connected mode may be converted to a scheme for stateless receivers. (Such conversion may require including with any transmission the entire 'history' of revocation events.) When discussing previously proposed schemes we will consider their performance when adapted to the stateless receiver scenario.

To survey previous results we should fix our notation. Let $N$ be the total number of users in the system let $r$ be the size of the revoked set $\mathcal{R}$. Another important parameter that is often considered is $t$, the upper bound on the size of the coalition an adversary can assemble. The algorithms in this paper do not require such a bound and we can think of $t=r$; on the other hand some previously proposed schemes depend on $t$ but are independent of $r$. The Broadcast Encryption method of [23] is one such scheme which allows the removal of any number of users as long as at most $t$ of them collude. There the message length is $O\left(t \log ^{2} t\right)$, a user must store a number of keys that is logarithmic in $t$ and the amount of work required by the user is $\tilde{O}(r / t)$ decryptions.

The logical-tree-hierarchy (LKH) scheme, suggested independently by Wallner et. al. [42] and Wong et. al. [43], is designed for the connected mode for multicast re-keying applications. It revokes a single user at a time, and updates the keys of all remaining users. If used in our scenario, it requires a transmission of $2 r \log N$ keys to revoke $r$ users, each user should store $\log N$ keys and the amount of work each user should do is $r \log N$ encryptions (the expected number is $O(r)$ for an average user). These bounds are somewhat improved in $[12,13,32]$, but unless the storage at the user is extremely high they still require a transmission of length $\Omega(r \log N)$. The key assignment of this scheme and the key assignment of our first method are similar; see further discussion on comparing the two methods in Section 3.1.

Luby and Staddon [31] considered the information theoretic setting and devised bounds for any revocation algorithms under this setting. Their "Or Protocol" fits our Subset-Cover framework. In fact, as we show in Section 3.3, our second algorithm (the Subset Difference method) which is not information theoretic, beats their lower bound (Theorem 12 in [31]). Garay, Staddon and Wool [27] introduced the notion of long-lived broadcast encryption. In this scenario, keys of compromised decoders are no longer used for encryptions. The question they address is how to adapt the broadcast encryption scheme so as to maintain the security of the system for the good users.

The method of Kumar et. al [30] enables one-time revocation of up to $r$ users with message lengths of $O(r \log N)$ and $O\left(r^{2}\right)$.

CPRM [18] is one of the methods that explicitly considers the stateless scenario. Our Subset Difference method outperforms CPRM by a factor of about 25 in the number of revocations it can handle when all the other parameters are fixed; Section 4.5 contains a detailed description and comparison.

Tracing Mechanisms. The notion of a tracing system was first introduced by Chor, Fiat and Naor in [16], and was later refined to the Threshold Traitor model in [34], [17]. Its goal is to distribute decryption keys to the users so as to allow the detection of at least one key that is used in a pirate box or clone using keys of at most $t$ users. Black-box tracing assumes that only the outcome of the decoding box can be examined. [34], [17] provide combinatorial and probabilistic constructions that guarantee tracing with high probability. To trace $t$ traitors, they require each user to store $O(t \log N)$ keys and to perform a single decryption operation. The message length is $4 t$. The public key tracing scheme of Boneh and Franklin [7] provides a numbertheoretic deterministic method for tracing. Note that in all of the above methods $t$ is an $a$-priori bound.

Preventing Leakage of Keys. The problem of preventing illegal leakage of keys has been attacked by a
number of quite different approaches. The legal approach, suggested by Pfitzmann [39], requires a method that not only traces the leaker but also yields a proof for the liability of the traitor (the user whose keys are used by an illegal decoder). Hence, leakage can be fought via legal channels by presenting this proof to a third party. The self enforcement approach, suggested by Dwork, Lotspiech and Naor [20], aims at deterring users from revealing their personal keys. The idea is to provide a user with personal keys that contain some sensitive information about the user which the user will be reluctant to disclose. The trace-and-revoke approach is to design a method that can trace the identity of the user whose key was leaked; in turn, this user's key is revoked from the system for future uses. The results in this paper fall into the latter category, albeit in a slightly relaxed manner. Although our methods assure that leaked keys will become useless in future transmissions, it may not reveal the actual identities of all leaking keys, thus somewhat lacking self-enforcement.

Content Tracing: In addition to tracing leakers who give away their private keys there are methods that attempt to detect illegal users who redistribute the content after it is decoded. This requires the assumption that good watermarking techniques with the following properties are available: it is possible to insert one of several types of watermarks into the content so that the adversary cannot create a "clean" version with no watermarks (or a watermark it did not receive). Typically, content is divided into segments that are watermarked separately. This setting with protection against collusions was first investigated by Boneh and Shaw [9]. A related setting with slightly stronger assumptions on the underlying watermarking technique was investigated in [24, 5, 41]. By introducing the time dimension, Fiat and Tassa [24] propose the dynamic tracing scenario in which the watermarking of a segment depends on feedback from the previous segment and which detects all traitors. Their algorithm was improved by Berkman, Parnas and Sgall [5], and a scheme which requires no real-time computation/feedback for this model was given in Safavani-Naini and Wang [41]. Content tracing is relevant to our scenario in that any content tracing mechanism can be combined with a key-revocation method to ensure that the traced users are indeed revoked and do not receive new content in the future. Moreover, the tracing methods of [24] are related to the tracing algorithm of Section 5.2.

Integration of tracing and revocation. Broadcast encryption can be combined with tracing schemes to yield trace-and-revoke schemes. While Gafni et. al. [26] only consider combinatorial constructions, the schemes in Naor and Pinkas [35] are more general. The previously best known trace-and-revoke algorithm of [35] can tolerate a coalition of at most $t$ users. It requires to store $O(t)$ keys at each user and to perform $O(r)$ decryptions; the message length is $r$ keys, however these keys are elements in a group where the Decisional Diffie-Hellman problem is difficult and therefore these keys may be longer than symmetric keys. The tracing model of [35] is not a "pure" black-box model. Anzai et. al [2] employs a similar method for revocation, but without tracing capabilities. Our results improve upon this algorithm both in the work that must be performed at the user and in the lengths of the keys transmitted in the message.

### 1.2 Summary of Results

In this paper we define a generic framework encapsulating several previously proposed revocation methods, called Subset-Cover algorithms. These algorithms are based on the principle of covering all non-revoked users by disjoint subsets from a predefined collection. We define the security of a revocation scheme and provide a sufficient condition (key-indistinguishability) for a revocation algorithm in the Subset-Cover Framework to be secure. An important consequence of this framework is the separation between long-lived keys and short-term keys. The framework can be easily extended to the public-key scenario.

We then provide two new instantiations of revocation schemes in the Subset-Cover Framework, with a

| Method | Message Length | Storage @ Receiver | Processing time | no. Decryptions |
| :---: | :---: | :---: | :---: | :---: |
| Complete Subtree | $r \log \frac{N}{r}$ |  |  |  |
| Subset Difference | $2 r-1$ | $\frac{\log N}{2} \log ^{2} N$ | $O(\log \log N)$ | 1 |

Figure 1: Performance Tradeoff for the Complete Subtree method and the Subset Difference method
different performance tradeoff (summarized in Table $1.2^{3}$ ). Both instantiations are tree-based, namely the subsets are derived from a virtual tree structure imposed on all devices in the system. The first requires a message length of $r \log N$ and storage of $\log N$ keys at the receiver and constitutes a moderate improvement over previously proposed schemes; the second exhibits a substantial improvement: it requires a message length of $2 r-1$ (in the worst case, or $1.38 r$ in the average case) and storage of $\frac{1}{2} \log ^{2} N$ keys at the receiver. $N$ is the total number of devices, and $r$ is the number of revoked devices. Furthermore, these algorithms are $r$-flexible, namely they do not assume an upper bound of the number of revoked receivers.

Thirdly, we present a tracing mechanism that works in tandem with a Subset-Cover revocation scheme. We identify the bifurcation property for a Subset-Cover scheme. Our two constructions of revocation schemes posses this property. We show that every scheme that satisfies the bifurcation property can be combined with the tracing mechanism to yield a trace-and-revoke scheme. The integration of the two mechanisms is seamless in the sense that no change is required for any one of them. Moreover, no a-priori bound on the number of traitors is needed for our tracing scheme. In order to trace $t$ illegal users, the first revocation method requires a message length of $t \log N$, and the second revocation method requires a message length of $5 t$.
Main Contributions: the main improvements that our methods achieve over previously suggested methods, when adopted to the stateless scenario, are:

- Reducing the message length to linear in $r$ regardless of the coalition size, while maintaining a single decryption at the user's end. This applies also to the case where public keys are used, without a substantial length increase.
- The seamless integration between revocation and tracing: the tracing mechanism does not require any change of the revocation algorithm and no a priori bound on the number of traitors, even when all traitors cooperate among themselves.
- The rigorous treatment of the security of such schemes, identifying the effect of parameter choice on the overall security of the scheme.

Organization of the paper. Section 2 describes the framework for Subset-Cover algorithms. Section 3 describes two specific implementations of such algorithms. Section 4 presents extensions, implementation issues, public-key methods, application to multicasting as well as casting the recently proposed CPRM method (for DVD-audio and SD cards) in the Subset-Cover Framework. Section 5 provides the traitors tracing extensions to Subset-Cover revocation algorithms and their seamless integration. In Section 6 we define the "key-indistinguishability" property and provide the main theorem characterizing the security of revocation algorithms in the Subset-Cover framework.

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## 2 The Subset-Cover Revocation Framework

### 2.1 Preliminaries - Problem Definition

Let $\mathcal{N}$ be the set of all users, $|\mathcal{N}|=N$, and $\mathcal{R} \subset \mathcal{N}$ be a group of $|\mathcal{R}|=r$ users whose decryption privileges should be revoked. The goal of a revocation algorithm is to allow a center to transmit a message $M$ to all users such that any user $u \in \mathcal{N} \backslash \mathcal{R}$ can decrypt the message correctly, while even a coalition consisting of all members of $\mathcal{R}$ cannot decrypt it. The exact definition of the latter is provided in Section 6 .

A system consists of three parts: (1) An initiation scheme, which is a method for assigning the receivers secret information that will allow them to decrypt. (2) The broadcast algorithm - given a message $M$ and the set $\mathcal{R}$ of users that should be revoked outputs a ciphertext message $M^{\prime}$ that is broadcast to all receivers. (3) A decryption algorithm - a (non-revoked) user that receives ciphertext $M^{\prime}$ using its secret information should produce the original message $M$. Since the receivers are stateless, the output of the decryption should be based on the current message and the secret information only.

### 2.2 The Framework

We present a framework for algorithms which we call Subset-Cover. In this framework an algorithm defines a collection of subsets $S_{1}, \ldots, S_{w}, S_{j} \subseteq \mathcal{N}$. Each subset $S_{j}$ is assigned (perhaps implicitly) a long-lived key $L_{j}$; each member $u$ of $S_{j}$ should be able to deduce $L_{j}$ from its secret information. Given a revoked set $\mathcal{R}$, the remaining users $\mathcal{N} \backslash \mathcal{R}$ are partitioned into disjoint subsets $S_{i_{1}}, \ldots, S_{i_{m}}$ so that

$$
\mathcal{N} \backslash \mathcal{R}=\bigcup_{j=1}^{m} S_{i_{j}}
$$

and a session key $K$ is encrypted $m$ times with $L_{i_{1}}, \ldots, L_{i_{m}}$.
Specifically, an algorithm in the framework uses two encryption schemes:

- A method $F_{K}:\{0,1\}^{*} \mapsto\{0,1\}^{*}$ to encrypt the message itself. The key $K$ used will be chosen fresh for each message $M$ - a session key - as a random bit string. $F_{K}$ should be a fast method and should not expand the plaintext. The simplest implementation is to Xor the message $M$ with a stream cipher generated by $K$.
- A method to deliver the session key to the receivers, for which we will employ an encryption scheme. The keys $L$ here are long-lived. The simplest implementation is to make $E_{L}:\{0,1\}^{\ell} \mapsto\{0,1\}^{\ell}$ a block cipher.

An exact discussion of security requirements of these primitives is given in Section 6. Some suggestions for the implementation of $F_{K}$ and $E_{L}$ are given in Section 4.1. The algorithm consists of three components:

Scheme Initiation : Every receiver $u$ is assigned private information $I_{u}$. For all $1 \leq i \leq w$ such that $u \in S_{i}$, $I_{u}$ allows $u$ to deduce the key $L_{i}$ corresponding to the set $S_{i}$. Note that the keys $L_{i}$ can be chosen either (i) uniformly at random and independently from each other (which we call the information-theoretic case) or (ii) as a function of other (secret) information (which we call the computational case), and thus may not be independent of each other.
The Broadcast algorithm at the Center:

1. Choose a session encryption key $K$.
2. Given a set $\mathcal{R}$ of revoked receivers, the center finds a partition of the users in $\mathcal{N}-\mathcal{R}$ into disjoint subsets $S_{i_{1}}, \ldots, S_{i_{m}}$. Let $L_{i_{1}}, \ldots, L_{i_{m}}$ be the keys associated with the above subsets.
3. The center encrypts $K$ with keys $L_{i_{1}}, \ldots, L_{i_{m}}$ and sends the ciphertext

$$
\left\langle\left[i_{1}, i_{2}, \ldots, i_{m}, E_{L_{i_{1}}}(K), E_{L_{i_{2}}}(K), \ldots, E_{L_{i_{m}}}(K)\right], F_{K}(M)\right\rangle
$$

The portion in square brackets preceding $F_{K}(M)$ is called the header and $F_{K}(M)$ is called the body.
The Decryption step at the receiver $u$, upon receiving a broadcast message

$$
\left\langle\left[i_{1}, i_{2}, \ldots, i_{m}, C_{1}, C_{2}, \ldots, C_{m}\right], M^{\prime}\right\rangle:
$$

1. Find $i_{j}$ such that $u \in S_{i_{j}}$ (in case $u \in \mathcal{R}$ the result is null).
2. Extract the corresponding key $L_{i_{j}}$ from $I_{u}$.
3. Compute $\left.D_{L_{i j}}\left(C_{j}\right)\right)$ to obtain $K$.
4. Compute $D_{K}\left(M^{\prime}\right)$ to obtain and output $M$.

A particular implementation of such scheme is specified by (1) the collection of subsets $S_{1}, \ldots, S_{w}$ (2) the key assignment to each subset in the collection (3) a method to cover the non-revoked receivers $\mathcal{N} \backslash \mathcal{R}$ by disjoint subsets from this collection, and (4) A method that allows each user $u$ to find its cover $S$ and compute its key $L_{S}$ from $I_{u}$. The algorithm is evaluated based upon three parameters:
i. Message Length - the length of the header that is attached to $F_{K}(M)$, which is proportional to $m$, the number of sets in the partition covering $\mathcal{N} \backslash \mathcal{R}$.
ii. Storage size at the receiver - how much private information (typically, keys) does a receiver need to store. For instance, $I_{u}$ could simply consists of all the keys $S_{i}$ such that $u \in S_{i}$, or if the key assignment is more sophisticated it should allow the computation of all such keys.
iii. Message processing time at receiver. We often distinguish between decryption and other types of operations.

It is important to characterize the dependence of the above three parameters in both $N$ and $r$. Specifically, we say that a revocation scheme is flexible with respect to $r$ if the storage at the receiver is not a function of $r$. Note that the efficiency of setting up the scheme and computing the partition (given $\mathcal{R}$ ) is not taken into account in the algorithm's analysis. However, for all schemes presented in this paper the computational requirements of the sender are rather modest: finding the partition takes time linear in $|\mathcal{R}| \log \mathcal{N}$ and the encryption is proportional to the number of subsets in the partition.

### 2.3 Security of the Framework: Key-Indistinguishability

Section 6 discusses in detail the security of an algorithm in the Subset-Cover framework. Intuitively, we identify a critical property that is required from the key-assignment method in order to provide a secure Subset-Cover algorithm. We say that a subset-cover algorithm satisfies the "key-indistinguishability" property if for every subset $S_{i}$ its key $L_{i}$ is indistinguishable from a random key given all the information of all users that are not in $S_{i}$. Note that any scheme in which the keys to all subsets are chosen independently satisfies this property. We then proceed to show that any subset-cover algorithm that satisfies the keyindistinguishability property provides a secure encryption of the message (the overall encryption security is expressed as a function of the security provided by $E$ and $F$ ).

## 3 Two Subset-Cover Revocation Algorithms

We now describe two instantiations of revocation schemes in the Subset-Cover framework with a different performance tradeoff, as summarized in table 1.2. Each is defined over a different collection of subsets. Both schemes are $r$-flexible, namely they work with any number of revocations. In the first scheme, the key assignment is information-theoretic and in the other scheme the key assignment is computational. The first method is natural; the second method is more involved, and exhibits a substantial improvement over previous methods.

In both schemes the subsets and the partitions are obtained by imagining the receivers as the leaves in a rooted full binary tree with $N$ leaves (assume that $N$ is a power of 2 ). Such a tree contains $2 N-1$ nodes (leaves plus internal nodes) and for any $1 \leq i \leq 2 N-1$ we assume that $v_{i}$ is a node in the tree. The systems differ in the collections of subsets they consider.

### 3.1 The Complete Subtree Method

The collection of subsets $S_{1}, \ldots, S_{w}$ in our first scheme corresponds to all complete subtrees in the full binary tree with $N$ leaves. For any node $v_{i}$ in the full binary tree (either an internal node or a leaf, $2 N-1$ altogether) let the subset $S_{i}$ be the collection of receivers $u$ that correspond to the leaves of the subtree rooted at node $v_{i}$. In other words, $u \in S_{i}$ iff $v_{i}$ is an ancestor of $u$. The key assignment method is simple: assign an independent and random key $L_{i}$ to every node $v_{i}$ in the complete tree. Provide every receiver $u$ with the $\log N+1$ keys associated with the nodes along the path from the root to leaf $u$.

For a given set $\mathcal{R}$ of revoked receivers, let $u_{1}, \ldots, u_{r}$ be the leaves corresponding to the elements in $\mathcal{R}$. The method to partition $\mathcal{N} \backslash \mathcal{R}$ into disjoint subsets is as follows. Consider the (directed) Steiner Tree $S T(\mathcal{R})$ defined by the set $\mathcal{R}$ of vertices and the root, i.e. the minimal subtree of the full binary tree that connects all the leaves in $\mathcal{R}$. $S T(\mathcal{R})$ is unique. Let $S_{i_{1}}, \ldots, S_{i_{m}}$ be all the subtrees of the original tree that "hang" off $S T(\mathcal{R})$, that is, all subtrees whose roots $v_{1}, \ldots, v_{m}$ are adjacent to nodes of outdegree 1 in $S T(\mathcal{R})$, but they are not in $S T(\mathcal{R})$. The next claim follows immediately and shows that this construction is indeed a cover, as required.

Claim 1 1. Every leaf $u \notin \mathcal{R}$ is in exactly one subset in the above partition.

## 2. A leaf $u \in \mathcal{R}$ does not belong to any subset in the above partition.

The cover size: The Steiner tree $S T(\mathcal{R})$ has $r$ leaves. An internal node is in $S T(\mathcal{R})$ iff it is on some path to a point in $\mathcal{R}$, therefore there are at most $r \log N$ nodes in $S T(\mathcal{R})$. A finer analysis takes into account double counting of the nodes closer to the root and the fact that a node of outdegree 2 in $S T(\mathcal{R})$ does not produce a subset, and shows that the number of subsets is at most $r \log (N / r)$. The analysis is as follows: note that the number of sets is exactly the number of degree 1 nodes in $S T(\mathcal{R})$. Assume by induction on the tree height that this is true for trees of depth $i$, i.e. that in a subtree with $r$ leaves the maximum number of nodes of degree 1 is at most $r \cdot(i-\log r)$. Then consider a tree of depth $i+1$. If all the leaves are contained in one subtree of depth $i$, then by induction the total number of nodes of degree 1 is at most $r \cdot(i-\log r)+1 \leq r \cdot(i+1-\log r)$. Otherwise, the number of nodes of degree 1 is the number of nodes of degree 1 in the left subtree (that has $r_{1} \geq 1$ leaves) plus the number of nodes of degree 1 in the right subtree (that has $r_{2} \geq 1$ leaves) and $r=r_{1}+r_{2}$. By induction, this is at most $r_{1} \cdot\left(i-\log r_{1}\right)+r_{2} \cdot\left(i-\log r_{2}\right)=$ $r \cdot i-\left(r_{1} \log r_{1}+r_{2} \log r_{2}\right) \leq r \cdot(i+1-\log r)$ since $\left(r_{1} \log r_{1}+r_{2} \log r_{2}\right) \geq r(\log r-1)$. Note that this is also the average number of subsets (where the $r$ leaves are chosen at random).
The Decryption Step: Given a message

$$
\left.\left\langle\left[i_{1}, \ldots, i_{m}, E_{L_{i_{1}}}(K), E_{L_{i_{2}}}(K), \ldots, E_{L_{i_{m}}}(K)\right], F_{K}(M)\right]\right\rangle
$$

a receiver $u$ needs to find whether any of its ancestors is among $i_{1}, i_{2}, \ldots i_{m}$; note that there can be only one such ancestor, so $u$ may belong to at most one subset.

There are several ways to facilitate an efficient search in this list ${ }^{4}$. First consider a generic method that works whenever each receiver is a member of relatively few subsets $S_{i}$ : the values $i_{1}, i_{2}, \ldots i_{m}$ are put in a hash table and in addition a perfect hash function $h$ of the list is transmitted as well (see [15] for a recent survey of such functions). The length of the description of $h$ can be relatively small compared to the length of the list i.e. it can be $o(m \log w)$. The receiver $u$ should check for all $i$ such that $u \in S_{i}$ whether $i$ is in the list by computing $h(i)$. In our case this would mean checking $\log N$ values.

Furthermore, suppose that we are interested in using as few bits as possible to represent the collection of subsets used $\left\{i_{1}, i_{2}, \ldots i_{m}\right\}$. The information-theoretic bound on the number of bits needed is $\left\lceil\log \binom{w}{m}\right\rceil$, which is roughly $m \log w / m$, using Stirling's approximation. (Note that when $m \approx \sqrt{w}$ this represents a factor 2 compression compared to storing $\left\{i_{1}, i_{2}, \ldots i_{m}\right\}$ explicitly.) However we are interested in a succinct representation of the collection that allows efficient lookup in this list. It turns out that with an additive factor of $O(m+\log \log w)$ bits it is possible to support an $O(1)$ lookup, see [10, 38]; the results they provide are even slightly better, but this bound is relatively simple to achieve.

It turns out that we can do even better for the complete subtree method, given the special structure. For each node $u$, the desired ancestor $i_{j}$ in the list is the one with which $u$ and $i_{j}$ have the longest common prefix. Searching for this can be done by $\log \log N$ comparisons given the right preprocessing of the data, see [33].

Summarizing, in the complete subtree method (i) the message header consists of at most $r \log \frac{N}{r}$ keys and encryptions (ii) receivers have to store $\log N$ keys and (iii) processing a message requires $O(\log \log N)$ operations plus a single decryption operation.
Security: The key assignment in this method is information theoretic, that is keys are assigned randomly and independently. Hence the "key-indistinguishability" property of this method follows from the fact that no $u \in \mathcal{R}$ is contained in any of the subsets $i_{1}, i_{2}, \ldots i_{m}$, as stated in Claim 1 .

Theorem 2 The Complete Subtree Revocation method requires (i) message length of at most $r \log \frac{N}{r}$ keys (ii) to store $\log N$ keys at a receiver and (iii) $O(\log \log N)$ operations plus a single decryption operation to decrypt a message. Moreover, the method is secure in the sense of Definition 11.

Comparison to the Logical Key Hierarchy (LKH) approach : Readers familiar with the LKH method of $[42,43]$ may find it instructive to compare it to the Complete Subtree Scheme. The main similarity lies in the key assignment - an independent label is assigned to each node in the binary tree. However, these labels are used quite differently - in the multicast re-keying LKH scheme some of these labels change at every revocation. In the Complete Subtree method labels are static; what changes is a single session key.

Consider an extension of the LKH scheme which we call the Clumped re-keying method: here, $r$ revocations are performed at a time. For a batch of $r$ revocations, no label is changed more than once, i.e. only the "latest" value is transmitted and used. In this variant the number of encryptions is roughly the same as in the Complete Subtree method, but it requires $\log N$ decryptions at the user, (as opposed to a single decryption in our framework). An additional advantage of the Complete Subtree method is the separation of the labels and the session key which has a consequence on the message length; see discussion at Section 4.1.

[^3]
$S_{i, j}$ contains all marked leaves (non-black).

### 3.2 The Subset Difference Method

The main disadvantage of the Complete Subtree method is that $\mathcal{N} \backslash \mathcal{R}$ may be partitioned into a number of subsets that is too large. The goal is now to reduce the partition size. We show an improved method that partitions the non-revoked receivers into at most $2 r-1$ subsets (or $1.25 r$ on average), thus getting rid of a $\log N$ factor and effectively reducing the message length accordingly. In return, the number of keys stored by each receiver increases by a factor of $\frac{1}{2} \cdot \log N$. The key characteristic of the Subset-Difference method, which essentially leads to the reduction in message length, is that in this method any user belongs to substantially more subsets than in the first method $(O(N)$ instead of $\log N)$. The challenge is then to devise an efficient procedure to succinctly encode this large set of keys at the user.

## The subset description

As in the previous method, the receivers are viewed as leaves in a complete binary tree. The collection of subsets $S_{1}, \ldots, S_{w}$ defined by this algorithm corresponds to subsets of the form "a group of receivers $G_{1}$ minus another group $G_{2}{ }^{\prime}$, where $G_{2} \subset G_{1}$. The two groups $G_{1}, G_{2}$ correspond to leaves in two full binary subtrees. Therefore a valid subset $S$ is represented by two nodes in the tree ( $v_{i}, v_{j}$ ) such that $v_{i}$ is an ancestor of $v_{j}$. We denote such subset as $S_{i, j}$. A leaf $u$ is in $S_{i, j}$ iff it is in the subtree rooted at $v_{i}$ but not in the subtree rooted at $v_{j}$, or in other words $u \in S_{i, j}$ iff $v_{i}$ is an ancestor of $u$ but $v_{j}$ is not. Figure 2 depicts $S_{i, j}$. Note that all subsets from the Complete Subtree Method are also subsets of the Subset Difference Method; specifically, a subtree appears here as the difference between its parent and its sibling. The only exception is the full tree itself, and we will add a special subset for that. We postpone the description of the key assignment till later; for the time being assume that each subset $S_{i, j}$ has an associated key $L_{i, j}$.

## The Cover

For a given set $\mathcal{R}$ of revoked receivers, let $u_{1}, \ldots, u_{r}$ be the leaves corresponding to the elements in $\mathcal{R}$. The Cover is a collection of disjoint subsets $S_{i_{1}, j_{1}}, S_{i_{2}, j_{2}} \ldots, S_{i_{m}, j_{m}}$ which partitions $\mathcal{N} \backslash \mathcal{R}$. Below is an
algorithm for finding the cover, and an analysis of its size (number of subsets).
Finding the Cover: The method partitions $\mathcal{N} \backslash \mathcal{R}$ into disjoint subsets $S_{i_{1}, j_{1}}, S_{i_{2}, j_{2}} \ldots, S_{i_{m}, j_{m}}$ as follows: let $S T(\mathcal{R})$ be the (directed) Steiner Tree induced by $\mathcal{R}$ and the root. We build the subsets collection iteratively, maintaining a tree $T$ which is a subtree of $S T(\mathcal{R})$ with the property that any $u \in \mathcal{N} \backslash \mathcal{R}$ that is below a leaf of $T$ has been covered. We start by making $T$ be equal to $S T(\mathcal{R})$ and then iteratively remove nodes from $T$ (while adding subsets to the collection) until $T$ consists of just a single node:

1. Find two leaves $v_{i}$ and $v_{j}$ in $T$ such that the least-common-ancestor $v$ of $v_{i}$ and $v_{j}$ does not contain any other leaf of $T$ in its subtree. Let $v_{l}$ and $v_{k}$ be the two children of $v$ such that $v_{i}$ a descendant of $v_{l}$ and $v_{j}$ a descendant of $v_{k}$. (If there is only one leaf left, make $v_{i}=v_{j}$ to the leaf, $v$ to be the root of $T$ and $v_{l}=v_{k}=v$. )
2. If $v_{l} \not \equiv v_{i}$ then add the subset $S_{l, i}$ to the collection; likewise, if $v_{k} \not \equiv v_{j}$ add the subset $S_{k, j}$ to the collection.
3. Remove from $T$ all the descendants of $v$ and make it a leaf.

An alternative description of the cover algorithm is as follows: consider maximal chains of nodes with outdegree 1 in $S T(\mathcal{R})$. More precisely, each such chain is of the form $\left[v_{i_{1}}, v_{i_{2}}, \ldots v_{i_{\ell}}\right]$ where (i) all of $v_{i_{1}}, v_{i_{2}}, \ldots v_{i_{\ell-1}}$ have outdegree 1 in $S T(\mathcal{R})$ (ii) $v_{i_{\ell}}$ is either a leaf or a node with outdegree 2 and (iii) the parent of $v_{i_{1}}$ is either a node of outdegree 2 or the root. For each such chain where $\ell \geq 2$ add a subsets $S_{i_{1}, i_{\ell}}$ to the cover. Note that all nodes of outdegree 1 in $S T(\mathcal{R})$ are members of precisely one such chain.
The cover size: Lemma 3 shows that a cover can contain at most $2 r-1$ subsets for any set of $r$ revocations. Furthermore, if the set of revoked leaves is random, then the average number of subsets in a cover is $1.25 r$.

Lemma 3 Given any set of revoked leaves $\mathcal{R}$, the above method partitions $\mathcal{N} \backslash \mathcal{R}$ into at most $2 r-1$ disjoint subsets.

Proof: Every iteration increases the number of subsets by at most two (in step 2) and reduces the number of the Steiner leaves by one (in Step 3), except the last iteration that may not reduce the number of leaves but adds only one subset. Starting with $r$ leaves, the process generates the total of $2 r-1$ subsets. Moreover, every non-revoked $u$ is in exactly one subset, the one defined by the first chain of nodes of outdegree 1 in $S T(R)$ that is encountered while moving from $u$ towards the root. This encounter must hit a non-empty chain, since the path from $u$ to the root cannot join $S T(R)$ in an outdegree 2 node, since this implies that $u \in \mathcal{R}$.

The next lemma is concerned with covering more general sets than those obtained by removing users. Rather it assumes that we are removing a collection of subsets from the Subset Difference collection. It is applied later in Sections 4.2 and 5.2.

Lemma 4 Let $\mathcal{S}=S_{i_{1}}, S_{i_{2}}, \ldots S_{i_{m}}$ be a collection of $m$ disjoint subsets from the underlying collection defined by the Subset Difference method, and $\mathcal{U}=\cup_{j=1}^{m} S_{i_{j}}$. Then the leaves in $\mathcal{N} \backslash \mathcal{U}$ can be covered by at most $3 m-1$ subsets from the underlying Subset Difference collection.

Proof: The proof is by induction on $m$. When $m=1, \mathcal{S}$ contains a single set. Let this set be $S_{a, b}$, which is the set that is represented by two nodes in the tree $\left(v_{a}, v_{b}\right)$. Denote by $v_{c}$ and $v_{c^{\prime}}$ the parent and the sibling of $v_{b}$ respectively (it is possible that $v_{a} \equiv v_{c}$ ), and by $r$ the root of the tree. Then the leaves in $\mathcal{N} \backslash \mathcal{U}$ are covered by the following two sets $S_{r, a}$ and $S_{c, c^{\prime}}$. If $v_{a} \equiv v_{c}$ then the cover consists of a single set, $S_{r, c^{\prime}}$.

To handle the case where $m>1$, we need the following definition. We say that a set $S_{x, y}$ is nested within the set $S_{a, b}$ if the tree node $v_{x}$ is contained in the subtree rooted at $v_{b}$. Note that if two subsets $S_{a, b}$
and $S_{a^{\prime}, b^{\prime}}$ are disjoint but not nested then the subtrees rooted at $v_{a}$ and $v_{a^{\prime}}$ must be disjoint ${ }^{5}$. Consider the following two cases:

1. All sets in $\mathcal{S}$ are maximal with respect to the nesting property. Let $S_{i_{j}}=S_{a_{j}, b_{j}}$ be the $j^{\text {th }}$ set in $\mathcal{S}$. A cover for $\mathcal{N} \backslash \mathcal{U}$ is constructed by first covering all the subtrees rooted at the $v_{b_{j}}$ 's, and then covering the rest of the leaves that are not contained in any one of the subtrees rooted at $v_{a_{j}}$. That is, for each set $S_{a_{j}, b_{j}}$ in $\mathcal{S}$, construct the set $S_{c, c^{\prime}}$ where $v_{c}$ and $v_{c^{\prime}}$ are the parent and the sibling of $v_{b_{j}}$ respectively for the total of $m$ sets. To cover the rest, treat the nodes $v_{a_{1}}, \ldots, v_{a_{m}}$ as $m$ revoked leaves and apply Lemma 3 to cover this tree. This requires $2 m-1$ additional sets, hence the number of sets required to cover $\mathcal{N} \backslash \mathcal{U}$ in this case is $3 m-1$.
2. $\mathcal{S}=\mathcal{S}_{1} \cup \mathcal{S}_{2}$ such that $\left|\mathcal{S}_{1}\right|=k \geq 1$ and there exists a maximal set $S_{a, b} \in \mathcal{S}_{2}$ with respect to the nesting property such that all sets in $\mathcal{S}_{1}$ are nested within $S_{a, b}$. Let $\mathcal{U}^{\prime}$ be the subtree rooted at $v_{b}$. The idea is to first cover $\mathcal{N} \backslash\left(\mathcal{U} \cup \mathcal{U}^{\prime}\right)$ and then cover the leaves in $\mathcal{U}^{\prime} \backslash \mathcal{U}$. The first part of the cover can be obtained by applying the lemma recursively with the input $\mathcal{S}_{2}$, and the second part by applying it recursively with $\mathcal{S}_{1}$. By the induction hypothesis, this requires the total number of $3(m-k)-1+3 k-1=3 m-2$ sets.

Average-case analysis: The analysis of Lemma 3 is a worst-case analysis and there are instances which achieve actually require $2 r-1$ sets. However, it is a bit pessimistic in the sense that it ignores the fact that a chain of nodes of outdegree 1 in $S T(\mathcal{R})$ may consist only of the end point, in which case no subset is generated. This corresponds to the case where $v_{l} \equiv v_{i}$ or $v_{r} \equiv v_{j}$ in Step 2. Suppose that the revoked set $\mathcal{R}$ is selected at random from all subsets of cardinality $r$ of $\mathcal{N}$, then what is the expected number of subsets generated? The question is how many outdegree 1 chains are empty (i.e. contain only one point). We can bound it from above as follows: consider any chain for which it is known that there are $k$ members beneath it. Then the probability that the chain is not empty is at most $2^{-(k-1)}$. For any $1 \leq k \leq r$ there can be at most $r / k$ chains such that there are $k$ leaves beneath it, since no such chain can be ancestor of another chain with $k$ descendants. Therefore the expected number of non-empty chains is bounded by

$$
\sum_{k=1}^{r} \frac{r}{k} \cdot \frac{1}{2^{k-1}} \leq 2 r \sum_{k=1}^{\infty} \frac{1}{k} \cdot \frac{1}{2^{k}} \leq 2 \ln 2 \cdot r \approx 1.38 \cdot r
$$

Simulation experiments have shown a tighter bound of $1.25 r$ for the random case. So the actual number of subsets used by the Subset Difference scheme is expected to be slightly lower than the $2 r-1$ worst case result.

## Key assignment to the subsets

We now define what information each receiver must store. If we try and repeat the information-theoretic approach of the previous scheme where each receiver needs to store explicitly the keys of all the subsets it belongs to, the storage requirements would expand tremendously: consider a receiver $u$; for each complete subtree $T_{k}$ it belongs to, $u$ must store a number of keys proportional to the number of nodes in the subtree $T_{k}$ that are not on the path from the root of $T_{k}$ to $u$. There are $\log N$ such trees, one for each height $1 \leq k \leq \log N$, yielding a total of $\sum_{k=1}^{\log N}\left(2^{k}-k\right)$ which is $O(N)$ keys.

[^4]We therefore devise a key assignment method that requires a receiver to store only $O(\log N)$ keys per subtree, for the total of $O\left(\log ^{2} N\right)$ keys.

While the total number of subsets to which a user $u$ belongs is $O(N)$, these can be grouped into $\log N$ clusters defined by the first subset $i$ (from which another subsets is subtracted). The way we proceed with the keys assignment is to choose for each $1 \leq i \leq N$ corresponding to an internal node in the full binary tree a random and independent value $\mathrm{LABEL}_{i}$. This value should induce the keys for all legitimate subsets of the form $S_{i, j}$. The idea is to employ the method used by Goldreich, Goldwasser and Micali [28] to construct pseudo-random functions, which was also used by Fiat and Naor [23] for purposes similar to ours.

Let $G$ be a (cryptographic) pseudo-random sequence generator (see definition below) that triples the input, i.e. whose output length is three times the length of the input; let $G_{L}(S)$ denote the left third of the output of $G$ on seed $S, G_{R}(S)$ the right third and $G_{M}(S)$ the middle third. We say that $G:\{0,1\}^{n} \mapsto$ $\{0,1\}^{3 n}$ is a pseudo-random sequence generator if no polynomial-time adversary can distinguish the output of $G$ on a randomly chosen seed from a truly random string of similar length. Let $\varepsilon_{4}$ denote the bound on the distinguishing probability.

Consider now the subtree $T_{i}$ (rooted at $v_{i}$ ). We will use the following top-down labeling process: the root is assigned a label $\mathrm{LABEL}_{i}$. Given that a parent was labeled $S$, its two children are labeled $G_{L}(S)$ and $G_{R}(S)$ respectively. Let $\mathrm{LABEL}_{i, j}$ be the label of node $v_{j}$ derived in the subtree $T_{i}$ from $\mathrm{LABEL}_{i}$. Following such a labeling, the key $L_{i, j}$ assigned to set $S_{i, j}$ is $G_{M}$ of $\mathrm{LABEL}_{i, j}$. Note that each label induces three parts: $G_{L}$ - the label for the left child, $G_{R}$ - the label for the right child, and $G_{M}$ the key at the node. The process of generating labels and keys for a particular subtree is depicted in Figure 3. For such a labeling process, given the label of a node it is possible to compute the labels (and keys) of all its descendants. On the other hand, without receiving the label of an ancestor of a node, its label is pseudo-random and for a node $j$, given the labels of all its descendants (but not including itself) the key $L_{i, j}$ is pseudo-random (LABEL ${ }_{i, j}$, the label of $v_{j}$, is not pseudo-random given this information simply because one can check for consistency of the labels). It is important to note that given $\mathrm{LABEL}_{i}$, computing $L_{i, j}$ requires at most $\log N$ invocations of $G$.

We now describe the information $I_{u}$ that each receiver $u$ gets in order to derive the key assignment described above. For each subtree $T_{i}$ such that $u$ is a leaf of $T_{i}$ the receiver $u$ should be able to compute $L_{i, j}$ iff $j$ is not an ancestor of $u$. Consider the path from $v_{i}$ to $u$ and let $v_{i_{1}}, v_{i_{2}}, \ldots v_{i_{k}}$ be the nodes just "hanging off" the path, i.e. they are adjacent to the path but not ancestors of $u$ (see Figure 3). Each $j$ in $T_{i}$ that is not an ancestor of $u$ is a descendant of one of these nodes. Therefore if $u$ receives the labels of $v_{i_{1}}, v_{i_{2}}, \ldots v_{i_{k}}$ as part of $I_{u}$, then invoking $G$ at most $\log N$ times suffices to compute $L_{i, j}$ for any $j$ that is not an ancestor of $u$.

As for the total number of keys (in fact, labels) stored by receiver $u$, each tree $T_{i}$ of depth $k$ that contains $u$ contributes $k-1$ keys (plus one key for the case where there are no revocations), so the total is

$$
1+\sum_{k=1}^{\log N+1} k-1=1+\frac{(\log N+1) \log N}{2}=\frac{1}{2} \log ^{2} N+\frac{1}{2} \log N+1
$$

Decryption Step: At decryption time, a receiver $u$ first finds the subset $S_{i, j}$ such that $u \in S_{i, j}$, and computes the key corresponding to $L_{i, j}$. Using the techniques described in the complete subtree method for table lookup structure, this subset can be found in $O(\log \log N)$. The evaluation of the subset key takes now at most $\log N$ applications of a pseudo-random generator. After that, a single decryption is needed.

$\operatorname{LABEL}_{i, j}$ and the key $L_{i, j}$. Right: leaf $u$ receives the labels of $v_{i_{1}}, \ldots v_{i_{k}}$ that are induced by the label $\mathrm{LABEL}_{i}$ of $v_{i}$.

## Security

In order to prove security we show that the key-indistinguishability condition (Definition 9 of Section 6) holds for this method, namely that each key is indistinguishable from a random key for all users not in the corresponding subset. Theorem 12 of Section 6 proves that this condition implies the security of the algorithm.

Observe first that for any $u \in \mathcal{N}, u$ never receives keys that correspond to subtrees to which it does not belong. Let $S_{i}$ denote the set of leaves in the subtree $T_{i}$ rooted at $v_{i}$. For any set $S_{i, j}$ the key $L_{i, j}$ is (information theoretically) independent of all $I_{u}$ for $u \notin S_{i}$. Therefore we have to consider only the combined secret information of all $u \in S_{j}$. This is specified by at most $\log N$ labels - those hanging on the path from $v_{i}$ to $v_{j}$ plus the two children of $v_{j}$ - which are sufficient to derive all other labels in the combined secret information. Note that these labels are $\log N$ strings that were generated independently by $G$, namely it is never the case that one string is derived from another. Hence, a hybrid argument implies that the probability of distinguishing $L_{i, j}$ from random can be at most $\varepsilon_{4} / \log N$, where $\varepsilon_{4}$ is the bound on distinguishing outputs of $G$ from random strings.

Theorem 5 The Subset Difference method requires (i) message length of at most $2 r-1$ keys (ii) to store $\frac{1}{2} \log ^{2} N+\frac{1}{2} \log N+1$ keys at a receiver and (iii) $O(\log N)$ operations plus a single decryption operation to decrypt a message. Moreover, the method is secure in the sense of Definition 11.

### 3.3 Lower Bounds

## Generic lower bound

Any ciphertext in a revocation system when $r$ users are revoked should clearly encode the original message plus the revoked subset, since it is possible to test which users decrypt correctly and which incorrectly using the preassigned secret information only (that was chosen independently of the transmitted message). Therefore we have a "generic" lower bound of $\log \binom{N}{r} \approx r \log N$ bits on the length of the header (or extra bits). Note that the subset difference method approaches this bound - the number of extra bits there is $O(r \cdot$ key-size $)$.

## Lower bounds for the information-theoretic case

If the keys to all the subsets are chosen independently (and hence $u$ explicitly receives in $I_{u}$ all $L_{i}$ such that $u \in S_{i}$ ) then Luby and Staddon's lower bound for the "Or Protocol" [31] can be applied. They used the Sunflower Lemma (see below) to show that any scheme which employs $m$ subsets to revoke $r$ users must have at least one member with at least $\frac{\binom{N}{r}^{1 / m}}{m r}$ keys. This means that if we want the number of subsets $m$ to be at most $r$, then the receivers should store at least $\Omega\left(N / r^{3}\right)$ keys (as $\binom{N}{r} \geq\left(\frac{N}{r}\right)^{r}$ ). In the case where $r \ll N$, our (non-information-theoretic) Subset Difference method does better than this lower bound.

Note that when the number of subsets used in a broadcast is $O(r \log N)$ (as it is in the Complete Subtree method) then the above bound becomes useless. We now show that even if one is willing to use this many subsets (or even more), then at least $\Omega(\log N)$ keys should be stored by the receivers. We recall the Sunflower Lemma of Erdos and Rado (see [21]).

Definition 6 Let $S_{1}, S_{2}, \ldots, S_{\ell}$ be subsets of some underlying finite ground set. We say that they are a sunflower if the intersections of any pair of the subsets are equal, in other words, for all $1 \leq i<j \leq \ell$ we have $S_{i} \cap S_{j}=\bigcap_{i=1}^{\ell} S_{i}$.

The Sunflower Lemma says that in every set system there exists a sufficiently large sunflower: in a collection of $N$ subsets each of size at most $k$ there exists a sunflower consisting of at least $\frac{N^{1 / k}}{k}$ subsets.

Consider now the sets $T_{1}, T_{2}, \ldots T_{N}$ of keys the receivers store. I.e. $T_{u}=\left\{L_{i} \mid u \in S_{i}\right\}$. If for all $u$ we have that $\left|T_{u}\right| \leq k$, then there exists a sunflower of $\frac{N^{1 / k}}{k}$ subsets. Pick one $u$ such that $T_{u}$ is in the sunflower and make $\mathcal{R}=\{u\}$. This means that in order to cover the other members of the sunflower we must use at least $\frac{N^{1 / k}}{k}-1$ keys, since no $S_{i}$ can be used to cover two of the other members of the sunflower (otherwise $S_{i}$ must also have the revoked $u$ as a member). This means, for instance, that if $k=\sqrt{\log N}$ then just to revoke a single user requires using at least $\frac{2 \sqrt{\log N}}{\sqrt{\log N}}-1$ subsets.

## 4 Further Discussions

### 4.1 Implementation Issues

Implementing $E_{L}$ and $F_{K}$
One of the issues that arises in implementing a Subset-Cover scheme is how to implement the two cryptographic primitives $E_{L}$ and $F_{K}$. The basic requirements from $E_{L}$ and $F_{K}$ were outlined above in Section 2. However, it is sometimes desirable to chose an encryption $F$ that might be weaker (uses shorter keys)
than the encryption chosen for $E$. The motivation for that is twofold: (1) to speedup the decoding process at the receiver (2) to shorten the length of the header. Such a strategy makes sense, for example, for copyright protection purposes. There it may not make sense to protect a specific ciphertext so that breaking it is very expensive; on the other hand we do want to protect the long lived keys of the system with a strong encryption scheme.

Suppose that $F$ is implemented by using a stream cipher with a long key, but sending some of its bits in the clear; thus $K$ corresponds to the hidden part of the key and this is the only part that needs to be encrypted in the header. (One reason to use $F$ in such a mode rather than simply using a method designed with a small key is to prevent a preprocessing attack against $F$.) This in itself does not shorten the header, since it depends on the block-length of $E$ (assuming $E$ is implemented by block-cipher). We now provide a specification for using $E$, called Prefix-Truncation, which reduces the header length as well, in addition to achieving speedup, without sacrificing the security of the long-lived keys. Let Prefix ${ }_{i} S$ denote the first $i$ bits of a string $S$. Let $E_{L}$ be a block cipher and $\mathcal{U}$ be a random string whose length is the length of the block of $E_{L}$. Let $K$ be a relatively short key for the cipher $F_{K}$ (whose length is, say, 56 bits). Then, $\left[\operatorname{Prefix}_{|K|} E_{L}(\mathcal{U})\right] \oplus K$ provides an encryption that satisfies the definition of $E$ as described in Section 6. The Prefix-Truncated header is therefore:

$$
\left\langle\left[i_{1}, i_{2}, \ldots, i_{m}, \mathcal{U},\left[\operatorname{Prefix}_{|K|} E_{L_{i_{1}}}(\mathcal{U})\right] \oplus K, \ldots,\left[\operatorname{Prefix}_{|K|} E_{L_{i_{m}}}(\mathcal{U})\right] \oplus K\right], F_{K}(M)\right\rangle
$$

Note that this reduces the length of the header down to about $m \times|K|$ bits long (say $56 m$ ) instead of $m \times|L|$. In the case where the key length of $E$ is marginal, then the following heuristic can be used to remove the factor $m$ advantage that the adversary has in a brute-force attack which results from encrypting the same string $\mathcal{U}$ with $m$ different keys. Instead, encrypt the string $\mathcal{U} \oplus i_{j}$, namely

$$
\left\langle\left[i_{1}, i_{2}, \ldots, i_{m}, \mathcal{U},\left[\operatorname{Prefix}_{|K|} E_{L_{i_{1}}}\left(\mathcal{U} \oplus i_{1}\right)\right] \oplus K, \ldots,\left[\operatorname{Prefix}_{|K|} E_{L_{i_{m}}}\left(\mathcal{U} \oplus i_{m}\right)\right] \oplus K\right], F_{K}(M)\right\rangle
$$

## All-Or-Nothing Encryptions for $F_{K}$

As before, we can imagine cases where the key used by $F_{K}$ is only marginally long enough. Moreover, in a typical scenario like copyright protection, the message $M$ is long (e.g. $M$ may be a title on a CD or a DVD track). In such cases, it is possible to extract more security from the long message for a fixed number of key bits using the All-Or-Nothing encryption mode originally suggested by [40]. These techniques assure that the entire ciphertext must be decrypted before even a single message block can be determined. The concrete method of [40] results in a penalty of a factor of three in the numbers encryptions/decryptions required by a legitimate user; however, for a long message that is composed of $l$ blocks, a brute-force attack requires a factor of $l$ more time than a similar attack would require otherwise. Other All-Or-Nothing methods can be applied as well.

The drawback of using an All-Or-Nothing mode is its latency, namely the entire message $M$ must be decoded before the first block of plaintext is known. This makes the technique unusable for applications that cannot tolerate such latency.

## Frequently Refreshed Session Keys

Suppose that we want to prevent an illegal redistribution channel that will use some low bandwidth means to send $K$, the session key (a low bandwidth label or a bootlegged CD). A natural approach to combat such channel is to encode different parts of the message $M$ with different session keys, and to send all different
session keys encrypted with all the subset keys. That is, send $l>1$ different session keys all encrypted with the same cover, thus increasing the length of the header by a factor of $l$. This means that in order to have only a modest increase in the header information it is important that $m$, the number of subsets, will be as small as possible. Note that the number of decryptions that the receiver needs to perform in order to obtain its key $\mathcal{L}_{i_{j}}$ which is used in this cover remains one.

## Storage at the Center

In both the Complete Subtree and Subset Difference methods, a unique label is associated with each node in the tree. Storing these labels explicitly at the Center can become a serious constraint. However, these labels can be generated at the center by applying a pseudo-random function on the name of the node without affecting the security of the scheme. This reduces the storage required by at the Center to the single key of the pseudo-random function.

Furthermore, it may be desirable to distribute the center between several servers with the objective of avoiding a single or few points of attack. In such a case the distributed pseudo-random functions of [36] may be used to define the labels.

### 4.2 Hierarchical Revocation

Suppose that the receivers are grouped in a hierarchical manner, and that it is desirable to revoke a group that consists of the subordinates of some entity, without paying a price proportional to the group size (for instance all the players of a certain manufacturer). Both methods of Section 3 lend themselves to hierarchical revocation naturally, given the tree structure. If the hierarchy corresponds to the tree employed by the methods, then to revoke the receivers below a certain node counts as just a single user revocation.

By applying Lemma 4 we get that in the Subset Difference Method we can remove any collection of $m$ subsets and cover the rest with $3 m-1$ subsets. Hence, the hierarchical revocation can be performed by first constructing $m$ sets that cover all revoked devices, and then covering all the rest with $3 m-1$, yielding the total of $4 m$ sets.

### 4.3 Public Key methods

In some scenarios it is desireable to use a revocation scheme in a public-key mode, i.e. when the party that generates the ciphertext is not necessarily trustworthy and should not have access to the decryption keys of the users, or when ciphertexts may be generated by a number of parties. Any Subset-Cover revocation algorithm can be used in this mode: the Center (a trusted entity) generates the private-keys corresponding to the subsets and hands each user the private keys it needs for decryption. The (non necessarily trusted) party that generates the ciphertext should only have access to public-keys corresponding to the subsets which we call "the public-key file". That is, $E$ is a public key cryptosystem whereas $F$ is as before. In principal, any public key encryption scheme with sufficient security can be used for $E$. However, not all yield a system with a reasonable efficiency. Below we discuss the problems involved, and show that a Diffie-Hellman type scheme best serves this mode.

Public Key Generation: Recall that the Subtree Difference method requires that subset keys are derived from labels. If used in a public-key mode, the derivation yields random bits that are then used to generate the private/public key pair. For example, if RSA keys are used, then the random strings that are generated by the Pseudo Random Generator $G$ can be used as the random bits which are input to the procedure which generates an RSA key. However, this is rather complicated, both in terms of the bits and time needed.

Therefore, whenever the key assignment is not information-theoretic it is important to use a public-key scheme where the mapping from random bits to the keys is efficient. This is the case with the Diffie-Hellman scheme.

Size of Public Key File: The problem is that the public key file might be large, proportional to $w$, the number of subsets. In the Complete Subtree method $w=2 N-1$ and in the Subtree Difference method it is $N \log N$. An interesting open problem is to come up with a public-key cryptosystem where it is possible to compress the public-keys to a more manageable size. For instance, an identity-based cryptosystem would be helpful for the information-theoretic case where keys are assigned independently. A recent proposal that fits this requirement is [8].

Prefix-Truncated Headers: We would like to use the Prefix-Truncation, described in Section 4.1, with public-key cryptosystem to reduce the header size without sacrificing security of long-term keys. It can not be employed with an arbitrary public key cryptosystem (e.g. RSA). However, a Diffie-Hellman public key system which can be used for the Prefix-Truncation technique can be devised in the following manner.

Let $G$ be a group with a generator $g$ and let the subset keys be $L_{1}=y_{1}, L_{2}=y_{2}, \ldots, L_{w}=y_{w}$ elements in $G$. Let $g^{y_{1}}, g^{y_{2}}, \ldots, g^{y_{w}}$ be their corresponding public keys. Define $h$ as a pairwise-independent function $h: G \mapsto\{0,1\}^{|K|}$ that maps elements which are randomly distributed over $G$ to randomly distributed strings of the desired length (see e.g. [37] for a discussion of such functions). Given the subsets $S_{i_{1}}, \ldots, S_{i_{m}}$ to be used in the header, the encryption $E$ can be done by picking a new element $x$ from $G$, publicizing $g^{x}$, and encrypting $K$ as $E_{L_{i_{j}}}(K)=h\left(g^{x y_{i_{j}}}\right) \oplus K$. That is, the header now becomes

$$
\left\langle\left[i_{1}, i_{2}, \ldots, i_{m}, g^{x}, h, h\left(g^{x y_{i_{1}}}\right) \oplus K, \ldots, h\left(g^{x y_{i_{m}}}\right) \oplus K\right], F_{K}(M)\right\rangle
$$

Interestingly, in terms of the broadcast length such system hardly increases the number of bits in the header as compared with a shared-key system - the only difference is $g^{x}$ and the description of $h$. Therefore this difference is fixed and does not grow with the number of revocations. Note however that the scheme as defined above is not immune to chosen-ciphertext attacks, but only to chosen plaintext ones. Coming up with public-key schemes where prefix-truncation is possible that are immune to chosen ciphertext attacks of either kind is an interesting challenge ${ }^{6}$.

### 4.4 Applications to Multicast

The difference between key management for the scenario considered in this paper and for the Logical Key Hierarchy for multicast is that in the latter the users (i.e. receivers) may update their keys [43, 42]. This update is referred to as a re-keying event and it requires all users to be connected during this event and change their internal state (keys) accordingly. However, even in the multicast scenario it is not reasonable to assume that all the users receive all the messages and perform the required update. Therefore some mechanism that allows individual update must be in place. Taking the stateless approach gets rid of the need for such a mechanism: simply add a header to each message denoting who are the legitimate recipients by revoking those who should not receive it. In case the number of revocations is not too large this may yield a more manageable solution. This is especially relevant when there is a single source for the sending messages or when public-keys are used.
Backward secrecy: Note that revocation in itself lacks backward secrecy in the following sense: a constantly listening user that has been revoked from the system records all future transmission (which it can't decrypt anymore) and keeps all ciphertexts. At a later point it gains a valid new key (by re-registering)

[^5]which allows decryption of all past communication. Hence, a newly acquired user-key can be used to decrypt all past session keys and ciphertexts. The way that [43, 42] propose to achieve backward secrecy is to perform re-keying when new users are added to the group (such a re-keying may be reduced to only one way chaining, known as LKH+), thus making such operations non-trivial. We point out that in the subsetcover framework and especially in the two methods we proposed it may be easier: At any given point of the system include in the set of revoked receivers all identities that have not been assigned yet. As a result, a newly assigned user-key cannot help in decrypting an earlier ciphertext. Note that this is feasible since we assume that new users are assigned keys in a consecutive order of the leaves in the tree, so unassigned keys are consecutive leaves in the complete tree and can be covered by at most $\log N$ sets (of either type, the Complete-Subtree method or the Subtree-Difference method). Hence, the unassigned leaves can be treated with the hierarchical revocation technique, resulting in adding at most $\log N$ revocations to the message.

### 4.5 Comparison to CPRM

CPRM/CPPM (Content Protection for Recordable Media and Pre-Recorded Media) is a technology announced and developed by 4 companies (known as the 4C's): IBM, Intel, Matsushita and Toshiba [18]. It defines a method for protecting content on physical media such as recordable DVD, DVD Audio, Secure Digital Memory Card and Secure CompactFlash. A licensing Entity (the Center) provides a unique set of secret device keys to be included in each device at manufacturing time. The licensing Entity also provides a Media Key Block (MKB) to be placed on each compliant media (for example, on the DVD). The MKB is essentially the Header of the ciphertext which encrypts the session key. It is assumed that this header resides on a write-once area on the media, e.g. a Pre-embossed lead-in area on the recordable DVD. When the compliant media is placed in a player/recorder device, it computes the session key from the Header (MKB) using its secret keys; the content is then encrypted/decrypted using this session key.

The algorithm employed by CPRM is essentially a Subset-Cover scheme. Consider a table with $A$ rows and $C$ columns. Every device (receiver) is viewed as a collection of $C$ entries from the table, exactly one from each column, that is $u=\left[u_{1}, \ldots, u_{C}\right]$ where $u_{i} \in\{0,1, \ldots, A-1\}$. The collection of subsets $S_{1}, \ldots, S_{w}$ defined by this algorithm correspond to subsets of receivers that share the same entry at a given column, namely $S_{r, i}$ contains all receivers $u=\left[u_{1}, \ldots, u_{C}\right]$ such that $u_{i}=r$. For every $0 \leq i \leq A-1$ and $1 \leq j \leq C$ the scheme associates a key denoted by $L_{i, j}$. The private information $I_{u}$ that is provided to a device $u=\left[u_{1}, \ldots, u_{C}\right]$ consists of $C$ keys $L_{u_{1}, 1}, L_{u_{2}, 2}, \ldots, L_{u_{C}, C}$.

For a given set $\mathcal{R}$ of revoked devices, the method partitions $\mathcal{N} \backslash \mathcal{R}$ as follows: $S_{i, j}$ is in the cover iff $S_{i, j} \cap \mathcal{R}=\emptyset$. While this partition guarantees that a revoked device is never covered, there is a low probability that a non-revoked device $u \notin \mathcal{R}$ will not be covered as well and therefore become non-functional ${ }^{7}$.

The CPRM method is a Subset-Cover method with two exceptions: (1) the subsets in a cover are not necessarily disjoint and (2) the cover is not always perfect as a non-revoked device may be uncovered. Note that the CPRM method is not $r$-flexible: the probability that a non-revoked device is uncovered grows with $r$, hence in order to keep it small enough the number of revocations must be bounded by $A$.

For the sake of comparing the performance of CPRM with the two methods suggested in this paper, assume that $C=\log N$ and $A=r$. Then, the message is composed of $r \log N$ encryptions, the storage at the receiver consists of $\log N$ keys and the computation at the receiver requires a single decryption. These bounds are similar to the Complete Subtree method; however, unlike CPRM, the Complete Subtree method is $r$-flexible and achieves perfect coverage. The advantage of the Subset Difference Method is much more substantial: in addition to the above, the message consists of $1.25 r$ encryptions on average, or of at most $2 r-1$ encryptions, rather than $r \log N$.

[^6]For example, in DVD Audio, the amount of storage that is dedicated for its MKB (the header) is 3 MB . This constraints the maximum allowed message length. Under a certain choice of parameters, such as the total number of manufactured devices and the number of distinct manufacturers, with the current CPRM algorithm the system can revoke up to about 10,000 devices. In contrast, for the same set of parameters and the same 3 MB constraint, a Subset-Difference algorithm achieves up to 250,00(!) revocations, a factor of 25 improvement over the currently used method. This major improvement is partly due to fact that hierarchical revocation can be done very effectively, a property that the current CPRM algorithm does not have.

## 5 Tracing Traitors

It is highly desirable that a revocation mechanism could work in tandem with a tracing mechanism to yield a trace and revoke scheme. We show a tracing method that works for many schemes in the subset-cover framework. The method is quite efficient. The goal of a tracing algorithm is to find the identities of those that contributed their keys to an illicit decryption box and revoke them; short of identifying them we should render the box useless by finding a "pattern" that does not allow decryption using the box, but still allows broadcasting to the legitimate users. Note that this is a slight relaxation of the requirement of a tracing mechanism, say in [34] (which requires an identification of the traitor's identity) and in particular it lacks self enforcement [20]. However as a mechanism that works in conjunction with the revocation scheme it is a powerful tool to combat piracy.

## The model

Suppose that we have found an illegal decryption-box (decoder, or clone) which contains the keys associated with at most $t$ receivers $u_{1}, \ldots, u_{t}$ known as the "traitors".

We are interested in "black-box" tracing, i.e. one that does not take the decoder apart but by providing it with an encrypted message and observing its output (the decrypted message) tries to figure out who leaked the keys. A pirate decoder is of interest if it correctly decodes with probability $p$ which is at least some threshold $q$, say $q>0.5$. We assume that the box has a "reset button", i.e. that its internal state may be retrieved to some initial configuration. In particular this excludes a "locking" strategy on the part of the decoder which says that in case it detects that it is under test, it should refuse to decode further. Clearly software-based systems can be simulated and therefore have the reset property.

The result of a tracing algorithm is either a subset consisting of traitors or a partition into subsets that renders the box useless i.e. given an encryption with the given partition it decrypts with probability smaller than the threshold $q$ while all good users can still decrypt.

In particular, a "subsets based" tracing algorithm devises a sequence of queries which, given a black-box that decodes with probability above the threshold $q$, produces the results mentioned above. It is based on constructing useful sets of revoked devices $\mathcal{R}$ which will finally allow the detection of the receiver's identity or the configuration that makes the decoder useless. A tracing algorithm is evaluated based on (i) the level of performance downgrade it imposes on the revocation scheme (ii) number of queries needed.

### 5.1 The Tracing Algorithm

Subset tracing: An important procedure in our tracing mechanism is one that given a partition $\mathcal{S}=$ $S_{i_{1}}, S_{i_{2}}, \ldots S_{i_{m}}$ and an illegal box outputs one of two possible outputs: either (1) that the box cannot decrypt with probability greater than the threshold when the encryption is done with partition $\mathcal{S}$ or (ii) Finds

$S_{i, j}$, depicted in the left. The black triangle indicates the excluded subtree. $L$ and $R$ are the left and the right children of $v_{i}$. The resulting sets $S_{L, j}$ and $S_{i, L}$ are depicted to the right.
a subset $S_{i_{j}}$ such that $S_{i_{j}}$ contains a traitor. Such a procedure is called subset tracing. We describe it in detail in Section 5.1.1.
Bifurcation property: Given a subset-tracing procedure, we describe a tracing strategy that works for many Subset-Cover revocation schemes. The property that the revocation algorithm should satisfy is that for any subset $S_{i}, 1 \leq i \leq w$, it is possible to partition $S_{i}$ into two (or constant) roughly equal sets, i.e. that there exists $1 \leq i_{1}, i_{2} \leq w$ such that $S_{i}=S_{i_{1}} \cup S_{i_{2}}$ and $\left|S_{i_{1}}\right|$ is roughly the same as $\left|S_{i_{2}}\right|$. For a Subset Cover scheme, let the bifurcation value be the relative size of the largest subset in such a split.

Both the Complete Subtree and the Subtree Difference methods satisfy this requirement: in the case of the Complete Subtree Method each subset, which is a complete subtree, can be split into exactly two equal parts, corresponding to the left and right subtrees. Therefore the bifurcation value is $1 / 2$. As for the Subtree Difference Method, Each subset $S_{i, j}$ can be split into two subsets each containing between one third and two thirds of the elements. Here, again, this is done using the left and right subtrees of node $i$. See Figure 4. The only exception is when $i$ is a parent of $j$, in which case the subset is the complete subtree rooted at the other child; such subsets can be perfectly split. The worst case of $(1 / 3,2 / 3)$ occurs when $i$ is the grandparent of $j$. Therefore the bifurcation value is $2 / 3$.
The Tracing Algorithm: We now describe the general tracing algorithm, assuming that we have a good subset tracing procedure. The algorithm maintains a partition $S_{i_{1}}, S_{i_{2}}, \ldots S_{i_{m}}$. At each phase one of the subsets is partitioned, and the goal is to partition a subset only if it contains a traitor.

Each phase initially applies the subset-tracing procedure with the current partition $\mathcal{S}=S_{i_{1}}, S_{i_{2}}, \ldots S_{i_{m}}$. If the procedure outputs that the box cannot decrypt with $\mathcal{S}$ then we are done, in the sense that we have found a way to disable the box without hurting any legitimate user. Otherwise, let $S_{i_{j}}$ be the set output by the procedure, namely $S_{i_{j}}$ contains the a traitor.

If $S_{i_{j}}$ contains only one possible candidate - it must be a traitor and we permanently revoke this user; this doesn't hurt a legitimate user. Otherwise we split $S_{i_{j}}$ into two roughly equal subsets and continue with the new partitioning. The existence of such a split is assured by the bifurcation property.
Analysis: Since a partition can occur only in a subset that has a traitor and contains more than one element, it follows that the number of iterations can be at $\operatorname{most} t \log _{a} N$, where $a$ is the inverse of the bifurcation
value (a more refined expression is $t\left(\log _{a} N-\log _{2} t\right.$ ), the number of edges in a binary tree with $t$ leaves and depth $\log _{a} N$.)

### 5.1.1 The Subset Tracing Procedure

The Subset Tracing procedure first tests whether the box decodes with sufficiently high probability (say greater than 0.5 ) when the partition is $\mathcal{S}=S_{i_{1}}, S_{i_{2}}, \ldots S_{i_{m}}$. If not, then it concludes (and outputs) that the box cannot decrypt with $\mathcal{S}$. Otherwise, it needs to find a subset $S_{i_{j}}$ that contains a traitor.

Let $p_{j}$ be the probability that the box decodes the ciphertext

$$
\left\langle\left[i_{1}, i_{2}, \ldots, i_{m}, E_{L_{i_{1}}}\left(R_{K}\right), E_{L_{i_{2}}}\left(R_{K}\right), \ldots, E_{L_{i_{j}}}\left(R_{K}\right), E_{L_{i_{j+1}}}(K), \ldots, E_{L_{i_{m}}}(K)\right], F_{K}(M)\right\rangle
$$

where $R_{K}$ is a random string of the same length as the key $K$. That is, $p_{j}$ is the probability of decoding when the first $j$ subsets are noisy and the remaining subsets encrypt the correct key. Note that $p_{0}=p$ and $p_{m}=0$, hence there must be some $0<j \leq m$ for which $\left|p_{j-1}-p_{j}\right| \geq \frac{p}{m}$.

Claim 7 Let $\varepsilon$ be an upper bound on the sum of the probabilities of breaking the encryption scheme $E$ and key assignment method. If $p_{j-1}$ is different from $p_{j}$ by more than $\varepsilon$, then the set $S_{i_{j}}$ must contain a traitor.

Proof: From the box's point of view, a ciphertext that contains $j-1$ noisy subsets is different from a ciphertext that contains $j$ noisy subsets only if the box is able to distinguish between $E_{L_{i_{j}}}(K)$ and $E_{L_{i_{j}}}\left(R_{K}\right)$. Since this cannot be due to breaking the encryption scheme or the key assignment method alone, it follows that the box must contain $L_{i_{j}}$.

We now describe a binary-search-like method that efficiently finds a pair of values $p_{j}, p_{j-1}$ among $p_{0}, \ldots, p_{m}$ satisfying $\left|p_{j-1}-p_{j}\right| \geq \frac{p}{m}$. Starting with the entire interval $[1, m]$, the search is repeatedly narrowed down to an arbitrary interval $[a, b]$. At each stage, the middle value $p_{\frac{a+b}{}}$ is computed (approximately) and the interval is further halved either to the left half or to the right half, depending on difference between $p_{\frac{a+b}{2}}$ and the endpoint values $p_{a}$ and $p_{b}$ of the interval and favoring the interval with the larger difference. The method is outlined below; it outputs the index $j$.

```
\(\underline{\text { SubsetTracing }\left(a, b, p_{a}, p_{b}\right)}\)
If ( \(a==b-1\) )
    return \(b\)
Else
    \(\mathrm{c}=\left\lceil\frac{a+b}{2}\right\rceil\)
    Find \(p_{c}\)
    If \(\left|p_{c}-p_{a}\right| \geq\left|p_{b}-p_{a}\right|\)
        SubsetTracing \(\left(a, c, p_{a}, p_{c}\right)\)
    Else
        SubsetTracing \(\left(c, b, p_{c}, p_{b}\right)\)
```

Efficiency: Let the probability of error be $\epsilon$ and the range error be $\delta$. Subset tracing is comprised of $\log m$ steps. At each step it should decide with probability at least $1-\epsilon$ the following:

- If $\frac{\left|p_{c}-p_{a}\right|}{\left|p_{b}-p_{a}\right|}>\frac{1}{2}(1+\delta)$, decide " $\left|p_{c}-p_{a}\right|>\left|p_{b}-p_{c}\right| "$
- If $\frac{\left|p_{c}-p_{a}\right|}{\left|p_{b}-p_{a}\right|}<\frac{1}{2}(1-\delta)$, decide " $\left|p_{c}-p_{a}\right|<\mid p_{b}-p_{c}$ ""
- Otherwise, any decision is acceptable.

In order to distinguish these two cases apply Claim 8 below. Since the Claim is applied $\log m$ times, choose $\delta=\frac{1}{\log m}$. At each step with probability at least $1-\varepsilon$ the interval $\left|p_{b}-p_{a}\right|$ shrinks by at least a factor of $\frac{1}{2}(1-\delta)$, so at the $i^{\text {th }}$ step the interval length is (with probability at least $\left.i \cdot \epsilon\right)$ larger than $\left(\frac{1}{2}(1-\delta)\right)^{i}$; hence the smallest possible interval when $i=\delta=\frac{1}{\log m}$ is of length $\Delta \geq \frac{1}{e m}$, with probability at least $\varepsilon \log m$. It follows that a subset tracing procedure that works with success probability of $(1-\varepsilon \log m)$ requires at most $O\left(m^{2} \log \frac{1}{\varepsilon} \log ^{3} m\right)$ ciphertext queries to the decoding box over the entire procedure. Note that a total probability of success bounded away from zero is acceptable, since it is possible to verify that the resulting $p_{j-1}, p_{j}$ differ, and hence $\epsilon$ can be $O(1 / \log m)$.

Claim 8 Let $p_{a}, p_{b}$ be the two probabilities at the end-points of an interval $[a, b]$ such that $\left|p_{a}-p_{b}\right| \geq \Delta$, and let $X_{c}$ be a random variable such that $\operatorname{Prob}\left[X_{c}=1\right]=p_{c}$ where $p_{c}$ is unknown. We would like to sample the decoding box and decide " $\left|p_{c}-p_{a}\right|>\left|p_{b}-p_{c}\right|$ " or " $\left|p_{c}-p_{a}\right|<\left|p_{b}-p_{c}\right|$ " according to the definition given above. The number of samples (i.e. ciphertext queries) required to reach this conclusion with error at most $\varepsilon$ is $O\left(\log \left(\frac{1}{\varepsilon}\right) /\left(\Delta^{2} \delta^{2}\right)\right)$.

Proof: Let $X_{a}, X_{b}$ and $X_{c}$ be $\{0,1\}$ variables satisfying $P\left[X_{a}=1\right]=p_{a}, P\left[X_{b}=1\right]=p_{b}$ and $P\left[X_{c}=\right.$ $1]=p_{c}$. The variant of Chernoff bounds described in [1], Corollary A. 7 [p. 236], states that for a sequence of mutually independent random variables $Y_{1}, \ldots, Y_{n}$ satisfying $P\left[Y_{i}=1-p\right]=p$ and $P\left[Y_{i}=-p\right]=1-p$ it holds that $P\left[\left|\sum_{i}^{n} Y_{i}\right|>t\right]<2 e^{-2 t^{2} / n}$ for $t>0$. Suppose we want to estimate $p_{a}$ by sampling $n_{a}$ times from the distribution of $X_{a}$. Let $p_{a}^{\prime}$ be estimation that results from this sampling. Applying the above Chernoff's bound we can conclude that $P\left[\left|p_{a}^{\prime}-p_{a}\right|>t\right]<2 e^{-2 n\left(t+p_{a}\right)^{2}}$. Hence, by choosing $n_{a}=\frac{\ln \frac{2}{\varepsilon}}{2\left(t+p_{a}\right)^{2}}$, the estimated $p_{a}^{\prime}$ obtained from sampling $n_{a}$ times satisfies $P\left[\left|p_{a}^{\prime}-p_{a}\right|>t\right]<\varepsilon$. Clearly, by sampling $n=\frac{\ln \frac{2}{\epsilon}}{2 t^{2}}>n_{a}$ times the $\epsilon$-bounded error is also achieved. Analogously, this analysis holds for the process of sampling from $X_{b}$ and $X_{c}$, where $p_{b}^{\prime}$ and $p_{c}^{\prime}$ are the estimations that result from sampling the distributions $X_{b}$ and $X_{c}$.

In order to decide whether " $\left|p_{c}-p_{a}\right|>\left|p_{b}-p_{c}\right|$ " or " $\left|p_{c}-p_{a}\right|<\left|p_{b}-p_{c}\right|$ ":

- Sample $n=\frac{\ln \frac{2}{\delta}}{2\left(\frac{\delta \delta}{4}\right)^{2}}$ times from each of the distributions $X_{a}, X_{b}$ and $X_{c}$ and compute $p_{a}^{\prime}, p_{b}^{\prime}, p_{c}^{\prime}$, the estimations for $p_{a}, p_{b}, p_{c}$ respectively.
- If $p_{c}^{\prime}>\frac{p_{a}^{\prime}+p_{b}^{\prime}}{2}$ then decide " $\left|p_{c}-p_{a}\right|>\left|p_{b}-p_{c}\right|$ "
- If $p_{c}^{\prime}<\frac{p_{a}^{\prime}+p_{b}^{\prime}}{2}$ then decide " $\left|p_{c}-p_{a}\right|<\left|p_{b}-p_{c}\right|$ "

The number of samples conducted by this procedure is $3 n=O\left(\log \left(\frac{1}{\varepsilon}\right) /\left(\Delta^{2} \delta^{2}\right)\right)$. We now have to show that this decision is in accordance with the definition above. Note that the Chernoff bound implies that with probability $1-\epsilon$ we have (i) $p_{a}^{\prime} \in\left(p_{a}-\frac{\Delta \delta}{4}, p_{a}+\frac{\Delta \delta}{4}\right)$, (ii) $p_{b}^{\prime} \in\left(p_{b}-\frac{\Delta \delta}{4}, p_{b}+\frac{\Delta \delta}{4}\right)$ and (iii) $p_{c}^{\prime} \in\left(p_{c}-\frac{\Delta \delta}{4}, p_{c}+\frac{\Delta \delta}{4}\right)$.

If $\frac{\left|p_{c}-p_{a}\right|}{\left|p_{b}-p_{a}\right|}>\frac{1}{2}(1+\delta)$ then by substituting $\Delta \leq p_{b}-p_{a}$ we get that $p_{c}>\frac{p_{b}+p_{a}}{2}+\frac{\Delta \delta}{2}$. Combining this with the above, $p_{c}^{\prime} \geq p_{c}-\frac{\Delta \delta}{4}>\frac{p_{b}+p_{a}}{2}+\frac{\Delta \delta}{4} \geq \frac{p_{a}^{\prime}+p_{b}^{\prime}}{2}$ so the correct decision is reached. Similarly, if $\left.\frac{\mid p_{c}-p_{a}}{p_{b}-p_{a}} \right\rvert\,<\frac{1}{2}(1-\delta)$.

Noisy binary search: A more sophisticated procedure is to treat the Subset-Tracing procedure as noisy binary search, as in [22]. They showed that in a model where each answer is correct with some fixed probability (say greater than $2 / 3$ ) that is independent of history it is possible to perform a binary search in $O(\log N)$ queries. Each step might require backtracking; in the subset-tracing scenario, the procedure backtracks if the condition $\left|p_{a}-p_{b}\right| \geq\left(\frac{1}{2}\right)^{i}$ does not hold at the $i^{\text {th }}$ step (which indicates an error in an earlier decision). Estimating the probability values within an accuracy of $\frac{1}{m}$ while guaranteeing a constant probability of error requires only $O\left(m^{2}\right)$ ciphertexts queries. This effectively means that we can fix $\delta$ and $\epsilon$ to be constants (independent of $m$ ). Therefore, we can perform the noisy binary search procedure with $O\left(m^{2} \log m\right)$ queries.

### 5.2 Improving the Tracing Algorithm

The basic traitors tracing algorithm described above requires $t \log (N / t)$ iterations. Furthermore, since at each iteration the number of subsets in the partition increases by one, tracing $t$ traitors may result with up to $t \log (N / t)$ subsets and hence in messages of length $t \log (N / t)$. This bound holds for any SubsetCover method satisfying the Bifurcation property, and both the Complete Subtree and the Subset Difference methods satisfy this property. What is the bound on the number of traitors that the algorithm can trace?

Recall that the Complete Subtree method requires a message length of $r \log (N / r)$ for $r$ revocations, hence the tracing algorithm can trace up to $r$ traitors if it uses the Complete Subtree method. However, since the message length of the Subset Difference method is at most $2 r-1$, only $\frac{2 r-1}{\log N / r}$ traitors can be traced if Subset Difference is used. We now describe an improvement on the basic tracing algorithm that reduces the number of subsets in the partition to $5 t-1$ for the Subset Difference method (although the number of iterations remains $t \log (N / t)$ ). With this improvement the algorithm can trace up to $r / 5$ traitors.

Note that among the $t \log N / t$ subsets generated by the basic tracing algorithm, only $t$ actually contain a traitor. The idea is to repeatedly merge those subsets which are not known to contain a traitor. ${ }^{8}$ Specifically, we maintain at each iteration a frontier of at most $2 t$ subsets plus $3 t-1$ additional subsets. In the following iteration a subset that contains a traitor is further partitioned; as a result, a new frontier is defined and the remaining subsets are re-grouped.
Frontier subsets: Let $S_{i_{1}}, S_{i_{2}}, \ldots S_{i_{m}}$ be the partition at the current iteration. A pair of subsets ( $S_{i_{j 1}}, S_{i_{j 2}}$ ) is said to be in the frontier if $S_{i_{1}}$ and $S_{i_{j 2}}$ resulted from a split-up of a single subset at an earlier iteration. Also neither ( $S_{i_{j 1}}$ nor $S_{i_{j 2}}$ ) was singled out by the subset tracing procedure so far. This definition implies that the frontier is composed of $k$ disjoint pairs of buddy subsets. Since buddy-subsets are disjoint and since each pair originated from a single subset that contained a traitor (and therefore has been split) $k \leq t$.

We can now describe the improved tracing algorithm which proceeds in iterations. Every iteration starts with a partition $\mathcal{S}=S_{i_{1}}, S_{i_{2}}, \ldots S_{i_{m}}$. Denote by $F \subset S$ the frontier of $S$. An iteration consists of the following steps, by the end of which a new partition $\mathcal{S}^{\prime}$ and a new frontier $F^{\prime}$ is defined.

- As before, use the Subset Tracing procedure to find a subset $S_{i_{j}}$ that contains a traitor. If the tracing procedure outputs that the box can not decrypt with $\mathcal{S}$ then we are done. Otherwise, split $S_{i_{j}}$ into $S_{i_{j 1}}$ and $S_{i_{j 2}}$.
- $F^{\prime}=F \cup S_{i_{j 1}} \cup S_{i_{j 2}}\left(S_{i_{11}}\right.$ and $S_{i_{j 2}}$ are now in the frontier). Furthermore, if $S_{i_{j}}$ was in the frontier $F$ and $S_{i_{k}}$ was its buddy-subset in $F$ then $F^{\prime}=F^{\prime} \backslash S_{i_{k}}$ (remove $S_{i_{k}}$ from the frontier).

[^7]- Compute a cover $\mathcal{C}$ for all receivers that are not covered by $F^{\prime}$. Define the new partition $\mathcal{S}^{\prime}$ as the union of $\mathcal{C}$ and $F^{\prime}$.

To see that the process described above converges, observe that at each iteration the number of new small frontier sets always increases by at least one. More precisely, at the end of each iteration construct a vector of length $N$ describing how many sets of size $i, 1 \leq i \leq N$, constitute the frontier. It is easy to see that these vectors are lexicographically increasing. The process must stop when or before all sets in the frontier are singletons.

By definition, the number of subsets in a frontier can be at most $2 t$. Furthermore, they are paired into at most $t$ disjoint buddy subsets. As for non-frontier subsets $(\mathcal{C})$, Lemma 4 shows that covering the remaining elements can be done by at most $|F| \leq 3 t-1$ subsets (note that we apply the lemma so as to cover all elements that are not covered by the buddy subsets, and there are at most $t$ of them). Hence the partition at each iteration is composed of at most $5 t-1$ subsets.

### 5.3 Tracing Traitors from Many Boxes

As new illegal decoding boxes, decoding clones and hacked keys are continuously being introduced during the lifetime of the system, a revocation strategy needs to be adopted in response. This revocation strategy is computed by first revoking the identities (leaves) of all the receivers that need to be excluded, resulting in some partition $\mathcal{S}_{0}$. Furthermore, to trace traitors from possibly more than one black box and make all of these boxes non-decoding, the tracing algorithm needs to be run in parallel on all boxes by providing all boxes with the same input. The initial input is the partition $\mathcal{S}_{0}$ that results from direct revocation of all known identities. As the algorithm proceeds, when the first box detects a traitor in one of the sets it re-partitions accordingly and the new partition is now input to all boxes simultaneously. The output of this simultaneous algorithm is a partition (or "revocation strategy") that renders all revoked receivers and illegal black boxes invalid.

## 6 Security of the Framework

In this section we discuss the security of a Subset-Cover algorithm. Intuitively, we identify a critical property that is required from the key-assignment method in order to provide a secure Subset-Cover algorithm. We say that a subset-cover algorithm satisfies the "key-indistinguishability" property if for every subset $S_{i}$ its key $L_{i}$ is indistinguishable from a random key given all the information of all users that are not in $S_{i}$. We then proceed to show that any subset-cover algorithm that satisfies the key-indistinguishability property provides a secure encryption of the message.

We must specify what is a secure revocation scheme, i.e. describe the adversary's power and what is considered a successful break. We provide a sufficient condition for a Subset-Cover revocation scheme $\mathcal{A}$ to be secure. We start by stating the assumptions on the security of the encryption schemes $E$ and $F$. All security definitions given below refer to an adversary whose challenge is of the form: distinguish between two cases ' $i$ ' and 'ii'.

### 6.1 Assumptions on the Primitives

Recall that the scheme employs two cryptographic primitives $F_{K}$ and $E_{L}$. The security requirements of these two methods are different, since $F_{K}$ uses short lived keys whereas $E_{L}$ uses long-lived ones. In both cases we phrase the requirements in terms of a the probability of success in distinguishing an encryption
of the true message from an encryption of a random message. It is well known that such formulation is equivalent to semantic security (that anything that can be computed about the message given the ciphertext is computable without it), see $[29,28,4]^{9}$.

The method $F_{K}$ for encrypting the body of the message should obey the following property: consider any feasible adversary $\mathcal{B}$ that chooses a message $M$ and receives for a randomly chosen $K \in\{0,1\}^{\ell}$ one of the following (i) $F_{K}(M)$ (ii) $F_{K}\left(R_{M}\right)$ for a random message $R_{M}$ of length $|M|$. The probability that $\mathcal{B}$ distinguishes the two cases is negligible and we denote the bound by $\varepsilon_{1}$, i.e.

$$
\mid \operatorname{Pr}\left[\mathcal{B} \text { outputs 'i’ } \mid F_{K}(M)\right]-\operatorname{Pr}\left[\mathcal{B} \text { outputs 'i' } \mid F_{K}\left(R_{M}\right)\right] \mid \leq \varepsilon_{1}
$$

Note that implementing $F_{K}$ by a pseudo-random generator (stream-cipher) where $K$ acts as the seed and whose output is Xored bit-by bit with the message satisfies this security requirement.

The long term encryption method $E_{L}$ should withstand a more severe attack, in the following sense: consider any feasible adversary $\mathcal{B}$ that for a random key $L$ gets to adaptively choose polynomially many inputs and examine $E_{L}$ 's encryption and similarly provide ciphertexts and examine $E_{L}$ 's decryption. Then $\mathcal{B}$ is faced with the following challenge: for a random plaintext $x$ (which is provided in the clear) it receives one of (i) $E_{L}(x)$ or (ii) $E_{L}\left(R_{x}\right)$ where $R_{x}$ is a random string of length $|x|$. The probability that $\mathcal{B}$ distinguishes the two cases is negligible and we denote the bound by $\varepsilon_{2}$, i.e.

$$
\mid \operatorname{Pr}\left[\mathcal{B} \text { outputs ‘i’ } \mid E_{L}(x)\right]-\operatorname{Pr}\left[\mathcal{B} \text { outputs ‘i’ } \mid E_{L}\left(R_{x}\right)\right] \mid \leq \varepsilon_{2}
$$

Note that the above specification indicates that $E$ should withstand a chosen-ciphertext attack in the preprocessing mode in the terminology of [19] or CCA-I in [3]. Possible implementation of $E_{L}$ can be done via pseudo-random permutations (which model block-ciphers). See more details on the efficient implementation of $F$ and $E$ in Section 4.1.
Key Assignment: Another critical cryptographic operation performed in the system is the key assignment method, i.e. how a user $u$ derives the keys $L_{i}$ for the sets $S_{i}$ such that $u \in S_{i}$. We now identify an important property the key assignment method in a subset-cover algorithm should possess that will turn out to be sufficient to provide security for the scheme:

Definition 9 Let $\mathcal{A}$ be a Subset-Cover revocation algorithm that defines a collection of subsets $S_{1}, \ldots, S_{w}$. Consider a feasible adversary $\mathcal{B}$ that

1. Selects $i, 1 \leq i \leq w$
2. Receives the $I_{u}$ 's (secret information that u receives) for all $u \in \mathcal{N} \backslash S_{i}$

We say that $\mathcal{A}$ satisfies the key-indistinguishability property if the probability that $\mathcal{B}$ distinguishes $L_{i}$ from a random key $R_{L_{i}}$ of similar length is negligible and we denote this by $\varepsilon_{3}$, i.e.

$$
\mid \operatorname{Pr}\left[\mathcal{B} \text { outputs } \quad i ’ \mid L_{i}\right]-\operatorname{Pr}\left[\mathcal{B} \text { outputs } \quad i \prime \mid R_{L_{i}}\right] \mid \leq \varepsilon_{3}
$$

Note that all "information theoretic" key assignment schemes, namely schemes in which the keys to all the subsets are chosen independently, satisfy Definition 9 with $\varepsilon_{3}=0$.

The next lemma is a consequence of the key-indistinguishability property and will be used in the proof of Theorem 12, the Security Theorem.

[^8]Lemma 10 For any $1 \leq i \leq w$ let $S_{i_{1}}, S_{i_{2}} \ldots, S_{i_{t}}$ be all the subsets that are contained in $S_{i}$; Let $L_{i_{1}}, \ldots, L_{i_{t}}$ be their corresponding keys. For any adversary $\mathcal{B}$ that selects $i, 1 \leq i \leq w$, and receives $I_{u}$ for all $u \in \mathcal{N} \backslash S_{i}$, if $\mathcal{B}$ attempts to distinguish the keys $L_{i_{1}}, \ldots, L_{i_{t}}$ from random keys $R_{L_{i_{1}}}, \ldots, R_{L_{i_{t}}}$ (of similar lengths) then

$$
\mid \operatorname{Pr}\left[\mathcal{B} \text { outputs ' } i \prime \mid L_{i_{1}}, \ldots, L_{i_{t}}\right]-\operatorname{Pr}\left[\mathcal{B} \text { outputs ' } i \prime \mid R_{L_{i_{1}}}, \ldots, R_{L_{i_{t}}}\right] \mid \leq t \cdot \varepsilon_{3} .
$$

Proof: Let us rename the subsets $S_{i_{1}}, S_{i_{2}} \ldots, S_{i_{t}}$ as $S_{1}, S_{2}, \ldots S_{t}$ and order them according to their size; that is for all $j=1, \ldots, t, S_{j} \subseteq S_{i}$ and $\left|S_{1}\right| \geq\left|S_{2}\right| \geq \ldots\left|S_{t}\right|$. We will now use a hybrid argument: consider an "input of the $j^{t h}$ type" as one where the first $j$ keys are the true keys and the remaining $t-j$ keys are random keys. $\forall 1 \leq j \leq t$, let $p_{j}$ be the probability that $\mathcal{B}$ outputs ' $i$ ' when challenged with an input of the $j^{\text {th }}$ type, namely

$$
p_{j}=\operatorname{Pr}\left[\mathcal{B} \text { outputs ‘i’ } \mid L_{1}, \ldots, L_{j}, R_{L_{j+1}}, \ldots, R_{L_{t}}\right]
$$

Suppose that the lemma doesn't hold, that is $\left|p_{t}-p_{0}\right|>t \cdot \varepsilon_{3}$. Hence there must be some $j$ for which $\left|p_{j}-p_{j-1}\right|>\varepsilon_{3}$. We now show how to create an adversary $\mathcal{B}^{\prime}$ that can distinguish between $R_{L_{j}}$ and $L_{j}$ with probability $>\varepsilon_{3}$, contradicting the key-indistinguishability property. The actions of $\mathcal{B}^{\prime}$ result from a simulation of $\mathcal{B}$ :

- When $\mathcal{B}$ selects $S_{i}, \mathcal{B}^{\prime}$ selects the subset $S_{j} \subseteq S_{i}$ from the above discussion (that is, the $j$ for which $\left|p_{j}-p_{j-1}\right|>\varepsilon_{3}$ ). It receives $I_{u}$ for all $u \in \mathcal{N} \backslash S_{j}$ and hence can provide $\mathcal{B}$ with $I_{u}$ for all $u \in \mathcal{N} \backslash S_{i}$.
- When $\mathcal{B}^{\prime}$ is given a challenge $X$ and needs to distinguish whether $X$ is $R_{L_{j}}$ or $L_{j}$, it creates a challenge to $\mathcal{B}$ that will be $L_{1}, \ldots, L_{j}, R_{L_{j+1}}, \ldots, R_{L_{t}}$ or $L_{1}, \ldots, L_{j-1}, R_{L_{j}}, R_{L_{j+1}}, \ldots, R_{L_{t}}$. Note that due their order $S_{1}, \ldots, S_{j-1} \not \subset S_{j}$; since $\mathcal{B}^{\prime}$ received $I_{u}$ for all $u \in \mathcal{N} \backslash S_{j}$ it knows the keys $L_{1}, \ldots, L_{j-1}$, while $R_{L_{j+1}}, \ldots, R_{L_{t}}$ are chosen at random. The $j$ th string in the challenge is simply $X$ (the one $\mathcal{B}^{\prime}$ received as a challenge.) $\mathcal{B}^{\prime}$ response is simply $\mathcal{B}$ 's answer to the query.

The advantage that $\mathcal{B}^{\prime}$ has in distinguishing between $R_{L_{j}}$ and $L_{j}$ is exactly the advantage $B^{\prime}$ has in distinguishing between $L_{1}, \ldots, L_{j}, R_{L_{j+1}}, \ldots, R_{L_{t}}$ and $L_{1}, \ldots, L_{j-1}, R_{L_{j}}, R_{L_{j+1}}, \ldots, R_{L_{t}}$, which is by assumption larger than $\varepsilon_{3}$, contradicting the key-indistinguishability property.

### 6.2 Security Definition of a Revocation Scheme

To define the security of a revocation scheme we first have to consider the power of the adversary in this scenario (and make pessimistic assumption on its ability). The adversary can pool the secret information of several users, and it may have some influence on the the choice of messages encrypted in this scheme (chosen plaintext). Also it may create bogus messages and see how legitimate users (that will not be revoked) react. Finally to say that the adversary has broken the scheme means that when the users who have provided it their secret information are all revoked (otherwise it is not possible to protect the plaintext) the adversary can still learn something about the encrypted message. Here we define "learn" as distinguishing its encryption from random (again this is equivalent to semantic security).

Definition 11 consider an adversary $\mathcal{B}$ that gets to

1. Select adaptively a set $\mathcal{R}$ of receivers and obtain $I_{u}$ for all $u \in \mathcal{R}$. By adaptively we mean that $\mathcal{B}$ may select messages $M_{1}, M_{2} \ldots$ and revocation set $\mathcal{R}_{1}, \mathcal{R}_{2}, \ldots$ (the revocation sets need not correspond to the actual corrupted users) and see the encryption of $M_{i}$ when the revoked set is $\mathcal{R}_{i}$. Also $\mathcal{B}$ can create a ciphertext and see how any (non-corrupted) user decrypts it. It then asks to corrupt a receiver $u$ and obtains $I_{u}$. This step is repeated $|\mathcal{R}|$ times (for any $u \in \mathcal{R}$ ).
2. Choose a message $M$ as the challenge plaintext and a set $\mathcal{R}$ of revoked users that must include all the ones it corrupted (but may contain more).
$\mathcal{B}$ then receives an encrypted message $M^{\prime}$ with a revoked set $\mathcal{R}$. It has to guess whether $M^{\prime}=M$ or $M^{\prime}=R_{M}$ where $R_{M}$ is a random message of similar length. We say that a revocation scheme is secure if, for any (probabilistic polynomial time) adversary $\mathcal{B}$ as above, the probability that $\mathcal{B}$ distinguishes between the two cases is negligible.

### 6.3 The Security Theorem

We now state and prove the main security theorem, showing that the key-indistinguishability property is sufficient for a scheme in the subset-cover framework to be secure in the sense of Definition 11. Precisely,

Theorem 12 Let $\mathcal{A}$ be a Subset-Cover revocation algorithm where the key assignment satisfies the keyindistinguishability property (Definition 9) and where $E$ and $F$ satisfy the above requirements. Then $\mathcal{A}$ is secure in the sense of Definition 11 with security parameter $\delta \leq \varepsilon_{1}+2 m w\left(\varepsilon_{2}+4 w \varepsilon_{3}\right)$, where $w$ is the total number of subsets in the scheme and $m$ is the maximum size of a cover.

Proof: Let $\mathcal{A}$ be a Subset-Cover revocation algorithm with the key indistinguishability property. Let $\mathcal{B}$ be an adversary that behaves according to Definition 11 , where $\delta$ is the probability that $\mathcal{B}$ distinguishes between an encryption of $M$ and an encryption of a random message of similar length.

Recall that the adversary adaptively selects a set of receivers $\mathcal{R}$ and obtains $I_{u}$ for all $u \in \mathcal{R}$. $\mathcal{B}$ then selects a challenge message $M$. Let $\mathcal{S}=S_{i_{1}}, S_{i_{2}}, \ldots S_{i_{m}}$ be the cover of $\mathcal{N} \backslash \mathcal{R}$ defined by $\mathcal{A}$. As a challenge, $\mathcal{B}$ then receives an encrypted message and is asked to guess whether it encrypts $M$ or a random message $R_{M}$ of the same length as $M$. We consider $\mathcal{B}$ 's behavior in case not all the encryptions are proper. Let a "ciphertext of the $j^{\text {th }}$ type" be one where the first $j$ subsets are noisy and the remaining subsets encode the correct key. In other words the body is the encryption using $F_{K}$ and the header is:

$$
\left[i_{1}, i_{2}, \ldots, i_{m}, E_{L_{i_{1}}}\left(R_{K}^{1}\right), E_{L_{i_{2}}}\left(R_{K}^{2}\right), \ldots, E_{L_{i_{j}}}\left(R_{K}^{j}\right), E_{L_{i_{j+1}}}(K), \ldots, E_{L_{i_{m}}}(K)\right]
$$

where $K$ is a random key and $\left\{R_{K}^{i}\right\}$ are random strings of the same length as the key $K$. Let $\Delta_{j}$ be the advantage that for a ciphertext of the $j^{\text {th }}$ type $\mathcal{B}$ distinguishes between the cases where $F_{K}(M)$ or $F_{K}\left(R_{M}\right)$ are the body of the message. I.e.

$$
\Delta_{j}=\mid \operatorname{Pr}\left[\mathcal{B} \text { outputs ' } \mathrm{i} ’ \mid \text { body is } F_{K}(M)\right]-\operatorname{Pr}\left[\mathcal{B} \text { outputs ‘ } \mathrm{i} ’ \mid \text { body is } F_{K}\left(R_{M}\right)\right] \mid,
$$

where the header is of the $j^{\text {th }}$ type.
The assumption that $\mathcal{B}$ can break the revocation system implies that $\Delta_{0}=\delta$. We also know that $\Delta_{m} \leq \varepsilon_{1}$, the upper bound on the probability of breaking $F_{K}$, since in ciphertexts of the $m^{t h}$ type the encryptions $E_{L_{i_{j}}}$ in the header contain no information on the key $K$ used for the body so $K$ looks random to $\mathcal{B}$. Hence there must be some $0<j \leq m$ such that

$$
\left|\Delta_{j-1}-\Delta_{j}\right| \geq \frac{\delta-\varepsilon_{1}}{m}
$$

For this $j$ it must be the case that for either $M$ or $R_{M}$ the difference in the probability that $\mathcal{B}$ outputs ' i ' between the case when the header is of the $j^{\text {th }}$ type and when it is of the $(j-1)^{\text {th }}$ type (and the same message is in the body) is at least $\frac{\delta-\varepsilon_{1}}{2 m}$.

A ciphertext of the $(j-1)^{\text {th }}$ type is noticeably different from a ciphertext of the $j^{\text {th }}$ type only if it is possible to distinguish between $E_{L_{i j}}(K)$ and $E_{L_{i_{j}}}\left(R_{K}\right)$. Therefore, the change in the distinguishing advantage $\left|\Delta_{j-1}-\Delta_{j}\right| \geq \frac{\delta-\varepsilon_{1}}{m}$ can be used to either break the encryption $E_{L}$ or to achieve an advantage in distinguishing the keys. We will now show how $\mathcal{B}$ can be used to construct an adversary $\mathcal{B}^{\prime}$ that either breaks $E_{L}$ or breaks the key-indistinguishability property, as extended by Lemma 10. This in turn is used to derive bounds on $\delta$.

Formally, we now describe an adversary $\mathcal{B}^{\prime}$ that will use $\mathcal{B}$ as follows.

- $\mathcal{B}^{\prime}$ picks at random $1 \leq i \leq w$ and asks to obtain $I_{u}$ for all $u \notin S_{i}$; this is a guess that $S_{i_{j}}=S_{i}$.
- $\mathcal{B}^{\prime}$ receives either $L_{0}, L_{1}, \ldots, L_{t}$ or $R_{L_{0}}, R_{L_{1}}, \ldots, R_{L_{t}}$ where $L_{0}=L_{i}$, the key of the subset $S_{i}$, and $L_{1}, \ldots, L_{t}$ are defined as the keys in Lemma 10. It attempts to distinguish between the case where the input corresponds to true keys and the case where the input consists of random keys.
- $\mathcal{B}^{\prime}$ simulates $\mathcal{B}$ as well as the Center that generates the ciphertexts and uses $\mathcal{B}$ 's output:
- When the Center is faced with the need to encrypt (or decrypt) using the key of subset $S_{j}$ such that $S_{j} \nsubseteq S_{i}$, then it knows at least one $u \in S_{j}$; from $I_{u}$ it is possible to obtain $L_{j}$ and encrypt appropriately. If $S_{j} \subseteq S_{i}$ then $\mathcal{B}^{\prime}$ uses the key that was provided to it (either $L_{j}$ or $R_{L_{j}}$ ).
- When $\mathcal{B}$ decides to corrupt a user $u$, if $u \notin S_{i}$, then $\mathcal{B}^{\prime}$ can provide it with $I_{u}$. If $u \in S_{i}$ then the guess that $i_{j}=i$ was wrong and we abort the simulation.
- When the Center needs to generate the challenge ciphertext $M$ for $\mathcal{B}, \mathcal{B}^{\prime}$ finds a cover for $\mathcal{R}$, the set of users corrupted by $\mathcal{B}$. If $i_{j} \neq i$, then the guess was wrong and the simulation is aborted. Otherwise a random key $K$ is chosen and a body of a message encrypted with $K$ is generated where the encrypted message is either $M$ or $R_{M}$ (depending to whom the difference between $\Delta_{j}$ and $\Delta_{j-1}$ is due) and one of two experiments is performed:
Experiment $j$ : Create a header of ciphertext of the $j^{\text {th }}$ type.
Experiment $j-1$ : Create a header of ciphertext of the $(j-1)^{t h}$ type.
Provide as challenge to $\mathcal{B}$ the created header and body.
- If the simulation was aborted, output ' i ' or ' ii ' at random. Otherwise provide $\mathcal{B}$ 's output.

Denote by $P_{L}^{j}$ (and $P_{L}^{j-1}$ resp.) the probability that in experiment $j$ (experiment $j-1$ ) in case the input to $\mathcal{B}^{\prime}$ are the true keys the simulated $\mathcal{B}$ outputs ' i '; denote by $P_{R}^{j}$ (and $P_{R}^{j-1}$ resp.) the probability that in experiment $j$ (experiment $j-1$ ) in case the input to $\mathcal{B}^{\prime}$ are random keys the simulated $\mathcal{B}$ outputs ' i '. We claim that the differences between all these 4 probabilities can be bounded:

Claim $13\left|P_{L}^{j}-P_{L}^{j-1}\right| \geq \frac{\delta-\varepsilon_{1}}{2 w m}$
Proof: In case the input to $\mathcal{B}^{\prime}$ are the true keys, the resulting distribution that the simulated $\mathcal{B}$ experiences is what it would experience in a true execution (where the difference between a $j^{\text {th }}$ ciphertext and $(j-1)^{\text {th }}$ ciphertext are at least $\frac{\delta-\varepsilon_{1}}{2 m}$ ). The probability that the guess was correct is $1 / w$ and this is independent of the action of $\mathcal{B}$, so we can experience a difference of at least $\frac{\delta-\varepsilon_{1}}{2 w m}$ between the two cases.

Claim $14\left|P_{R}^{j}-P_{R}^{j-1}\right| \leq \varepsilon_{2}$
Proof: Since otherwise we can use $\mathcal{B}^{\prime}$ to attack $E$ : whenever there is a need to use the key corresponding to the set $S_{i}$, ask for an encryption using the random key. Similarly use the $K$ in the challenge for $E$ as the one in the challenge of $\mathcal{B}^{\prime}$.

Claim $15\left|P_{R}^{j}-P_{L}^{j}\right| \leq w \cdot \varepsilon_{3}$ and $\left|P_{R}^{j-1}-P_{L}^{j-1}\right| \leq w \cdot \varepsilon_{3}$
Proof: If any of the two inequalities does not hold, then we can use $\mathcal{B}^{\prime}$ as an adversary for Lemma 10 and contradict the safety of the key assignment (we know that $t \leq w$ ).

From these three claims and applying the inequality $|a-b|-|c-d| \leq|a-c|+|b-d|$ we can conclude that

$$
\frac{\delta-\varepsilon_{1}}{2 w m}-\varepsilon_{2} \leq 2 w \cdot \varepsilon_{3}
$$

and hence the overall security parameter of $\mathcal{A}$ satisfies $\delta \leq \varepsilon_{1}+2 m w\left(\varepsilon_{2}+2 w \varepsilon_{3}\right)$.

Weaker notions of security It is interesting to deal with the case where the encryption provided by $F$ is not so strong. To combat copyright piracy it may not make sense to protect a specific ciphertext so that breaking it is very expensive; on the other hand we do want to protect the long lived keys of the system. The security definition (Definition 11) can easily be adapted to the case where distinguishing $F_{K}(M)$ from $F_{K}\left(R_{M}\right)$ cannot be done in some time $T_{1}$ where $T_{1}$ is not too large (this may correspond to using a not very long key $K$ ): the challenge following the attack is to distinguish $F_{K}(M)$ from $F_{K}\left(R_{M}\right)$ it time less than $T_{1}^{\prime}$ not much smaller than $T_{1}$. Essentially the same statement and proof of security as Theorem 12 hold. The fact that retrieving $K$ does not have to be intractable, just simply expensive, means that $K$ does not necessarily have to be long; see discussion on the implications on the total message length in Section 4.1.

It is also possible to model the case where the protection that $F_{K}$ provides is not indistinguishability (e.g. $F_{K}$ encrypts only parts of the message $M$ that are deemed more important). In this case we should argue that the header does not provide more information regarding $M$ than does $F_{K}(M)$. More precisely, suppose that $\mathcal{M}$ is a distribution on messages $M$ and let $\mathcal{B}$ be an adversary that attacks the system as in Definition 11 but is given as a challenge a valid encryption of a message $M \in_{R} \mathcal{M}$ and attempts to compute some function of $M$ (e.g. $M$ defines a piece of music and the function is to map it to sounds). A scheme is considered secure if for any $\mathcal{M}$ and $\mathcal{B}$ there is a $\mathcal{B}^{\prime}$ that simply receives $F_{K}(M)$ without the header and (i) performs an amount of work proportional to $\mathcal{B}$ after receiving the challenge and (ii) whose output is indistinguishable from $\mathcal{B}$ 's output; the distinguisher should have access to $M$. Here again for any subset cover algorithm where $E$ and the key assignment algorithm satisfy the requirements of Section 6.1 the resulting scheme will satisfy the relaxed definition.

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[^1]:    ${ }^{1}$ For instance, the software clone known as DeCSS, that cracked the DVD Video "encryption", is shielded by a tamper-resistant software tool which makes it very hard to reverse engineer its code and know its details such as receivers identities or its decoding strategy.
    ${ }^{2}$ For instance in the case of cable TV the pirates should be forced to create their own cable network.

[^2]:    ${ }^{3}$ Note that the comparison in the processing time between the two methods treats an application of a pseudo-random generator and a lookup operation as having the same cost, even though they might be quite different. More explicitly, the processing of both methods consists of $O(\log \log N)$ lookups; in addition, the Subset Difference method requires at $\operatorname{most} \log N$ applications of a pseudo-random generator.

[^3]:    ${ }^{4}$ This is relevant when the data is on a disk, rather then being broadcast, since broadcast results in scanning the list anyhow

[^4]:    ${ }^{5}$ The only exception is the case where $b$ and $b^{\prime}$ are siblings and are both children of $a$. This is a degenerate case, and the two subsets should be replaced by a new subset $S_{a, a^{\prime}}$

[^5]:    ${ }^{6}$ Both the scheme of Cramer and Shoup [14] and the random oracle based scheme [25] require some specific information for each recipient; a possible approach with random oracles is to add a zk proof-of-knowledge for $x$.

[^6]:    ${ }^{7}$ This is similar to the scenario considered in [27]

[^7]:    ${ }^{8}$ This idea is similar to the second scheme of [24], Section 3.3. However, in [24] the merge is straightforward as their model allows any subset. In our model only members from the Subset Difference are allowed, hence a merge which produces subsets of this particular type is non-trivial.

[^8]:    ${ }^{9}$ One actually has to repeat such an equivalence proof for the adversaries in question.

